



# Combining Cyclic Timetable Optimization and Traffic Assignment

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Michael Kümmling

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## Motivation

- TAKT: software system for automatic timetable generation
- powerful automatic timetable calculation suitable for complex real-world problems
- timetable optimization possible
- no satisfying estimation of variables' weighting for large networks

## Goal

- traffic assignment fitted to timetable optimization

- Fundamentals
  - Timetabling
  - Traffic Demand Modeling
- Traffic Assignment Methods
  - Graph of Itineraries
  - Quantifying Itineraries
  - Finding Reasonable Itineraries
- Conclusion

- periodic event network  $\mathcal{N} = (\mathcal{K}, \mathcal{A}, t_T)$  mit
  - period  $t_T \in \mathbb{N}^+$
  - node  $i \in \mathcal{K}$  with potential  $T_i$
  - arc  $a \in \mathcal{A}: i \rightarrow j$  with span  $x_a = T_j - T_i - z_a t_T$  ( $i, j \in \mathcal{K}, z_a \in \mathbb{Z}$ )
    - $x_a$  with lower bound  $t_{min,a}$  and upper bound  $t_{max,a}$
- periodic timetable  $\vec{T}: \forall i \in \mathcal{K}: T_i \in \mathcal{N}, 0 \leq T_i < t_T$
- periodic timetable  $\vec{T}$  is feasible for an event network  $\mathcal{N}$  if and only if
  - $\forall a \in \mathcal{A}: i \rightarrow j: \exists z_a \in \mathbb{Z}: t_{min,a} \leq T_j - T_i - z_a t_T \leq t_{max,a}$
- PESP: decision problem, whether there exists a feasible timetable for  $\mathcal{N}$

# Timetabling

## Periodic Event Scheduling Problem (PESP)

- timetable optimization by minimization of slacks  $y_a$  weighted with  $\omega_a$

$$\sum_{a \in \mathcal{A}} \omega_a y_a \rightarrow \min$$

$$T_j - T_i - z_a t_T \geq t_{\min, a}$$

$$T_j - T_i - z_a t_T \leq t_{\max, a}$$

$$y_a - T_j + T_i + z_a t_T + t_{\min, a} = 0$$

$$\forall a: i \rightarrow j \in \mathcal{A}$$

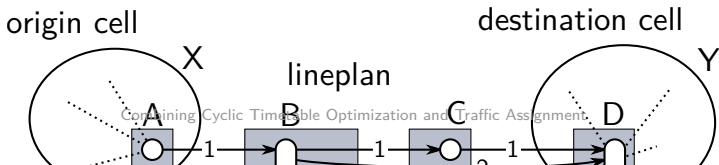
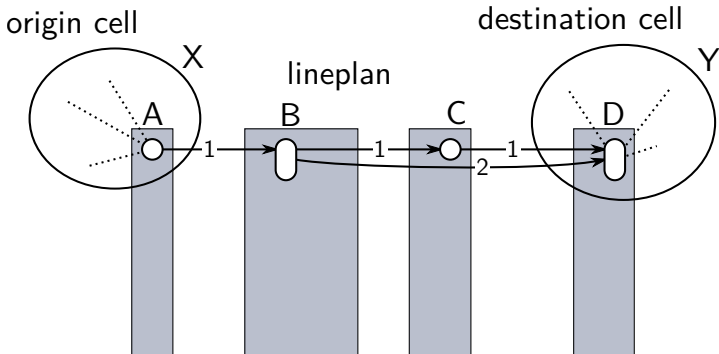
$$z_a \in \mathbb{Z}$$

the classic transport model:

- trip generation
- distribution (choice of destination)
- modal split (choice of mode)
- assignment (route choice)

for every origin-destination pair:

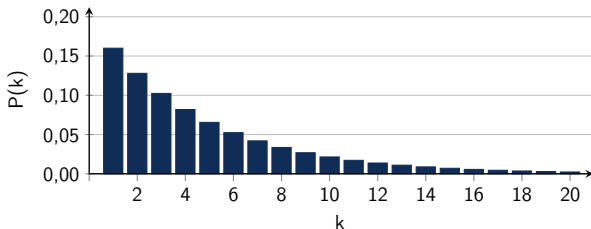
- determination of all reasonable itineraries
- quantification of itineraries
- distribution of the trips to itineraries

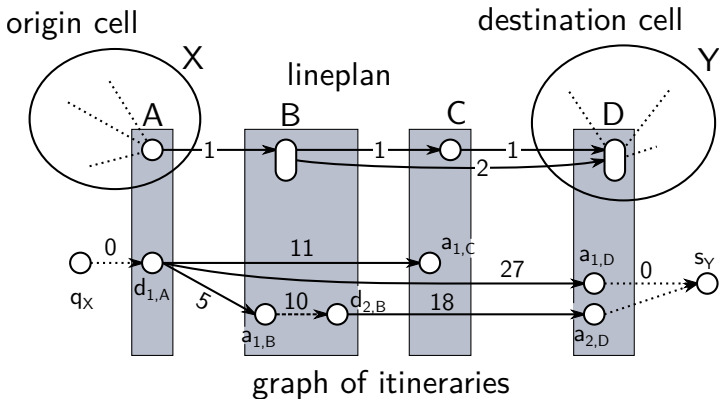




- most important criterion: traveling time
- existing timetables are no useful basis
- assumption of general, constant transfer times bears large deviation
- exact traveling times are unknown until conduction of timetable optimization
- traffic assignment and timetabling are interdependent; successive process leads to error
- error can be reduced by retrieving information from the event network
- bounding travel times without premature decision of timetable structure

- bounded values allow estimation of traveling times
- derived from delay distributions
- geometric distribution of probabilities of all permitted values:  $P(k) = p(1 - p)^k$
- e. g.,  $p = 0.2$ :

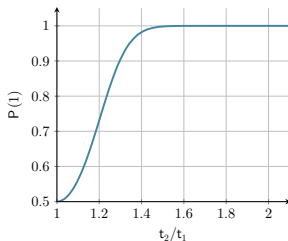




- set arc weights to estimated times

- estimation of shortest paths between all nodes (Floyd-Warshall algorithm)
- definition of maximum tolerable detour
- starting from all origins:  
construction of a tree of reasonable itineraries
  - exclusion of loops and side trips
  - exclusion of transfers which are in no way reasonable

- proportion of trips to reasonable itineraries by means of quantification
- number of trips for every stop and transfer  
≅ weights for timetable optimization



- traffic assignment method tailored for periodic timetable optimization
  - connection of transport planning and periodic timetabling
  - consideration of characteristics of regional and intercity rail passenger transport
- further outlook:
  - implementation of presented method
  - detailed analysis of parameters' effects
  - application of the findings in other fields like conflict resolving and traffic distribution

# Thank you for your attention.

## References



Jens Opitz: *Automatische Erzeugung und Optimierung von Taktfahrplänen in Schienenverkehrsnetzen*. PhD thesis, Technische Universität Dresden. Wiesbaden: Gabler Research, 2009. ISBN: 978-3-8349-2128-4.



Juan de Dios Ortúzar und Luis G. Willumsen: *Modelling Transport*. 4. Aufl. Chichester: John Wiley & Sons, 2011. ISBN: 9781119993520.





- constraint propagation within the event network
  - initialization of one potential to  $T_0 = \{0\}$
  - initialization of all other potentials to  $T_i = [0, t_T - 1]_{t_T}$
  - every constraint  $a: i \rightarrow j$  has a set of feasible spans  $\Delta_{ij}^{(t_T)} = [t_{min,a}, t_{max,a}]_{t_T}$
  - every constraint holds  $T_j = T_j \cap (T_i + \Delta_{ij}^{(t_T)})$  and  $T_i = T_i \cap (T_j - \Delta_{ij}^{(t_T)})$
  - further propagation of constraints to all nodes within the network
  - new (smaller) set of spans  $\Delta_{ij}^{(t_T)} = T_j - T_i$  for each arc

