

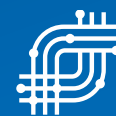
Yikai Zeng, Prof. Dr. Meng Wang

Chair of Traffic Process Automation,
“Friedrich List” Faculty of Transport and Traffic Science

Decentralized Truck Platooning Coordination

& an introduction to the Chair of Traffic Process Automation

59. Regelungstechnisches Kolloquium in Boppard
Boppard, 28-03-2025



Professur für
**Verkehrsprozess-
automatisierung**

Chair of Traffic Process Automation

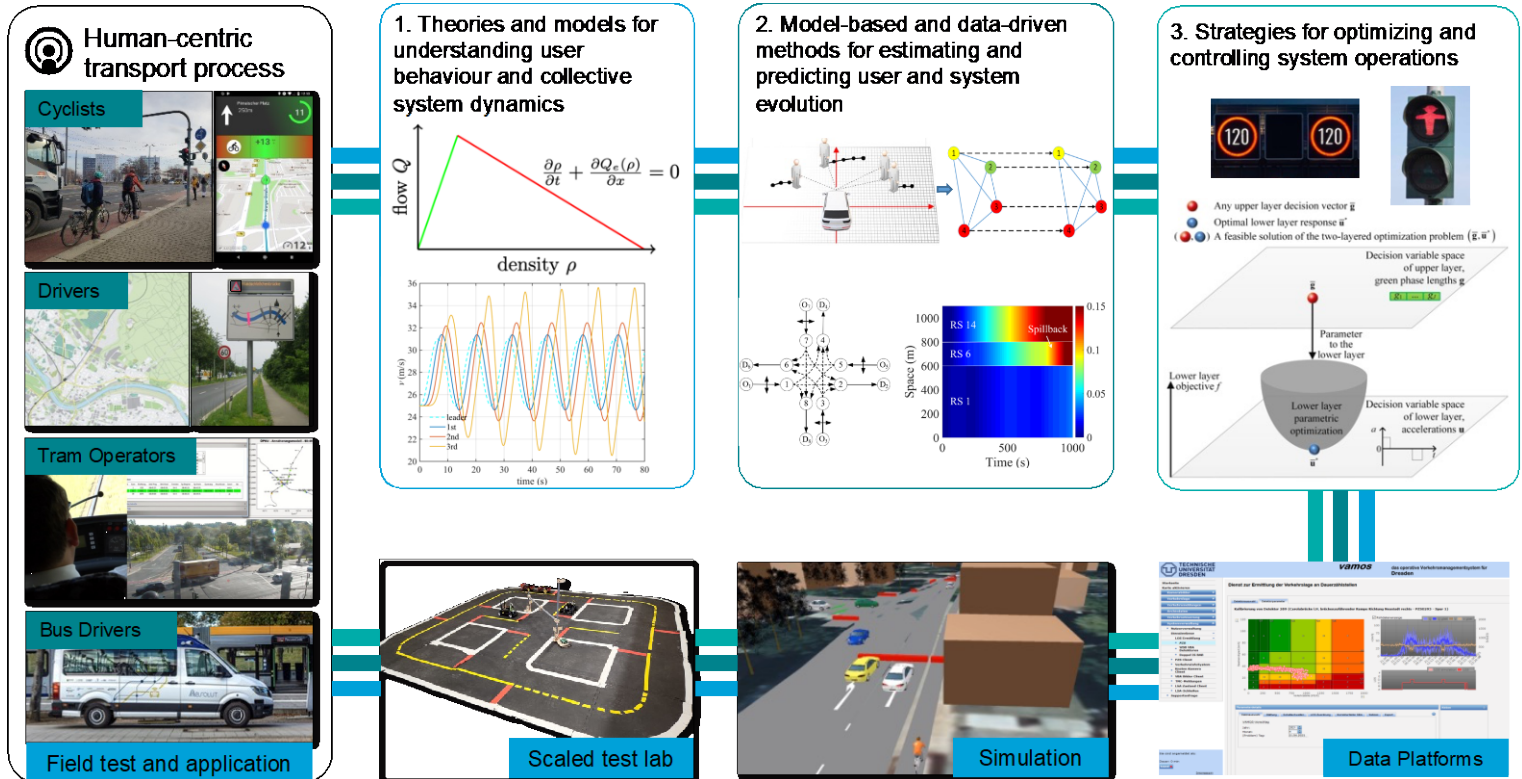
One of the **23** Transportation Chairs in the Faculty of Transport and Traffic Sciences @TU Dresden

Goal: Tackle transport challenges by leveraging communication and automation to **optimize and control** the operations of **multimodal** transport systems for **safety, efficiency and sustainability**.

Thematic area:

1. Traffic flow modelling and simulation
2. Multimodal traffic management
3. Connected and automated vehicles
4. Behaviour and services of vulnerable road users

Human-Centric (Closed-Loop) Systems Approach



4. Procedures, metrics and tooling for testing system performance and assessing macroscopic impact

Yikai Zeng, Raj T. Rajan and ,Meng Wang

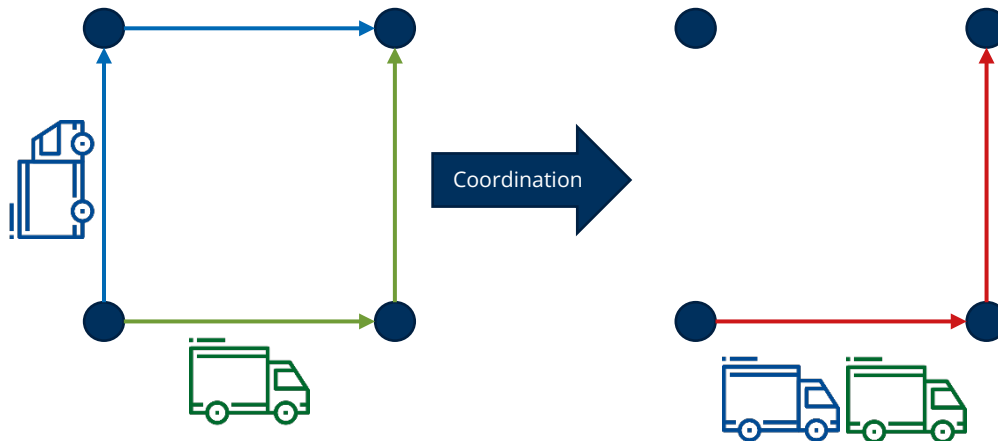
Decentralized coordination for truck platooning

Zeng, Y., Wang, M., & Rajan, R. T. (2022). Decentralized coordination for truck platooning. *Computer-Aided Civil and Infrastructure Engineering*, 37(15), 1997-2015.



Truck Platooning and its High-level Coordination

- Truck platooning : the active formation of a group of autonomous trucks traveling at close spacing
- Road tests reveal that a 13% of energy saving at a 10m gap and a 18% saving at a 4.7 m gap [1]
- Opportunistic platooning [3]: **Match by chance**
- Probability is low in ad-hoc network
- Actively seeking more chances: **high-level coordination of truck platooning [2]**



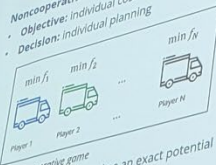
[1] Tsugawa, S. (2014, June). Results and issues of an automated truck platoon within the energy ITS project. In *2014 IEEE Intelligent Vehicles Symposium Proceedings* (pp. 642-647). IEEE.

[2] Johansson, A., Bai, T., Johansson, K. H., & Mårtensson, J. (2022). Platoon Cooperation Across Carriers: From System Architecture to Coordination. *IEEE Intelligent Transportation Systems Magazine*.

[3] Bhoopalam, A. K., Agatz, N., & Zuidwijk, R. (2018). Planning of truck platoons: A literature review and directions for future research. *Transportation research part B: methodological*, 107, 212-228.

Categories of Truck Platooning Coordination

- **Noncooperative Game**
- Objective: individual cost
- Decision: individual planning



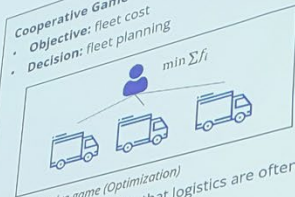
- **Non-cooperative game**
- Studied and formulated as an exact potential game [4]

Al-Jabbar, A., Nekouei, E., Johansson, K. G., & Malmgren, J. (2016, November). Multi-fleet platoon planning: A game-theoretic approach. In 2016 21st International Conference on Intelligent Transportation Systems (ITIS). IEEE.



Disciplinardes Truck Platooning Coordination
Professor für Verkehrsprozess- und -automatisierung / Yihai Zeng
Regelungstechnisches Kolloquium in Boppard

- **Cooperative Game**
- Objective: fleet cost
- Decision: fleet planning



- **Cooperative game (Optimization)**
- Captures the feature that logistics are often carried out by a fleet
- Overall cost is the primary concern of its manager
- Focus today

More global benefits potential



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GEFÖRDERT VOM



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