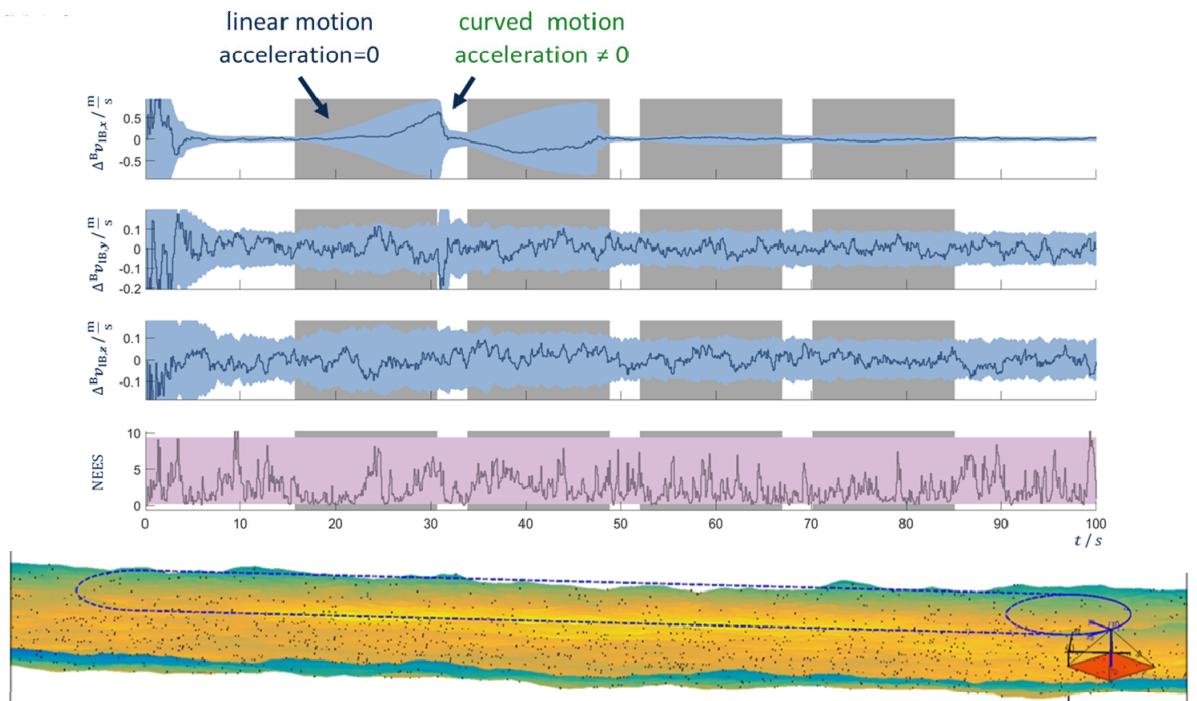
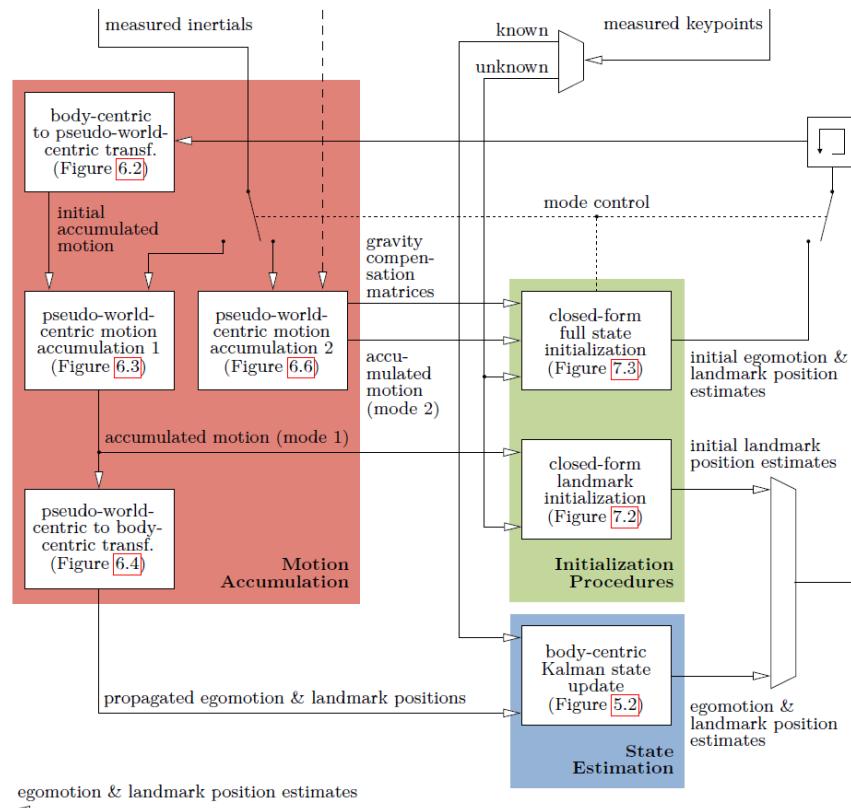


# Observability-driven 6DOF body-centric monocular SLAM



Ref.: Marcel Markgraf (geb. Tkocz), An Observability-Driven System Concept for Monocular-Inertial Egomotion and Landmark Position Determination, Dissertation TU Dresden, 2018.