

Diplomarbeit / Studienarbeit

Real-time capable implementation of a control system in ROS2

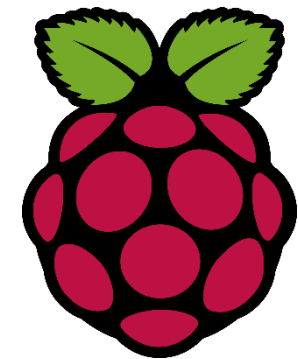


Small and inexpensive single-board computers (e.g. Raspberry Pi) now have high computing power. They are therefore to be used in the [RopeBot](#) project for complex calculations in the control system.

The goal of the work is to implement the existing control in ROS2 on a single-board computer. The computations are to be optimized in terms of computation time and real time.

Possible tasks are:

- Installation and configuration of a suitable real-time operating system
- Checking the existing control code for real-time capability and, if necessary, adapting the software
- Computation time optimization

 ROS

Contact

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