Prediction for Risk Processes

Egbert Dettweiler

Universität Tübingen

Abstract

A risk process is defined as a marked point process $((T_n, X_n))_{n\geq 1}$ on a certain probability space $(\Omega, \mathcal{F}, \mathbf{P})$, where the time points $T_1 < T_2 < \cdots$ are the claim arrival times of claims from a given portfolio of risks and the marks X_n are the claim amounts at time T_n . If $N_t(B)$ denotes the number of claims up to time t with claim amount in a Borel set B, then $((T_n, X_n))_{n\geq 1}$ can equivalently be described by the family of processes $(N_t(B))_{t\geq 0}$ with $B \in \mathcal{B}(\mathbb{R}_+)$. Suppose that (T, \mathcal{T}) is a measurable space, Θ a T-valued random variable, and that $(\mathcal{F}^{\Theta}_t)_{t\geq 0}$ is the filtration defined by $\mathcal{F}^{\Theta}_t = \sigma(\Theta) \vee \sigma(\{N_s(B) : s \leq t, B \in \mathcal{B}(\mathbb{R}_+)\})$. Assume that there is a family of (\mathcal{F}^{Θ}_t) -adapted processes $(\lambda_t(B))_{t\geq 0}$ $(B \in \mathcal{B}(\mathbb{R}_+))$ such that all processes $(N_t(B) - \int_0^t \lambda_s(B) ds)_{t\geq 0}$ are local (\mathcal{F}^{Θ}_t) martingales. Then $((T_n, X_n))_{n\geq 1}$ is called a Θ -mixed risk process, and for a number of reasons the random variable Θ is called the *portfolio structure*.

Now suppose that $Z = (Z_t)_{t\geq 0}$ is an (\mathcal{F}_t^{Θ}) -adapted process and that $(\mathcal{F}_t)_{t\geq 0}$ is a subfiltration of (\mathcal{F}_t^{Θ}) . The filtering problem for Z given (\mathcal{F}_t) is just the problem to determine the process $(\mathbf{E}\{Z_t \mid \mathcal{F}_t\})_{t\geq 0}$, and the prediction problem is the problem to determine for a given h > 0 the process $(\mathbf{E}\{Z_{t+h} \mid \mathcal{F}_t\})_{t\geq 0}$. For a number of relevant processes Z one can use a martingale property inherited from the martingale property of $((T_n, X_n))_{n\geq 1}$ to solve the filtering and the prediction problem. A typical example is the process $(S_t^B)_{t\geq 0}$ $(B \in \mathcal{B}(\mathbb{R}_+))$ given by $S_t^B = \sum_{n\geq 1} X_n \mathbf{1}_{\{T_n \leq t\}} \mathbf{1}_{\{X_n \in B\}}$. In this case the process $(S_t^B - \int_0^t \int_B x\lambda_s(dx)ds)_{t\geq 0}$ is a local (\mathcal{F}_t^{Θ}) -martingale.

1 Mixed Risk Processes

Let (E, \mathcal{E}) be a measurable space and let Δ denote an artificial element outside of E. We set $E_{\Delta} := E \cup \{\Delta\}$ and provide E_{Δ} with the σ -algebra $\mathcal{E}_{\Delta} := \sigma(\mathcal{E} \cup \{\{\Delta\}\})$. Now suppose that $(T_n)_{n\geq 1}$ is a *claim arrival process* on the probability space $(\Omega, \mathcal{F}, \mathbf{P})$, i.e. that \mathbf{P} -a.s.

$$0 =: T_0 \le T_1 \le T_2 \le \cdots$$
 with $T_{n-1} < T_n$, if $T_{n-1} < \infty$

and that $(X_n)_{n\geq 1}$ is a sequence of E_{Δ} -valued random variables such that the following condition holds:

$$T_n = \infty \iff X_n = \Delta$$
 . (1)

Then the double sequence $((T_n, X_n))_{n \ge 1}$ is called a *risk process* with *claim space* E. For n = 0 we make the convention $X_0 := \epsilon$ with a fixed $\epsilon \in E$.

We will always assume in the following that (E, \mathcal{E}) is a polish space provided with its Borel field. In most applications $E = \mathbb{R}_+$ and $\Delta = \infty$, i.e. $E_{\Delta} = \overline{\mathbb{R}}_+$. Then every X_n is interpreted as the claim size of the *n*-th claim and $(X_n)_{n\geq 1}$ will be called the *claim size process* or the *claim amount process* of the risk process.

Let us denote by $M^z_+(X, \mathcal{X})$ the space of all $\overline{\mathbb{Z}}_+$ -valued measures on a measurable space (X, \mathcal{X}) . Then a risk process $((T_n, X_n))_{n \geq 1}$ with claim space E can be equivalently described by the *random measure*

$$\mathcal{N}: (\Omega, \mathcal{F}, \mathbf{P}) \longrightarrow M^z_+(\mathbb{R}_+ \times E, \mathcal{B}(\mathbb{R}_+) \otimes \mathcal{E}) ,$$

defined by

$$\mathcal{N} := \sum_{n \ge 1} \delta_{(T_n, X_n)}$$
.

For $t \ge 0$ and $B \in \mathcal{E}$ we set

$$N_t(B) := \mathcal{N}([0,t] \times B) = \sum_{n \ge 1} \mathbb{1}_{\{T_n \le t\}} \mathbb{1}_{\{X_n \in B\}}$$

Then every $N_t(B)$ is a random variable and we can identify the random measure \mathcal{N} with the family $((N_t(B))_{t\geq 0})_{B\in\mathcal{E}}$ of stochastic processes. We will call

$$\mathcal{N} = \left((N_t(B))_{t \ge 0} \right)_{B \in \mathcal{E}}$$

the risk measure of the risk process $((T_n, X_n))_{n \geq 1}$.

Since $(N_t(E))_{t\geq 0}$ is just the *claim number process* of $(T_n)_{n\geq 1}$, we will also write N_t instead of $N_t(E)$.

Now let $\mathbf{F} = (\mathcal{F}_t)_{t\geq 0}$ be a given right continuous filtration on $(\Omega, \mathcal{F}, \mathbf{P})$. A family $\Lambda = ((\lambda_t(B))_{t\geq 0})_{B\in\mathcal{E}}$ of \mathbb{R}_+ -valued stochastic processes is called an **F**-intensity measure, if the following properties hold:

(i) for every fixed $B \in \mathcal{E}$ the process $(\lambda_t(B))_{t\geq 0}$ is an **F**-progressively measurable process with values in \mathbb{R}_+ .

(ii) for every fixed $t \ge 0$,

$$B \longmapsto \lambda_t(B)$$

is a finite measure on (E, \mathcal{E}) , and (iii) for every t > 0

(iii) for every $t \ge 0$,

$$\int_0^t \lambda_s(E) \, ds \, < \, \infty \quad \mathbf{P}\text{-a.s.}.$$

In the following we will just write λ_t instead of $\lambda_t(E)$.

Now suppose that $((T_n, X_n))_{n\geq 1}$ is a risk process with associated risk measure $\mathcal{N} = ((N_t(B))_{t\geq 0})_{B\in\mathcal{E}}$ and assume that \mathcal{N} is **F**-adapted. Then we say that \mathcal{N} (or $((T_n, X_n))_{n\geq 1}$) has the **F**-intensity measure $\Lambda = ((\lambda_t(B))_{t\geq 0})_{B\in\mathcal{E}}$, if

$$\left(N_{T_n \wedge t}(B) - \int_0^{T_n \wedge t} \lambda_s(B) \, ds\right)_{t \ge 0} \tag{2}$$

is an **F**-martingale for every $n \ge 1$ and every $B \in \mathcal{E}$. If the random variables $N_t := N_t(E)$ (t > 0) are *integrable* (in this case we will also say that the risk process $((T_n, X_n))_{n\ge 1}$ is *integrable*), then (2) just means that for all $B \in \mathcal{E}$ the processes

$$\left(N_t(B) - \int_0^t \lambda_s(B) \, ds\right)_{t \ge 0} \tag{3}$$

are **F**-martingales.

For $B \in \mathcal{E}$ the measure $\lambda_t(B) (dt \otimes d\mathbf{P})$ is obviously absolutely continuous relative to $\lambda_t(E) (dt \otimes d\mathbf{P})$. Hence there exists a Radon-Nikodym-density $\gamma_t(B)$ relative to $\lambda_t(E) (dt \otimes d\mathbf{P})$, and it is not difficult to prove that these densities can be chosen in such a way that

$$B \mapsto \gamma_t(B)$$

is a probability measure for all $\omega \in \Omega$. In case that always $\lambda_t(E) > 0$, one can just set

$$\gamma_t(B) := \frac{\lambda_t(B)}{\lambda_t(E)}.$$

In the following we assume always that

$$\lambda_t(B) = \gamma_t(B)\lambda_t \, ,$$

where γ_t is a probability measure on (E, \mathcal{E}) .

In this paper we will consider essentially two filtrations. The first filtration is the canonical filtration $\mathbf{F}^{\mathcal{N}} = (\mathcal{F}_t^{\mathcal{N}})_{t \geq 0}$ of \mathcal{N} , defined by

$$\mathcal{F}_t^{\mathcal{N}} := \sigma(\{N_s(B) \mid s \le t, B \in \mathcal{E}\}).$$

For the second filtration we take a measurable space (T, \mathcal{T}) , a measurable map

$$\Theta: (\Omega, \mathcal{F}, \mathbf{P}) \to (T, \mathcal{T}) ,$$

and define the filtration $\mathbf{F}^{\Theta} = (\mathcal{F}^{\Theta}_t)_{t \geq 0}$ by

$$\mathcal{F}_t^{\Theta} := \sigma(\Theta) \vee \mathcal{F}_t^{\mathcal{N}}.$$

 Θ will shortly be called the *portfolio structure*, and if $((T_n, X_n))_{n\geq 1}$ is a risk process with a \mathbf{F}^{Θ} -intensity measure $\Lambda = ((\lambda_t(B))_{t\geq 0})_{B\in\mathcal{E}}$, then $((T_n, X_n))_{n\geq 1}$ is called a Θ -mixed risk process. Suppose that $G = (G_t)_{t\geq 0}$ is a \mathbf{F}^{Θ} -adapted process. Then it is easily shown that on the set $\{T_{n-1} \leq t < T_n\}$ G_t only depends on $(T_k, X_k)_{k\leq n-1}$ and on Θ and we express this dependence by the notation

$$G_t = G_t(\Theta, (T_k, X_k)_{k \le n-1}) .$$

We will also often make use of the following convention: If a function f depends on $(t_j, x_j)_{j \le n}$, then we will use freely the different notations

$$f(t_1, \dots, t_n, x_1, \dots, x_n)$$
, $f((t_j, x_j)_{j \le n})$, or
 $f((t_i, x_i)_{1 \le i \le k-1}, (t_j, x_j)_{k \le j \le n})$ for $1 \le k \le n$.

For the purposes of this paper we need some further regularity properties of the \mathbf{F}^{Θ} -intensity measure

$$\Lambda = \left((\lambda_t(B))_{t \ge 0} \right)_{B \in \mathcal{E}}$$

of a Θ -mixed risk process $((T_n, X_n))_{n \ge 1}$.

1.1 Definition. The \mathbf{F}^{Θ} -intensity measure Λ is said to be *regular*, if the following condition holds:

There exists a σ -finite measure γ on (E, \mathcal{E}) such that

$$\gamma_t = g_t(\cdot; \Theta, T_1, \cdots, T_{n-1}, X_1, \cdots, X_{n-1})\gamma$$

on $\{T_{n-1} \leq t < T_n\}$, and such that

$$(t, x, \theta, t_1, \cdots, t_{n-1}, x_1, \cdots, x_{n-1}) \mapsto g_t(x; \theta, t_1, \cdots, t_{n-1}, x_1, \cdots, x_{n-1})$$

is measurable.

In case that Λ is regular, the distribution of

$$(\Theta, T_1, T_2, \cdots, X_1, X_2, \cdots)$$

can easily be computed. Denote by β the distribution of Θ and suppose that $u_1, \dots, u_n \in \mathbb{R}_+, B_1, \dots, B_n \in \mathcal{E}$, and $C \in \mathcal{T}$ are given. Then

$$\mathbf{P}\left\{T_{1} \leq u_{1}, \cdots, T_{n} \leq u_{n}, X_{1} \in B_{1}, \cdots, X_{n} \in B_{n}, \Theta \in C\right\}$$

$$= \int_{C} \int_{0}^{u_{1}} \int_{B_{1}} \cdots \int_{t_{n-1} \wedge u_{n}}^{u_{n}} \int_{B_{n}} G^{(n)}(y, (t_{i}, x_{i})_{i \leq n})$$

$$\gamma(dx_{n})dt_{n} \cdots \gamma(dx_{1})dt_{1}\beta(dy) ,$$

$$(4)$$

where the integrand $G^{(n)}(y, (t_i, x_i)_{i \le n})$ is given by

$$G^{(n)}(y,(t_i,x_i)_{i\leq n}) = \prod_{i=1}^{n} \left\{ g_{t_i}(x_i;y,(t_j,x_j)_{j\leq i-1}) + \lambda_{t_i}(y,(t_j,x_j)_{j\leq i-1}) e^{-\int_{t_{i-1}}^{t_i} \lambda_s(y,(t_j,x_j)_{j\leq i-1}) ds} \right\}.$$
(5)

There are also explicit formulas for a number of important conditional distributions. Define

$$\begin{aligned}
G_{\Theta,(T_{i},X_{i})_{i\leq n}}^{(n,k)}((t_{j},x_{j})_{1\leq j\leq k}) \\
&:= \prod_{l=1}^{k} \left\{ g_{t_{l}}(\Theta,(T_{i},X_{i})_{i\leq n},(t_{j},x_{j})_{1\leq j\leq l-1}) \\
&\cdot \lambda_{t_{l}}(\Theta,(T_{i},X_{i})_{i\leq n},(t_{j},x_{j})_{1\leq j\leq l-1}) e^{-\int_{t_{l-1}}^{t_{l}} \lambda_{s}(\Theta,(T_{i},X_{i})_{i\leq n},(t_{j},x_{j})_{1\leq j\leq l-1}) ds} \right\}
\end{aligned}$$
(6)

with the convention $t_0 = T_n$. Then for $n \ge 1$, $k \ge 1$, $u_1, \dots, u_k > 0$, and $B_1, \dots, B_k \in \mathcal{E}$ we have

We remark that

$$\mathcal{F}_{T_n}^{\Theta} = \sigma(\Theta, (T_j, X_j)_{0 \le j \le n})$$

There is also an explicit formula for the conditional distribution relative to the σ -algebra \mathcal{F}_t^{Θ} for $t \ge 0$ (cf. Dettweiler [2004]). For every $n \ge 1, k \ge 1, u_1, \cdots, u_k > 0$, and $B_1, \cdots, B_k \in \mathcal{E}$ one has

$$1_{\{T_{n-1} \le t < T_n\}} \mathbf{P} \{ T_n \le u_1, \cdots, T_{n+k-1} \le u_k,$$

$$X_n \in B_1, \cdots, X_{n+k-1} \in B_k \mid \mathcal{F}_t^{\Theta} \}$$

$$= 1_{\{T_{n-1} \le t < T_n\}} \int_{t \land u_1}^{u_1} \int_{B_1} \cdots \int_{s_{k-1} \land u_k}^{u_k} \int_{B_k} G_{\Theta,(T_i,X_i)_{i \le n-1}}^{t,(n-1,k)} ((t_j, x_j)_{1 \le j \le k})$$

$$\gamma(dx_k) dt_k \cdots \gamma(dx_1) dt_1 ,$$
(8)

where the density $G^{t,(n-1,k)}_{\Theta,(T_i,X_i)_{i\leq n-1}}$ is given by

$$G_{\Theta,(T_{i},X_{i})_{i\leq n-1}}^{t,(n-1,k)}((t_{j},x_{j})_{1\leq j\leq k})$$

$$:= \prod_{l=1}^{k} \left\{ g_{t_{l}}(\Theta,(T_{i},X_{i})_{i\leq n-1},(t_{j},x_{j})_{1\leq j\leq l-1}) \right.$$

$$\left. \cdot \lambda_{t_{l}}(\Theta,(T_{i},X_{i})_{i\leq n-1},(t_{j},x_{j})_{j\leq l-1}) e^{-\int_{t_{l-1}}^{t_{l}} \lambda_{s}(\Theta,(T_{i},X_{i})_{i\leq n-1},(t_{j},x_{j})_{j\leq l-1}) ds} \right\}$$

$$(9)$$

with the convention $t_0 = t$.

In this paper we will consider - beside the general results - three classes of special risk processes.

(a) Mixed (homogeneous) Poisson Risk Processes: This is the case, if $(\lambda_t)_{t\geq 0}$ is a constant process only depending on Θ and if also the densities g_t above only depend on Θ (and also not on t). This means that we assume

$$\lambda_t = \lambda(\Theta)$$
 , and (10)

$$g_t(\cdot;\Theta,T_1,\cdots,T_{n-1},X_1,\cdots,X_{n-1}) = g(\cdot;\Theta) .$$
(11)

(b) Mixed (inhomogeneous) Poisson Risk Processes: In this case we assume

$$\lambda_t = \lambda_t(\Theta)$$
 , and (12)

$$g_t(\cdot;\Theta,T_1,\cdots,T_{n-1},X_1,\cdots,X_{n-1}) = g_t(\cdot;\Theta) .$$
(13)

(c) Mixed Markovian Risk Processes: Here we suppose that we have on the sets $\{T_{n-1} \le t < T_n\}$ $(n \ge 1)$

$$\lambda_t = \lambda_t^{(n)}(\Theta)$$
 , and (14)

$$g_t(\cdot;\Theta, T_1, \cdots, T_{n-1}, X_1, \cdots, X_{n-1}) = g_t^{(n)}(\cdot;\Theta) ,$$
 (15)

and the mixed Markovian risk process is said to be *homogeneous*, if $\lambda_t^{(n)}$ and $g_t^{(n)}$ do not depend on t.

2 Prediction

From now on we will always assume that $((T_n, X_n))_{n \ge 1}$ is a Θ -mixed risk process with a regular \mathbf{F}^{Θ} -intensity measure Λ as described in definition 1.1.

Suppose that $Z = (Z_s)_{s\geq 0}$ is an integrable, \mathbf{F}^{Θ} -adapted process, that $0 \leq t < u$ are two given fixed time points and that \mathcal{G}_t is a fixed sub- σ -algebra of \mathcal{F}_t^{Θ} . Then we will call $\mathbf{E}\{Z_u | \mathcal{G}_t\}$ the prediction of Z_u on the basis of the informations given by \mathcal{G}_t (or more shortly: the prediction of Z_u given \mathcal{G}_t). This prediction problem will be solved in two steps: In this section we will first consider the prediction of Z_u given \mathcal{F}_t^{Θ} . Then in the next section we will solve the prediction of Z_u given \mathcal{G}_t by filtering $\mathbf{E}\{Z_u | \mathcal{F}_t^{\Theta}\}$, which simply means that we use the iteration formula for conditional expectations: $\mathbf{E}\{Z_u | \mathcal{G}_t\} = \mathbf{E}\{\mathbf{E}\{Z_u | \mathcal{F}_t^{\Theta}\} | \mathcal{G}_t\}$. Since $Z = (Z_s)_{s\geq 0}$ is assumed to be \mathbf{F}^{Θ} -adapted, we have

$$Z_u = \sum_{n \ge 1} \mathbb{1}_{\{T_{n-1} \le t < T_n\}} \sum_{k \ge 1} \mathbb{1}_{\{T_{n-1+k-1} \le u < T_{n-1+k}\}} Z_u(\Theta, (T_i, X_i)_{i \le n-1+k-1}).$$

Thus we obtain from (8) the general formula

$$\mathbf{E}\{Z_u \,|\, \mathcal{F}_t^{\Theta}\} = \sum_{n \ge 1} \mathbf{1}_{\{T_{n-1} \le t < T_n\}} \sum_{k \ge 1} I_{n,k}^{t,u}(\Theta, (T_i, X_i)_{i \le n-1}), \quad (16)$$

where

$$I_{n,k}^{t,u}(\Theta, (T_i, X_i)_{i \le n-1}) := \mathbf{E} \{ \mathbf{1}_{\{T_{n-1+k-1} \le u < T_{n-1+k}\}} Z_u(\Theta, (T_i, X_i)_{i \le n-1+k-1}) \mid \mathcal{F}_t^{\Theta} \}.$$

For k = 1 we have

$$I_{n,1}^{t,u}(\Theta, (T_i, X_i)_{i \le n-1}) = Z_u(\Theta, (T_i, X_i)_{i \le n-1} e^{-\int_t^u \lambda_r(\Theta, (T_i, X_i)_{i \le n-1})dr}, \quad (17)$$

and for k > 1 we have (with the convention $t_0 = t$)

$$I_{n,k}^{t,u}(\Theta, (T_i, X_i)_{i \le n-1})$$

$$= \int_t^u \int_E \cdots \int_{t_{k-2}}^u \int_E \left\{ Z_u(\Theta, (T_i, X_i)_{i \le n-1}, (t_j, x_j)_{1 \le j \le k-1}) \\ \cdot e^{-\int_t^u \lambda_r(\Theta, (T_i, X_i)_{i \le n-1}, (t_j, x_j)_{1 \le j \le k-1}) dr} G_{\Theta, (T_i, X_i)_{i \le n-1}}^{t, (n-1, k-1)} ((t_j, x_j)_{1 \le j \le k-1}) \right\} \\ \gamma(dx_{k-1}) dt_{k-1} \cdots \gamma(dx_1) dt_1 .$$
(18)

The double series in formula (16) reduces to a finite sum, if Z_u does not fully depend on $((T_n, X_n))_{n \ge 1}$, i.e. if

$$Z_u = Z_u(\Theta, (T_i, X_i)_{0 \le i \le m})$$

for some fixed $m \ge 0$. We omit the details.

We will restrict now to more special prediction problems. For this we assume that in the following always $E = \mathbb{R}_+$ (or at least \mathbb{R}^d), but we will still use the notation E to distinguish the claim space from the time axis.

For a fixed Borel subset B of E and $t \ge 0$ we set

$$S_t^B := \sum_{n \ge 1} X_n \mathbf{1}_{\{X_n \in B\}} \mathbf{1}_{\{T_n \le t\}} .$$
(19)

Then

$$S_t^B = \int_0^t \int_B x N(ds, dx) \, .$$

We will assume that for all $t \ge 0$

$$\mathbf{E} \int_0^t \int_B |x| \, g_s(x) \lambda_s \gamma(dx) ds \, < \, \infty \, . \tag{20}$$

Then one knows (cf. Dettweiler [2004]) that

$$\left(S_t^B - \int_0^t \int_B x \, g_s(x) \lambda_s \gamma(dx) ds\right)_{t \ge 0}$$

is an $\mathbf{F}^{\Theta}\text{-martingale.}$ This implies

$$\mathbf{E}\{S_u^B - S_t^B \,|\, \mathcal{F}_t^\Theta\} = \mathbf{E}\{\int_t^u \int_B x \,g_s(x)\lambda_s \gamma(dx)ds \,\big|\, \mathcal{F}_t^\Theta\} \,. \tag{21}$$

Thus the prediction of $S_u^B - S_t^B$ given \mathcal{F}_t^{Θ} is the same as the prediction of

$$Z_u := \int_t^u \int_B x \, g_s(x) \lambda_s \gamma(dx) ds \tag{22}$$

given \mathcal{F}_t^{Θ} .

If the density processes g and λ fully depend on $((T_n, X_n))_{n\geq 1}$, one has to use the general formula (16) for the Z_u given by (22), which clearly is not an easy and practical task. But there are two important special cases, where the prediction is quite easy, since g and λ only depend on Θ .

2.1 Proposition. Suppose that $((T_n, X_n))_{n\geq 1}$ is a mixed inhomogeneous Poisson risk process, for which the integrability assumption (20) holds. Then

$$\mathbf{E}\{S_u^B - S_t^B \,|\, \mathcal{F}_t^\Theta\} = \int_t^u \int_B x g_s(x;\Theta) \lambda_s(\Theta) \gamma(dx) ds \;. \tag{23}$$

If especially $((T_n, X_n))_{n\geq 1}$ is a mixed homogeneous Poisson risk process, then

$$\mathbf{E}\{S_u^B - S_t^B \,|\, \mathcal{F}_t^\Theta\} = (u - t)\lambda(\Theta) \int_B xg(x;\Theta)\gamma(dx) \,. \tag{24}$$

The prediction problem for general mixed risk processes is getting more simple in the following situation. We introduce the stopping time

$$T_t := \inf\{v > t \,|\, N_v - N_t \ge 1\} \;,$$

and consider the prediction problem for the increment $S^B_{T_t \wedge u} - S^B_t$. Since $T_t = T_n$ on $\{T_{n-1} \leq t < T_n\}$, we have

$$\mathbf{E}\{S_{T_{t}\wedge u}^{B} - S_{t}^{B} | \mathcal{F}_{t}^{\Theta}\} = \sum_{n\geq 1} \mathbf{1}_{\{T_{n-1}\leq t< T_{n}\}} \mathbf{E}\{\mathbf{1}_{\{T_{n}\leq u\}}\mathbf{1}_{\{X_{n}\in B\}}X_{n} | \mathcal{F}_{t}^{\Theta}\}, \quad (25)$$

and one obtains

$$\mathbf{E}\{S_{T_t \wedge u}^B - S_t^B \,|\, \mathcal{F}_t^\Theta\} = \sum_{n \ge 1} \mathbf{1}_{\{T_{n-1} \le t < T_n\}} J_n^{t,u}(\Theta, (T_i, X_i)_{i \le n-1}), \qquad (26)$$

where

$$J_n^{t,u}(\Theta, (T_i, X_i)_{i \le n-1})$$

$$= \int_t^u \left(\int_B x g_s(x; \Theta, (T_i, X_i)_{i \le n-1}) \gamma(dx) \right)$$

$$\lambda_s(\Theta, (T_i, X_i)_{i \le n-1}) e^{-\int_t^s \lambda_r(\Theta, (T_i, X_i)_{i \le n-1}) dr} ds .$$

$$(27)$$

Especially, we have the following result:

2.2 Proposition. Suppose that the integrability condition (20) holds. (a) If $((T_n, X_n))_{n\geq 1}$ is a mixed Markovian risk process (see (14) and (15), then

$$\mathbf{E}\{S^B_{T_t \wedge u} - S^B_t \mid \mathcal{F}^{\Theta}_t\} = \sum_{n \ge 1} \mathbb{1}_{\{T_{n-1} \le t < T_n\}} \int_t^u \Big(\int_B x g^{(n)}_s(x;\Theta) \gamma(dx) \Big) \lambda^{(n)}_s(\Theta) e^{-\int_t^s \lambda^{(n)}_r(\Theta) \, dr} \, ds \,. \tag{28}$$

Thus - in case that $((T_n, X_n))_{n \ge 1}$ is homogeneous -

$$\mathbf{E} \{ S^{B}_{T_{t} \wedge u} - S^{B}_{t} \mid \mathcal{F}^{\Theta}_{t} \}$$

$$= \sum_{n \ge 1} \mathbb{1}_{\{T_{n-1} \le t < T_{n}\}} \left(1 - e^{-(u-t)\lambda^{(n)}(\Theta)} \right) \left(\int_{B} x g^{(n)}(x;\Theta) \gamma(dx) \right).$$
(29)

(b) If $((T_n, X_n))_{n\geq 1}$ is a mixed inhomogeneous Poisson risk process, then

$$\mathbf{E}\{S^B_{T_t \wedge u} - S^B_t \,|\, \mathcal{F}^{\Theta}_t\} = \int_t^u \Big(\int_B x g_s(x;\Theta) \gamma(dx)\Big) \lambda_s(\Theta) e^{-\int_t^s \lambda_r(\Theta) \, dr} \, ds \,, \quad (30)$$

and in case of a homogeneous Poisson risk process

$$\mathbf{E}\{S^B_{T_t \wedge u} - S^B_t \,|\, \mathcal{F}^{\Theta}_t\} = \left(1 - e^{-(u-t)\lambda(\Theta)}\right) \left(\int_B xg(x;\Theta)\gamma(dx)\right). \tag{31}$$

In the next (and last) prediction problem we replace the deterministic time points tand u by the stopping times T_{n-1} and T_n , and consider the prediction of $X_n \mathbb{1}_{\{X_n \in B\}}$ given $\mathcal{F}_{T_{n-1}}^{\Theta}$. This means that we determine

$$\mathbf{E}\{X_{n}1_{\{X_{n}\in B\}} | \mathcal{F}_{T_{n-1}}^{\Theta}\} = \mathbf{E}\{X_{n}1_{\{X_{n}\in B\}} | \Theta, (T_{i}, X_{i})_{i\leq n-1}\}$$

From (7) we obtain

$$\mathbf{E} \{ X_{n} \mathbf{1}_{\{X_{n} \in B\}} | \mathcal{F}_{T_{n-1}}^{\Theta} \} \\
= \int_{T_{n-1}}^{\infty} \int_{B} x \, G_{\Theta,(T_{i},X_{i})_{i \leq n-1}}^{(n-1,1)}(t,x) \gamma(dx) \, dt \\
= \int_{T_{n-1}}^{\infty} \left(\int_{B} x \, g_{t}(x;\Theta,(T_{i},X_{i})_{i \leq n-1}) \gamma(dx) \right) \\
\lambda_{t}(\Theta,(T_{i},X_{i})_{i \leq n-1}) e^{-\int_{T_{n-1}}^{t} \lambda_{r}(\Theta,(T_{i},X_{i})_{i \leq n-1}) dr} \, dt \, .$$
(32)

This implies for our examples of mixed risk processes the following proposition:

2.3 Proposition. Suppose that the integrability condition (20) holds. (a) If $((T_n, X_n))_{n\geq 1}$ is a mixed Markovian risk process, then

$$\mathbf{E}\{X_n \mathbf{1}_{\{X_n \in B\}} \mid \mathcal{F}_{T_{n-1}}^{\Theta}\}$$

$$= \int_{T_{n-1}}^{\infty} \left(\int_B x g_t^{(n)}(x;\Theta) \gamma(dx) \right) \lambda_t^{(n)}(\Theta) e^{-\int_{T_{n-1}}^t \lambda_r^{(n)}(\Theta) \, dr} \, dt \, .$$
(33)

Thus - in case that $((T_n, X_n))_{n\geq 1}$ is homogeneous -

$$\mathbf{E}\{X_n \mathbf{1}_{\{X_n \in B\}} \mid \mathcal{F}_{T_{n-1}}^{\Theta}\} = \int_B x g^{(n)}(x; \Theta) \gamma(dx) .$$
(34)

(b) If $((T_n, X_n))_{n\geq 1}$ is a mixed inhomogeneous Poisson risk process, then

$$\mathbf{E}\{X_n \mathbf{1}_{\{X_n \in B\}} \mid \mathcal{F}_{T_{n-1}}^{\Theta}\} = \int_{T_{n-1}}^{\infty} \left(\int_B x g_t(x;\Theta) \gamma(dx)\right) \lambda_t(\Theta) e^{-\int_{T_{n-1}}^t \lambda_r(\Theta) \, dr} \, dt \, (35)$$

and in case of a mixed homogeneous Poisson risk process

$$\mathbf{E}\{X_n \mathbf{1}_{\{X_n \in B\}} \mid \mathcal{F}_{T_{n-1}}^{\Theta}\} = \int_B xg(x;\Theta)\gamma(dx) .$$
(36)

3 Filtering

In this section we filter the prediction formulas of the foregoing section relative to sub- σ -algebras \mathcal{G}_t of $\mathcal{F}_t^{\mathcal{N}}$ (resp. sub- σ -algebras $\mathcal{G}_{T_{n-1}}$ of $\mathcal{F}_{T_{n-1}}^{\mathcal{N}}$). First we consider filtering relative to $\mathcal{F}_t^{\mathcal{N}}$.

Let us make the following **convention:** Below there will often occur - in connection with conditional expectations - quotients of the form

$$\frac{F(x)}{G(x)}$$

where it may happen that the denominator G(x) is zero. In that case the value of that quotient is defined to be zero.

The following lemma will be the basis of most of the results in this section.

3.1 Lemma. Suppose that $F = F(\Theta, (T_i, X_i)_{i \le n-1})$ is integrable. Then for every $t \ge 0$ and every $n \ge 1$ the following filtering formula holds on the set $\{T_{n-1} \le t < T_n\}$:

$$\mathbf{E}\{F(\Theta, (T_i, X_i)_{i \le n-1}) \,|\, \mathcal{F}_t^{\mathcal{N}}\} = \frac{\Phi_t^{n, F}((T_i, X_i)_{i \le n-1})}{\Psi_t^n((T_i, X_i)_{i \le n-1})},$$
(37)

-

with

$$\Phi_{t}^{n,F}((T_{i}, X_{i})_{i \leq n-1})$$

$$= \int_{T} \left\{ F(y, (T_{i}, X_{i})_{i \leq n-1}) e^{-\int_{T_{n-1}}^{t} \lambda_{r}(y, (T_{i}, X_{i})_{i \leq n-1}) dr} \\ G^{(n-1)}(y, (T_{i}, X_{i})_{i \leq n-1}) \right\} \beta(dy)$$
(38)

and

$$\Psi_{t}^{n}((T_{i}, X_{i})_{i \leq n-1})$$

$$= \int_{T} \left\{ e^{-\int_{T_{n-1}}^{t} \lambda_{r}(y, (T_{i}, X_{i})_{i \leq n-1}) dr} \\ G^{(n-1)}(y, (T_{i}, X_{i})_{i \leq n-1}) \right\} \beta(dy) .$$
(39)

Proof. Let H be an arbitrary bounded, $\mathcal{F}_t^{\mathcal{N}}$ -measurable function. Since $H = H((T_i, X_i)_{i \leq n-1})$ on $\{T_{n-1} \leq t < T_n\}$ (cf. Dettweiler [2004]), we obtain from (4)

$$\int_{\Omega} 1_{\{T_{n-1} \le t < T_n\}} H F(\Theta, (T_i, X_i)_{i \le n-1}) d\mathbf{P}$$

$$= \int_{T} \left(\int_{0}^{t} \int_{E} \cdots \int_{t_{n-2}}^{t} \int_{E} \int_{t}^{\infty} \left\{ H((t_i, x_i)_{i \le n-1}) F(y, (t_i, x_i)_{i \le n-1}) \right\}$$

$$= G^{(n-1)}(y, (t_i, x_i)_{i \le n-1}) \lambda_{t_n}(y, (t_i, x_i)_{i \le n-1}) + G^{(n-1)}(y, (t_i, x_i)_{i \le n-1}) \lambda_{t_n}(y, (t_i, x_i)_{i \le n-1}) + G^{-\int_{t_{n-1}}^{t_n} \lambda_r(y, (t_i, x_i)_{i \le n-1}) dr} dt_n \gamma(dx_{n-1}) dt_{n-1} \cdots \gamma(dx_1) dt_1 \beta(dy)$$

$$\begin{split} &= \int_{T} \Big(\int_{0}^{t} \int_{E} \cdots \int_{t_{n-2}}^{t} \int_{E} \Big\{ H((t_{i}, x_{i})_{i \leq n-1}) F(y, (t_{i}, x_{i})_{i \leq n-1}) \\ &\quad G^{(n-1)}(y, (t_{i}, x_{i})_{i \leq n-1}) e^{-\int_{t_{n-1}}^{t} \lambda_{r}(y, (t_{i}, x_{i})_{j \leq n-1}) dr} \Big\} \\ &\quad \gamma(dx_{n-1}) dt_{n-1} \cdots \gamma(dx_{1}) dt_{1} \Big) \beta(dy) \\ &= \int_{0}^{t} \int_{E} \cdots \int_{t_{n-2}}^{t} \int_{E} H((t_{i}, x_{i})_{i \leq n-1}) \\ &\quad \Big(\int_{T} \Big\{ F(y, (t_{i}, x_{i})_{i \leq n-1}) e^{-\int_{t_{n-1}}^{t} \lambda_{r}(y, (t, x_{i})_{i \leq n-1}) dr} \\ &\quad G^{(n-1)}(y, (t_{i}, x_{i})_{i \leq n-1}) \Big\} \beta(dy) \Big) \gamma(dx_{n-1}) dt_{n-1} \cdots \gamma(dx_{1}) dt_{1} \\ &= \int_{0}^{t} \int_{E} \cdots \int_{t_{n-2}}^{t} \int_{E} \Big\{ H((t_{i}, x_{i})_{i \leq n-1}) \\ &\quad \Phi_{t}^{n,F}((t_{i}, x_{i})_{i \leq n-1}) \Big\} \gamma(dx_{n-1}) dt_{n-1} \cdots \gamma(dx_{1}) dt_{1} \\ &= \int_{0}^{t} \int_{E} \cdots \int_{t_{n-2}}^{t} \int_{E} \Big\{ H((t_{i}, x_{i})_{i \leq n-1}) \\ &\quad \Psi_{t}^{n}((t_{i}, x_{i})_{i \leq n-1}) \Big\} \gamma(dx_{n-1}) dt_{n-1} \cdots \gamma(dx_{1}) dt_{1} \\ &= \int_{T} \Big(\int_{0}^{t} \int_{E} \cdots \int_{t_{n-2}}^{t} \int_{E} \int_{E} \int_{t}^{\infty} \Big\{ H((t_{i}, x_{i})_{i \leq n-1}) \\ &\quad \Psi_{t}^{n}((t_{i}, x_{i})_{i \leq n-1}) \Big\} \gamma(dx_{n-1}) dt_{n-1} \cdots \gamma(dx_{1}) dt_{1} \\ &= \int_{T} \Big(\int_{0}^{t} \int_{E} \cdots \int_{t_{n-2}}^{t} \int_{E} \int_{T} \int_{0}^{\infty} \Big\{ H((t_{i}, x_{i})_{i \leq n-1}) \\ &\quad \Psi_{t}^{n}((t_{i}, x_{i})_{i \leq n-1}) \Big\} dt_{n} \gamma(dx_{n-1}) dt_{n-1} \cdots \gamma(dx_{1}) dt_{1} \Big\} \beta(dy) \\ &= \int_{\Omega} \mathbb{1}_{\{T_{n-1} \leq t < T_{n}\}} H \frac{\Phi_{t}^{n,F}((T_{i}, X_{i})_{i \leq n-1})}{\Psi_{t}^{n}((T_{i}, X_{i})_{i \leq n-1})} d\mathbf{P} \,. \end{split}$$

Since

$$1_{\{T_{n-1} \le t < T_n\}} \frac{\Phi_t^{n,F}((T_i, X_i)_{i \le n-1})}{\Psi_t^n((T_i, X_i)_{i \le n-1})}$$

is $\mathcal{F}_t^{\mathcal{N}}$ -measurable, the assertion of the lemma is proved.

The lemma could be applied quite general to the prediction formula (16). Thus we would get

$$\mathbf{E}\{Z_{u} \mid \mathcal{F}_{t}^{\mathcal{N}}\} = \sum_{n \ge 1} \mathbb{1}_{\{T_{n-1} \le t < T_{n}\}} \sum_{k \ge 1} \frac{\Phi_{t}^{n, I_{n,k}^{t, u}}((T_{i}, X_{i})_{i \le n-1})}{\Psi_{t}^{n}((T_{i}, X_{i})_{i \le n-1})} .$$
(40)

We will not pursue this general setting.

As a first concrete application, we compute the prediction of $S_u^B - S_t^B$ given \mathcal{F}_t^N for mixed Poisson processes(cf. proposition 2.1). We remark that for a mixed inhomogeneous Poisson process the density $G^{(n-1)}$ is given by

$$G^{(n-1)}(y,(t_i,x_i)_{i\leq n-1}) = e^{-\int_0^{t_{n-1}}\lambda_r(y)dr} \prod_{i=1}^{n-1} \left(g_{t_i}(x_i;y)\lambda_{t_i}(y)\right), \quad (41)$$

and for a mixed homogeneous Poisson process we have

$$G^{(n-1)}(y,(t_i,x_i)_{i\leq n-1}) = \lambda(y)^{n-1}e^{-t_{n-1}\lambda(y)}\prod_{i=1}^{n-1}g(x_i;y).$$
(42)

Thus the following results follow immediately from lemma 3.1

3.2 Proposition. Suppose that $((T_n, X_n))_{n\geq 1}$ is a mixed inhomogeneous Poisson risk process, for which the integrability assumption (20) holds. Then

$$\mathbf{E}\{S_{u}^{B} - S_{t}^{B} \mid \mathcal{F}_{t}^{\mathcal{N}}\} = \sum_{n \ge 1} \mathbf{1}_{\{T_{n-1} \le t < T_{n}\}} \frac{\Phi_{t,u}^{n,B}((T_{i}, X_{i})_{i \le n-1})}{\Psi_{t}^{n}((T_{i}, X_{i})_{i \le n-1})}, \quad (43)$$

with

$$\Phi_{t,u}^{n,B}((T_i, X_i)_{i \le n-1}) = \int_T \left\{ \left(\int_t^u \int_B x g_s(x; y) \lambda_s(y) \gamma(dx) ds \right) e^{-\int_0^t \lambda_r(y) dr} \right. (44) \\ \prod_{i=1}^{n-1} \left(g_{T_i}(X_i; y) \lambda_{T_i}(y) \right) \right\} \beta(dy) ,$$

and

$$\Psi_t^n((T_i, X_i)_{i \le n-1}) = \int_T e^{-\int_0^t \lambda_r(y) \, dr} \prod_{i=1}^{n-1} \left(g_{T_i}(X_i; y) \lambda_{T_i}(y) \right) \Big\} \beta(dy) \,.$$
(45)

If $((T_n, X_n))_{n \ge 1}$ is a mixed homogeneous Poisson risk process, then

$$\mathbf{E}\{S_{u}^{B} - S_{t}^{B} | \mathcal{F}_{t}^{\mathcal{N}}\} = \sum_{n \ge 1} \mathbb{1}_{\{T_{n-1} \le t < T_{n}\}} \frac{\Phi_{t,u}^{n,B}((X_{i})_{i \le n-1})}{\Psi_{t}^{n}((X_{i})_{i \le n-1})},$$
(46)

with

$$\Phi_{t,u}^{n,B}((X_i)_{i\leq n-1})$$

$$= (u-t) \int_T \left\{ \left(\int_B xg(x;y) \gamma(dx) \right) \lambda(y)^n e^{-t\lambda(y)} \prod_{i=1}^{n-1} g(X_i;y) \right\} \beta(dy)$$

$$(47)$$

and

$$\Psi_t^n((X_i)_{i \le n-1}) = \int_T \left\{ \lambda(y)^{n-1} e^{-t\lambda(y)} \prod_{i=1}^{n-1} g(X_i; y) \right\} \beta(dy) .$$
(48)

Remark. Suppose that the measure γ is a probability measure. Then the intensity measure Λ^* , defined by

$$\lambda_t^*(B) := \gamma(B) , \qquad (49)$$

is extremely simple, and it is not difficult to see that there is a probability measure \mathbf{P}^* on (Ω, \mathcal{F}) , such that relative to \mathbf{P}^* the risk process $(T_n, X_n)_{n \geq 1}$ has the \mathbf{F}^{Θ} -intensity measure Λ^* . It is easily proved (cf. also Brémaud [1981]) that the restriction of the original probability measure **P** to \mathcal{F}_t^{Θ} is absolutely continuous relative to the restriction of **P**^{*} to \mathcal{F}_t^{Θ} and has the Radon-Nikodym-density L_t , given by

$$L_t = e^t e^{-\int_{t_{n-1}}^t \lambda_r(\Theta, (T_i, X_i)_{i \le n-1}) dr} G^{(n-1)}(\Theta, (T_i, X_i)_{i \le n-1})$$
(50)

on $\{T_{n-1} \leq t < T_n\}$. It follows that (43) is just the formula

$$\mathbf{E}_{\mathbf{P}}\{S_u^B - S_t^B \mid \mathcal{F}_t^{\mathcal{N}}\} = \frac{\mathbf{E}_{\mathbf{P}^*}\{(S_u^B - S_t^B)L_t \mid \mathcal{F}_t^{\mathcal{N}}\}}{\mathbf{E}_{\mathbf{P}^*}\{L_t \mid \mathcal{F}_t^{\mathcal{N}}\}},$$
(51)

which is well known in the literature (cf. Brémaud [1981]). We will not pursue this idea (i.e. using a type of Girsanov transformation for prediction), since our formulas are immediate consequences from the construction of marked point processes.

In connection with the above theorem we consider a related prediction problem, which occurs, if for the given time point t there is only the information on

$$\{T_{n-1} \le t < T_n\}$$
, and $(X_i)_{i \le n-1}$ $(n \ge 1)$.

available. To model this situation we set

$$\mathcal{G}_{t}^{n} := \sigma(\{1_{\{T_{n-1} \le t < T_{n}\}}, X_{1}, \cdots, X_{n-1}\})$$

$$= \sigma(\{\{T_{n-1} \le t < T_{n}\} \cap \bigcap_{j=1}^{n-1} \{X_{j} \in B_{j}\} \mid B_{j} \in \mathcal{E} \ (1 \le j \le n-1)\})$$
(52)

and

$$\mathcal{G}_t := \bigvee_{n \ge 1} \mathcal{G}_t^n .$$
(53)

For the filtering relative to \mathcal{G}_t the following lemma is proved similarly as lemma 3.1.

3.4 Lemma. Suppose that $F = F(\Theta, (T_i, X_i)_{i \le n-1})$ is integrable. Then for every $t \ge 0$ and every $n \ge 1$ the following filtering formula holds on $\{T_{n-1} \le t < T_n\}$:

$$\mathbf{E}\{F(\Theta, (T_i, X_i)_{i \le n-1}) \mid \mathcal{G}_t\} = \mathbf{E}\{F(\Theta, (T_i, X_i)_{i \le n-1}) \mid \mathcal{G}_t^n\}$$

$$= \frac{\overline{\Phi}_t^{n, F}(X_i)_{i \le n-1}}{\overline{\Psi}_t^n((X_i)_{i \le n-1})}, \quad with$$
(54)

$$\overline{\Phi}_{t}^{n,F}((X_{i})_{i\leq n-1}) = \int_{T} \int_{0}^{t} \cdots \int_{t_{n-2}}^{t} \left\{ F(y,(t_{i},X_{i})_{i\leq n-1})e^{-\int_{t_{n-1}}^{t} \lambda_{r}(y,(t_{i},X_{i})_{i\leq n-1})dr} \\ G^{(n-1)}(y,(t_{i},X_{i})_{i\leq n-1}) \right\} dt_{n-1} \cdots dt_{1}\beta(dy)$$

and

$$\overline{\Psi}_{t}^{n}((X_{i})_{i\leq n-1}) = \int_{T} \int_{0}^{t} \cdots \int_{t_{n-2}}^{t} \left\{ e^{-\int_{t_{n-1}}^{t} \lambda_{r}(y,(t_{i},X_{i})_{i\leq n-1}) dr} \\ G^{(n-1)}(y,(t_{i},X_{i})_{i\leq n-1}) \right\} dt_{n-1} \cdots dt_{1}\beta(dy) .$$

If we apply this lemma to the filtering of $\mathbf{E}\{S_u^B - S_t^B | \mathcal{F}_t^\Theta\}$ relative to \mathcal{G}_t for mixed Poisson risk processes we get:

3.5 Proposition. Suppose that $((T_n, X_n))_{n\geq 1}$ is a mixed inhomogeneous Poisson risk process, for which the integrability assumption (20) holds. Then

$$\mathbf{E}\{S_{u}^{B} - S_{t}^{B} \,|\, \mathcal{G}_{t}\} = \sum_{n \ge 1} \mathbf{1}_{\{T_{n-1} \le t < T_{n}\}} \frac{\overline{\Phi}_{t,u}^{B}((X_{i})_{i \le n-1})}{\overline{\Psi}_{t}((X_{i})_{i \le n-1})} , \qquad (55)$$

with

$$\overline{\Phi}_{t,u}^{n,B}((X_i)_{i\leq n-1}) = \int_T \int_0^t \cdots \int_{t_{n-2}}^t \left\{ \left(\int_t^u \int_B xg_s(x;y)\lambda_s(y)\gamma(dx)ds \right) e^{-\int_0^t \lambda_r(y)\,dr} \\ \prod_{i=1}^{n-1} \left(g_{t_i}(X_i;y)\lambda_{t_i}(y) \right) \right\} dt_{n-1} \cdots dt_1 \beta(dy) ,$$

and

$$\overline{\Psi}_{t}^{n}((X_{i})_{i\leq n-1}) = \int_{T} \int_{0}^{t} \cdots \int_{t_{n-2}}^{t} e^{-\int_{0}^{t} \lambda_{r}(y) dr} \prod_{i=1}^{n-1} \left(g_{t_{i}}(X_{i};y) \lambda_{t_{i}}(y) \right) \Big\} dt_{n-1} \cdots dt_{1} \beta(dy) .$$

If $((T_n, X_n))_{n \ge 1}$ is a mixed homogeneous Poisson risk process, then (cf. proposition 3.2)

$$\mathbf{E}\{S_u^B - S_t^B \mid \mathcal{F}_t^{\mathcal{N}}\} = \mathbf{E}\{S_u^B - S_t^B \mid \mathcal{G}_t\}.$$
(56)

Now we consider the filtering of $\mathbf{E}\{S^B_{T_t \wedge u} - S^B_t | \mathcal{F}^{\Theta}_t\}$ relative to $\mathcal{F}^{\mathcal{N}}_t$ and also to \mathcal{G}_t . Using the formula (26) we get from lemma 3.1 and lemma 3.4 the following general result:

3.6 Proposition. Let $((T_n, X_n))_{n\geq 1}$ be a mixed risk process with regular \mathbf{F}^{Θ} intensity measure Λ and suppose that $S^B_{T_t \wedge u} - S^B_t$ is integrable. If $J^{t,u}_n$ is defined
by (27), then

$$\mathbf{E}\{S^{B}_{T_{t}\wedge u} - S^{B}_{t} \,|\, \mathcal{F}^{\mathcal{N}}_{t}\} = \sum_{n \ge 1} \mathbf{1}_{[T_{n-1}, T_{n}[}(t) \frac{\Phi^{n}_{t, u}((T_{i}, X_{i})_{i \le n-1})}{\Psi^{n}_{t}((T_{i}, X_{i})_{i \le n-1})},$$
(57)

where $\Phi_{t,u}^n$ and Ψ_t^n are given by

$$\Phi_{t,u}^{n}((T_{i},X_{i})_{i\leq n-1}) = \int_{T} \left\{ J_{t,u}^{n}(y,(T_{i},X_{i})_{i\leq n-1})e^{-\int_{t_{n-1}}^{t} \lambda_{r}(y,(T_{i},X_{i})_{i\leq n-1})dr} G^{(n-1)}(y,(T_{i},X_{i})_{i\leq n-1}) \right\} \beta(dy)$$

and

$$\Psi_t^n((T_i, X_i)_{i \le n-1}) = \int_T \Big\{ e^{-\int_{t_{n-1}}^t \lambda_r(y, (T_i, X_i)_{i \le n-1}) dr} G^{(n-1)}(y, (T_i, X_i)_{i \le n-1}) \Big\} \beta(dy)$$

For the filtering relative to \mathcal{G}_t we have

$$\mathbf{E}\{S_{T_t \wedge u}^B - S_t^B \,|\, \mathcal{G}_t\} = \sum_{n \ge 1} \mathbf{1}_{[T_{n-1}, T_n[}(t) \frac{\overline{\Phi}_{t, u}^n((X_i)_{i \le n-1})}{\overline{\Psi}_t^n((X_i)_{i \le n-1})},$$
(58)

where $\overline{\Phi}_{t,u}^n$ and $\overline{\Psi}_t^n$ are given by

$$\overline{\Phi}_{t,u}^{n}((X_{i})_{i\leq n-1}) = \int_{T} \int_{0}^{t} \cdots \int_{t_{n-2}}^{t} \left\{ J_{t,u}^{n}(y, (t_{i}, X_{i})_{i\leq n-1})e^{-\int_{t_{n-1}}^{t} \lambda_{r}(y, (t_{i}, X_{i})_{i\leq n-1})dr} G^{(n-1)}(y, (t_{i}, X_{i})_{i\leq n-1}) \right\} dt_{n-1} \cdots dt_{1}\beta(dy)$$

and

$$\overline{\Psi}_{t}^{n}((X_{i})_{i\leq n-1}) = \int_{T} \int_{0}^{t} \cdots \int_{t_{n-2}}^{t} \left\{ e^{-\int_{t_{n-1}}^{t} \lambda_{r}(y,(t_{i},X_{i})_{i\leq n-1})dr} \\ G^{(n-1)}(y,(t_{i},X_{i})_{i\leq n-1}) \right\} dt_{n-1} \cdots dt_{1}\beta(dy) .$$

The above general result can easily be applied to more special mixed risk processes. We just give two examples.

3.7 Proposition. Let $((T_n, X_n))_{n\geq 1}$ be a mixed risk process such that $S^B_{T_t \wedge u} - S^B_t$ is integrable. (a) If $((T_n, X_n))_{n\geq 1}$ is a mixed homogeneous Markovian risk process, then

$$\mathbf{E}\{S_{T_t \wedge u}^B - S_t^B \,|\, \mathcal{F}_t^{\mathcal{N}}\} = \sum_{n \ge 1} \mathbf{1}_{[T_{n-1}, T_n[}(t) \frac{\Phi_{t, u}^n((T_i, X_i)_{i \le n-1})}{\Psi_t^n((T_i, X_i)_{i \le n-1})},$$
(59)

with

$$\Phi_{t,u}^{n}((T_{i}, X_{i})_{i \leq n-1}) = \int_{T} \left\{ \left((1 - e^{-(u-t)\lambda^{(n)}(y)}) \int_{B} x g^{(n)}(x, y) \gamma(dx) \right) e^{-(t-T_{n-1})\lambda^{(n)}(y)} \\ e^{-\sum_{i=1}^{n-1} (T_{i}-T_{i-1})\lambda^{(i)}(y)} \prod_{i=1}^{n-1} \left(g^{(i)}(x; y)\lambda^{(i)}(y) \right) \right\} \beta(dy)$$

and

$$\Psi_{t,u}^{n}((T_{i}, X_{i})_{i \leq n-1}) = \int_{T} \left\{ e^{-(t-T_{n-1})\lambda^{(n)}(y)} e^{-\sum_{i=1}^{n-1} (T_{i}-T_{i-1})\lambda^{(i)}(y)} \\ \prod_{i=1}^{n-1} \left(g^{(i)}(x; y)\lambda^{(i)}(y) \right) \right\} \beta(dy) .$$

Similarly,

$$\mathbf{E}\{S_{T_t \wedge u}^B - S_t^B \,|\, \mathcal{G}_t\} = \sum_{n \ge 1} \mathbb{1}_{[T_{n-1}, T_n[}(t) \frac{\overline{\Phi}_{t, u}^n((X_i)_{i \le n-1})}{\overline{\Psi}_t^n((X_i)_{i \le n-1})}, \qquad (60)$$

with

$$\overline{\Phi}_{t,u}^{n}((X_{i})_{i\leq n-1}) = \int_{T} \left\{ \left((1 - e^{-(u-t)\lambda^{(n)}(y)}) \int_{B} xg^{(n)}(x,y)\gamma(dx) \right) \prod_{i=1}^{n-1} \left(g^{(i)}(x;y)\lambda^{(i)}(y) \right) \right. \\ \left. \left(\int_{0}^{t} \cdots \int_{t_{n-2}}^{t} e^{-(t-t_{n-1})\lambda^{(n)}(y) - \sum_{i=1}^{n-1}(t_{i}-t_{i-1})\lambda^{(i)}(y)} dt_{n-1} \cdots dt_{1} \right) \right\} \beta(dy)$$

and

$$\overline{\Psi}_{t,u}^{n}((X_{i})_{i\leq n-1}) = \int_{T} \left\{ \prod_{i=1}^{n-1} \left(g^{(i)}(x;y)\lambda^{(i)}(y) \right) \\ \left(\int_{0}^{t} \cdots \int_{t_{n-2}}^{t} e^{-(t-t_{n-1})\lambda^{(n)}(y) - \sum_{i=1}^{n-1} (t_{i}-t_{i-1})\lambda^{(i)}(y)} dt_{n-1} \cdots dt_{1} \right) \right\} \beta(dy) .$$

(b) If $((T_n, X_n))_{n \ge 1}$ is a mixed homogeneous Poisson risk process, then

$$\mathbf{E}\{S^{B}_{T_{t}\wedge u} - S^{B}_{t} | \mathcal{F}^{\mathcal{N}}_{t}\} = \mathbf{E}\{S^{B}_{T_{t}\wedge u} - S^{B}_{t} | \mathcal{G}_{t}\}$$

$$= \sum_{n\geq 1} \mathbb{1}_{\{T_{n-1}\leq t< T_{n}\}} \frac{\Phi^{n}_{t,u}((X_{i})_{i\leq n-1})}{\Psi^{n}_{t}((X_{i})_{i\leq n-1})},$$
(61)

with

$$\begin{split} \Phi_{t,u}^{n}((X_{i})_{i\leq n-1}) &= \int_{T} \Big\{ \Big(1 - e^{-(u-t)\lambda(y)} \Big) \\ &\int_{B} xg(x;y) \,\gamma(dx)\lambda(y)^{n-1} e^{-t\lambda(y)} \prod_{i=1}^{n-1} g(X_{i};y) \Big\} \beta(dy) \end{split}$$

and

$$\Psi_t((X_i)_{i \le n-1}) = \int_T \left\{ \lambda(y)^{n-1} e^{-t\lambda(y)} \prod_{i=1}^{n-1} g(X_i; y) \right\} \beta(dy) .$$

Now we consider the prediction of $X_n 1_{\{X_n \in B\}}$ given

$$\mathcal{G}_{T_{n-1}} = \sigma(\{X_1, \cdots, X_{n-1}\}),$$

i.e. the filtering of $\mathbf{E}\{X_n \mathbb{1}_{\{X_n \in B\}} \mid \mathcal{F}_{T_{n-1}}^{\Theta}\}$ relative to $\mathcal{G}_{T_{n-1}}$. If we write

$$J^n(\Theta, (T_i, X_i)_{i \le n-1})$$

for the right hand side of equation (32), we have the following general result:

3.8 Theorem. Let $((T_n, X_n))_{n\geq 1}$ be a mixed risk process with regular \mathbf{F}^{Θ} -intensity measure and suppose that $X_n \mathbf{1}_{\{X_n \in B\}}$ is integrable. Then

$$\mathbf{E}\{X_{n} \mathbf{1}_{\{X_{n} \in B\}} | (X_{i})_{i \leq n-1}\} = \frac{\overline{\Phi}_{n}((X_{i})_{i \leq n-1})}{\overline{\Psi}_{n}((X_{i})_{i \leq n-1})}$$
(62)

with

$$\overline{\Phi}_{n}((X_{i})_{i\leq n-1}) = \int_{T} \int_{0}^{\infty} \cdots \int_{t_{n-2}}^{\infty} \left\{ J^{n}(y, (t_{i}, X_{i})_{i\leq n-1}) \right\} dt_{n-1} \cdots dt_{1}\beta(dy) ,$$

and

$$\overline{\Psi}_n((X_i)_{i \le n-1}) = \int_T \int_0^\infty \cdots \int_{t_{n-2}}^\infty \left\{ G^{(n-1)}(y, (t_i, X_i)_{i \le n-1}) \right\} dt_{n-1} \cdots dt_1 \beta(dy) .$$

This result can easily be applied to special mixed risk processes. Thus we get e.g.: **3.9 Proposition**. (a) If $(T_n, X_n)_{n \ge 1}$ is a mixed Markovian risk process, then

$$J^{n}(y,(t_{i},x_{i})_{i\leq n-1}) = J^{n}(y,t_{n-1})$$

$$= \int_{t_{n-1}}^{\infty} \left(\int_{B} xg_{t_{n}}^{(n)}(x;y)\gamma(dx) \right) \lambda_{t_{n}}^{(n)}(y) e^{-\int_{t_{n-1}}^{t_{n}} \lambda_{s}^{(n)}(y)ds} dt_{n} ,$$
(63)

and

$$\mathbf{E}\{X_{n}\mathbf{1}_{\{X_{n}\in B\}} \mid (X_{i})_{1\leq i\leq n-1}\}$$

$$= \frac{\int_{T} \int_{0}^{\infty} \cdots \int_{t_{n-2}}^{\infty} J^{n}(y, t_{n-1})G^{(n-1)}(y, (t_{i}, X_{i})_{i\leq n-1})dt_{n-1} \cdots dt_{1}\beta(dy)}{\int_{T} \int_{0}^{\infty} \cdots \int_{t_{n-2}}^{\infty} G^{(n-1)}(y, (t_{i}, X_{i})_{i\leq n-1})dt_{n-1} \cdots dt_{1}\beta(dy)} ,$$
(64)

where

$$G^{(n-1)}(y,(t_i,x_i)_{i\leq n-1}) = \prod_{i=1}^{n-1} g_{t_i}^{(i)}(x;y)\lambda_{t_i}^{(i)}(y)e^{-\int_{t_{i-1}}^{t_i}\lambda_s^{(i)}(y)ds}$$

If $(T_n, X_n)_{n \ge 1}$ is homogeneous, then

$$J^{n}(y, t_{n-1}) = J^{n}(y) = \int_{B} xg^{(n)}(x; y)\gamma(dx)$$

and

$$\mathbf{E}\{X_{n}\mathbf{1}_{\{X_{n}\in B\}} | (X_{i})_{i\leq n-1}\} = \frac{\int_{T} \left\{ \int_{B} xg^{(n)}(x;y)\gamma(dx) \prod_{i=1}^{n-1} g^{(i)}(X_{i};y) \right\} \beta(dy)}{\int_{T} \left\{ \prod_{i=1}^{n-1} g^{(i)}(X_{i};y) \right\} \beta(dy)}.$$
(65)

(b) If $(T_n, X_n)_{n\geq 1}$ is a mixed homogeneous Poisson risk process, then

$$\mathbf{E}\{X_{n}\mathbf{1}_{\{X_{n}\in B\}} \mid (X_{i})_{i\leq n-1}\} = \frac{\int_{T} \left\{ \int_{B} xg^{(x)}(x;y)\gamma(dx) \prod_{i=1}^{n-1} g(X_{i};y) \right\} \beta(dy)}{\int_{T} \left\{ \prod_{i=1}^{n-1} g(X_{i};y) \right\} \beta(dy)}.$$
(66)

Proof. Formula (64) follows immediately from theorem 3.8. We just prove (65), which implies (66). From (64) we have

$$\mathbf{E}\{X_{n} 1_{\{X_{n} \in B\}} | (X_{i})_{i \leq n-1}\} = \frac{\overline{\Phi}_{n}((X_{i})_{i \leq n-1})}{\overline{\Psi}_{n}((X_{i})_{i \leq n-1})}$$

with

$$\overline{\Phi}_{n}((X_{i})_{i\leq n-1}) = \int_{T} \left\{ \left(\int_{0}^{\infty} \cdots \int_{t_{n-2}}^{\infty} \{ \prod_{i=1}^{n-1} \lambda^{(i)}(y) e^{-(t_{i}-t_{i-1})\lambda^{(i)}(y)} \} dt_{n-1} \cdots dt_{1} \right) \right. \\ \left. \int_{B} x g^{(n)}(x;y) \gamma(dx) \prod_{i=1}^{n-1} g^{(i)}(X_{i};y) \right\} \beta(dy)$$

and a similar formula for $\overline{\Psi}_n((X_i)_{1 \le i \le n-1})$. Thus (65) follows, since

$$\int_0^\infty \cdots \int_{t_{n-2}}^\infty \{\prod_{i=1}^{n-1} \lambda^{(i)}(y) e^{-(t_i - t_{i-1})\lambda^{(i)}(y)} \} dt_{n-1} \cdots dt_1 = 1$$

for every $y \in T$.

Remark. At a first glance the formulas (65) and (66) may a little bit surprise, since there is no dependence on the distributions of the claim arrival times T_1, \dots, T_{n-1} . But the reason is simple: The prediction of $X_n \mathbb{1}_{\{X_n \in B\}}$ given X_1, \dots, X_{n-1} replaces the natural time by the time points T_1, \dots, T_{n-1} and the independence of $(T_n)_{n\geq 1}$ and $(X_n)_{n\geq 1}$ reduces the prediction to a prediction problem for the discrete time process $(X_n)_{n\geq 1}$. The situation becomes quite different, if we consider the prediction of $X_n \mathbb{1}_{\{X_n \in B\}}$ given $(T_i, X_i)_{i\leq n-1}$:

Suppose that $((T_n, X_n))_{n \ge 1}$ is a mixed homogeneous Poisson risk process. Then

$$\mathbf{E}\{X_{n}\mathbf{1}_{\{X_{n}\in B\}} | (T_{i}, X_{i})_{i\leq n-1}\} = \mathbf{E}\{X_{n}\mathbf{1}_{\{X_{n}\in B\}} | T_{n-1}, X_{1}, \cdots, X_{n-1}\} = \frac{\int_{T}\{\left(\int_{B} xg(x; y)\gamma(dx)\right)e^{-T_{n-1}\lambda(y)}\lambda(y)^{n-1}\prod_{i=1}^{n-1}g(X_{i}; y)\}\beta(dy)}{\int_{T}\{e^{-T_{n-1}\lambda(y)}\lambda(y)^{n-1}\prod_{i=1}^{n-1}g(X_{i}; y)\}\beta(dy)}.$$
(67)

Since an increase of information gives surely more reliable prediction, formula (67) should be better than (65) in case there is the information on T_{n-1} .

As a last filtering problem we consider the problem of filtering the intensity measure Λ relative to $\mathbf{F}^{\mathcal{N}}$. It will turn out that the filtered intensity measure $\tilde{\Lambda}$ is again regular. We have the following general result, which follows easily from lemma 3.1:

3.11 Theorem. Suppose that the intensities $\lambda_t(B)$ ($t \ge 0$ and $B \in \mathcal{E}$) are integrable. Then the following formula holds:

$$\mathbf{E}\{\lambda_t(B) \mid \mathcal{F}_t^{\mathcal{N}}\} = \sum_{n \ge 1} \mathbf{1}_{[T_{n-1}, T_n[}(t)\tilde{\lambda}_t(B; (T_i, X_i)_{i \le n-1})), \qquad (68)$$

with

$$\tilde{\lambda}_t(B; (T_i, X_i)_{i \le n-1}) = \frac{\phi_t(B; (T_i, X_i)_{i \le n-1})}{\theta_t((T_i, X_i)_{i \le n-1})},$$
(69)

where ϕ_t and θ_t are given by (cf. (5))

$$\phi_t(B; (t_i, x_i)_{i \le n-1}) = \int_T \left\{ \int_B g_t(x; y, (t_i, x_i)_{i \le n-1}) \gamma(dx) \lambda_t(y, (t_i, x_i)_{i \le n-1}) \right. \\ \left. e^{-\int_{t_{n-1}}^t \lambda_r(y, (t_i, x_i)_{i \le n-1}) dr} G^{(n-1)}(y, (t_i, x_i)_{i \le n-1}) \right\} \beta(dy) ,$$

and

$$\theta_t((t_i, x_i)_{i \le n-1}) = \int_T \left\{ e^{-\int_{t_{n-1}}^t \lambda_r(y, (t_i, x_i)_{i \le n-1}) dr} G^{(n-1)}(y, (t_i, x_i)_{i \le n-1}) \right\} \beta(dy) ,$$

for $0 < t_1 < \cdots < t_{n-1}$ and $x_1, \cdots, x_{n-1} \in E$.

The $\mathbf{F}^{\mathcal{N}}$ -intensity measure

$$\tilde{\Lambda} = \left((\tilde{\lambda}_t(B))_{t \ge 0} \right)_{B \in \mathcal{E}}$$
(70)

given by (69) has a similar structure as the \mathbf{F}^{Θ} -intensity measure Λ . On the set $\{T_{n-1} \leq t < T_n\}$ we have

$$\tilde{\lambda}_t(dx; (T_i, X_i)_{i \le n-1}) = \tilde{\gamma}_t(dx; (T_i, X_i)_{i \le n-1}) \cdot \tilde{\lambda}_t((T_i, X_i)_{i \le n-1}), \quad (71)$$

where

$$\tilde{\lambda}_t((T_i, X_i)_{i \le n-1}) = \frac{\phi_t(E; (T_i, X_i)_{i \le n-1})}{\theta_t((T_i, X_i)_{i \le n-1})},$$
(72)

and where the probability measure $\tilde{\gamma}_t(dx; (T_i, X_i)_{i \leq n-1})$ has a density

 $\tilde{g}_t(x; (T_i, X_i)_{i \le n-1})$

relative to $\gamma(dx)$, which is given as follows:

We set for $x \in E$

$$\widetilde{\phi}_{t}(x;(t_{i},x_{i})_{i\leq n-1}) = \int_{T} \left\{ g_{t}(x;y,(t_{i},x_{i})_{i\leq n-1})\lambda_{t}(y,(t_{i},x_{i})_{i\leq n-1}) \\
e^{-\int_{t_{n-1}}^{t}\lambda_{r}(y,(t_{i},x_{i})_{i\leq n-1})dr} G^{(n-1)}(y,(t_{i},x_{i})_{i\leq n-1}) \right\} \beta(dy) ,$$
(73)

and choose a fixed, measurable $g^*: E \to \mathbb{R}_+$ such that $g^* \cdot \gamma$ is a probability measure. Then

$$\tilde{g}_t(x; (T_i, X_i)_{i \le n-1}) = \frac{\tilde{\phi}_t(x; (T_i, X_i)_{i \le n-1})}{\phi_t(E; (T_i, X_i)_{i \le n-1})} \mathbf{1}_{\{\phi_t(E; (T_i, X_i)_{i \le n-1}) > 0\}} + g^*(x) \mathbf{1}_{\{\phi_t(E; (T_i, X_i)_{i \le n-1}) = 0\}}.$$
(74)

3.12 Corollary. Let $((T_n, X_n))_{n\geq 1}$ be a mixed homogeneous Poisson risk process with the regular \mathbf{F}^{Θ} -intensity measure Λ given by (10) and (11). Then

$$\tilde{\lambda}_t(dx; (t_n, x_n)_{n \ge 0}) = \sum_{n \ge 1} \mathbf{1}_{[t_{n-1}, t_n[}(t) \tilde{\lambda}_t(dx; (t_i, x_i)_{i \le n-1})$$

with

$$\tilde{\lambda}_t(dx; (t_i, x_i)_{i \le n-1}) = \tilde{g}_t(x; (t_i, x_i)_{i \le n-1}) \gamma(dx) \tilde{\lambda}_t((t_i, x_i)_{i \le n-1}) , \qquad (75)$$

where

$$\tilde{\lambda}_t((t_i, x_i)_{i \le n-1}) = \frac{\int_T \prod_{i=1}^{n-1} g(x_i; y) \,\lambda(y)^n e^{-t\lambda(y)} \,\beta(dy)}{\int_T \prod_{i=1}^{n-1} g(x_i; y) \,\lambda(y)^{n-1} e^{-t\lambda(y)} \,\beta(dy)}$$

and

$$\tilde{g}_t(x; (t_i, x_i)_{i \le n-1}) = \frac{\int_T g(x; y) \prod_{i=1}^{n-1} g(x_i; y) \lambda(y)^n e^{-t\lambda(y)} \beta(dy)}{\int_T \prod_{i=1}^{n-1} g(x_i; y) \lambda(y)^n e^{-t\lambda(y)} \beta(dy)}.$$

Remark. It is well known (cf. e.g. Schmidt [1996]) that the filtering of a mixed Poisson process gives a Markov process. Corollary 3.12 shows that the filtering of a mixed Poisson risk process gives no longer a Markovian risk process.

3.14 Corollary. Let $((T_n, X_n))_{n\geq 1}$ be a mixed inhomogeneous Poisson risk process with the regular \mathbf{F}^{Θ} -intensity measure Λ given by (12) and (13). Then

$$\tilde{\lambda}_t(dx; (t_n, x_n)_{n \ge 0}) = \sum_{n \ge 1} \mathbf{1}_{[t_{n-1}, t_n[}(t) \tilde{\lambda}_t(dx; (t_i, x_i)_{i \le n-1})$$

with

$$\tilde{\lambda}_t(dx; (t_i, x_i)_{i \le n-1}) = \tilde{g}_t(x; (t_i, x_i)_{i \le n-1}) \gamma(dx) \tilde{\lambda}_t((t_i, x_i)_{i \le n-1}) , \qquad (76)$$

where

$$\tilde{\lambda}_{t}((t_{i}, x_{i})_{i \leq n-1}) = \frac{\int_{T} \prod_{i=1}^{n-1} \left(g_{t_{i}}(x_{i}; y) \,\lambda_{t_{i}}(y) \right) e^{-\int_{0}^{t} \lambda_{s}(y) \, ds} \,\beta(dy)}{\int_{T} \prod_{i=1}^{n-1} \left(g_{t_{i}}(x_{i}; y) \,\lambda_{t_{i}}(y) \right) e^{-\int_{0}^{t} \lambda_{s}(y) \, ds} \,\beta(dy)}$$

and

$$\tilde{g}_{t}(x;(t_{i},x_{i})_{i\leq n-1}) = \frac{\int_{T} g_{t}(x;y)\lambda_{t}(y)\prod_{i=1}^{n-1} g_{t_{i}}(x_{i};y)\lambda_{t_{i}}(y)e^{-\int_{0}^{t}\lambda_{s}(y)\,ds}\,\beta(dy)}{\int_{T}\prod_{i=1}^{n-1} \left(g_{t_{i}}(x_{i};y)\lambda_{t_{i}}(y)\right)e^{-\int_{0}^{t}\lambda_{s}(y)\,ds}\,\beta(dy)}$$

We omit the corresponding filtering result for the mixed Markovian risk process.

Theorem 3.11 has the following interpretation:

3.15 Proposition. Let $((T_n, X_n))_{n \ge 1}$ be an integrable, mixed risk process with regular \mathbf{F}^{Θ} -intensity measure

$$\Lambda = \left((\lambda_t(B))_{t \ge 0} \right)_{B \in \mathcal{E}} ,$$

and let

$$\tilde{\Lambda} = \left((\tilde{\lambda}_t(B))_{t \ge 0} \right)_{B \in \mathcal{E}} ,$$

be the intensity measure defined in theorem 3.11. Then $((T_n, X_n))_{n\geq 1}$ has the intensity measure $\tilde{\Lambda}$ for the filtration $\mathbf{F}^{\mathcal{N}}$.

Proof. We have to prove that for every $B \in \mathcal{E}$ the process

$$\left(N_t(B) - \int_0^t \tilde{\lambda}_s \, ds\right)_{t \ge 0}$$

is an $\mathbf{F}^{\mathcal{N}}\text{-martingale.}$ This follows, since for $0 \leq s < t$

$$\mathbf{E}\{N_t(B) - N_s(B) \mid \mathcal{F}_s^{\mathcal{N}}\} = \mathbf{E}\{\mathbf{E}\{N_t(B) - N_s(B) \mid \mathcal{F}_s^{\Theta}\} \mid \mathcal{F}_s^{\mathcal{N}}\}$$

$$= \mathbf{E}\{\mathbf{E}\{\int_s^t \lambda_r \, dr \mid \mathcal{F}_s^{\Theta}\} \mid \mathcal{F}_s^{\mathcal{N}}\}$$

$$= \mathbf{E}\{\int_s^t \lambda_r \, dr \mid \mathcal{F}_s^{\mathcal{N}}\}$$

$$= \mathbf{E}\{\int_s^t \tilde{\lambda}_r \, dr \mid \mathcal{F}_s^{\mathcal{N}}\} .$$

Remark. Proposition 3.15 could be used to compute directly the prediction formulas relative to $\mathcal{F}_t^{\mathcal{N}}$ proved in this section. But this looks much more complicated than the method of first predicting relative to \mathcal{F}_t^{Θ} and then filtering relative to $\mathcal{F}_t^{\mathcal{N}}$.

4 Prediction of the Claim Amount Distribution

The prediction problems of the foregoing sections are only a first step to get some insight into the future behaviour of mixed risk processes. One should have in mind that e.g. the prediction of the first claim amount

$$X_{t,u} := S_{T_t \wedge u} - S_t \quad (S_t = S_t^E)$$

in the planning period [t, u] is just a mean value on the basis of the informations given by $\mathcal{F}_t^{\mathcal{N}}$. For more reliable information one should not only consider the prediction of this mean value, but also (at least theoretically) the prediction of the distribution of $X_{t,u}$. Suppose that this distribution is given by

$$P_{t,u}(dz; \mathcal{F}_t^{\mathcal{N}}) . \tag{77}$$

Then one can easily predict in addition the "distance" $d(X_{(t)}, \varphi_t)$ to some given $\mathcal{F}_t^{\mathcal{N}}$ measurable function φ_t [one could imagine that φ_t is (connected with) the individual premium predicted by the last section]. This prediction would simply be given by the formula

$$\mathbf{E}\{d(X_{t,u},\varphi_t) \,|\, \mathcal{F}_t^{\mathcal{N}}\} = \int_E d(z,\varphi_t) P_{t,u}(dz;\mathcal{F}_t^{\mathcal{N}}) \,. \tag{78}$$

Such a distance $d(\cdot, \cdot)$ could be the euclidian distance

$$d_2(z,v) := (z-v)^2$$
. (79)

Thus for $\varphi_t = \mathbf{E}\{X_{t,u} | \mathcal{F}_t^{\mathcal{N}}\}\$ the prediction of $d_2(X_{t,u}, \varphi_t)$ is just the prediction of the conditional variance of $X_{t,u}$ given $\mathcal{F}_t^{\mathcal{N}}$. But there are also other "distances" (which are even more important): We set for a given $\varepsilon > 0$

$$d_{\varepsilon}(z,v) := \mathbf{1}_{\{z \ge v + \varepsilon\}}, \qquad (80)$$

and

$$d_{+}(z,v) := (z-v)_{+} .$$
(81)

Then the prediction of $d_{\varepsilon}(X_{t,u}, \varphi_t)$ e.g. is just the conditional probability of $\{X_{t,u} \geq \varphi_t + \varepsilon\}$ given $\mathcal{F}_t^{\mathcal{N}}$.

The formulas for the prediction of the claim amount distribution are derived similarly as the prediction formulas for $X_{t,u}$. Analogously to proposition 3.6 we get

4.1 Theorem. Let $((T_n, X_n))_{n\geq 1}$ be a integrable, mixed risk process with regular \mathbf{F}^{Θ} -intensity measure

$$\Lambda = \left((\lambda_t(B))_{t \ge 0} \right)_{B \in \mathcal{E}} ,$$

and define for $0 \le t < u, n \ge 1, y \in T, 0 < t_1 < \dots < t_{n-1}, x_1, \dots, x_{n-1} \in E$ and $A \in \mathcal{E}$

$$J_{n}^{t,u}(A; y, (t_{i}, x_{i})_{i \leq n-1}) = \int_{t}^{u} \left(\int_{A} g_{t_{n}}(x; y, (t_{i}, x_{i})_{i \leq n-1}) \gamma(dx) \right)$$

$$\lambda_{t_{n}}(y, (t_{i}, x_{i})_{i \leq n-1}) e^{-\int_{t}^{t_{n}} \lambda_{s}(y, (t_{i}, x_{i})_{i \leq n-1}) ds} dt_{n}$$

$$+ 1_{A}(0) e^{-\int_{t}^{u} \lambda_{s}(y, (t_{i}, x_{i})_{i \leq n-1}) ds} .$$
(82)

Then

$$\mathbf{P}\{X_{t,u} \in A \,|\, \mathcal{F}_t^{\mathcal{N}}\} = \sum_{n \ge 1} \mathbf{1}_{[T_{n-1}, T_n[}(t) \frac{\Phi_n^{t,u}(A; (T_i, X_i)_{i \le n-1})}{\Psi_n^t((T_i, X_i)_{i \le n-1})},$$
(83)

where $\Phi_n^{t,u}(A)$ and Ψ_n^t are given by

$$\begin{split} \Phi_n^{t,u}(A;(T_i,X_i)_{i\leq n-1}) &= \int_T \Big\{ J_n^{t,u}(A;y,(T_i,X_i)_{i\leq n-1}) e^{-\int_{t_{n-1}}^t \lambda_r(y,(T_i,X_i)_{i\leq n-1})dr} \\ & G^{(n-1)}(y,(T_i,X_i)_{i\leq n-1}) \Big\} \beta(dy) \;, \end{split}$$

and

$$\Psi_n^t((T_i, X_i)_{i \le n-1}) = \int_T \left\{ e^{-\int_{t_{n-1}}^t \lambda_r(y, (T_i, X_i)_{i \le n-1}) dr} G^{(n-1)}(y, (T_i, X_i)_{i \le n-1}) \right\} \beta(dy) .$$

Thus we have the formula

$$P_{t,u}(dz; \mathcal{F}_t^{\mathcal{N}}) = \sum_{n \ge 1} \mathbb{1}_{[T_{n-1}, T_n[}(t) \frac{\Phi_n^{t,u}(dz; (T_i, X_i)_{i \le n-1})}{\Psi_n^t((T_i, X_i)_{i \le n-1})} .$$
(84)

Proof. Since

$$X_{t,u} = \sum_{n \ge 1} \mathbb{1}_{\{T_{n-1} \le t < T_n\}} X_n \mathbb{1}_{\{T_n \le u\}} ,$$

we have

$$\{X_{t,u} \in A\} \cap \{T_{n-1} \le t < T_n\} = \{X_n \mathbb{1}_{\{T_n \le u\}} \in A\} \cap \{T_{n-1} \le t < T_n\}.$$

If $0 \notin A$, then

$$\{X_n 1_{\{T_n \le u\}} \in A\} = \{X_n \in A\} \cap \{T_n \le u\},\$$

and if $0 \in A$, then

$$\{X_n 1_{\{T_n \le u\}} \in A\} = (\{X_n \in A\} \cap \{T_n \le u\}) \cup \{u < T_n\}$$

where the union on the right hand side clearly is disjoint. Altogether we have

$$1_{\{X_{t,u} \in A\}} = \sum_{n \ge 1} 1_{\{T_{n-1} \le t < T_n\}} \left(1_{\{X_n \in A\} \cap \{T_n \le u\}} + 1_A(0) 1_{\{u < T_n\}} \right).$$

Thus the prediction of $1_{\{X_{t,u} \in A\}}$ given \mathcal{F}_t^{Θ} is given by (cf. section 2, esp. (27))

$$\mathbf{E}\{\mathbf{1}_{\{X_{t,u}\in A\}} \mid \mathcal{F}_{t}^{\Theta}\} = \sum_{n\geq 1} \mathbf{1}_{\{T_{n-1}\leq t< T_{n}\}} J_{n}^{t,u}(A;\Theta,(t_{i},x_{i})_{i\leq n-1}),$$

where $J_n^{t,u}$ is defined by (82). An application of lemma 3.1 then proves (83).

Thus we get for example, if d denotes one of the "distances" introduced above, the following prediction formula:

4.2 Corollary. Let φ_t be $\mathcal{F}_t^{\mathcal{N}}$ -measurable and suppose that $d(X_{t,u}, \varphi_t)$ is integrable. Then

$$\mathbf{E}\{d(X_{t,u},\varphi_t) \,|\, \mathcal{F}_t^{\mathcal{N}}\} = \mathbf{1}_{\{T_{n-1} \leq t < T_n\}} \frac{\Phi_n^{t,u}(G; (T_i, X_i)_{i \leq n-1})}{\Psi_n^t((T_i, X_i)_{i \leq n-1})} ,$$

where

and where $\Phi_n^{t,u}(G)$ is defined analogously to $\Phi_n^{t,u}(A)$ (with $J_n^{t,u}(A)$ replaced by $G_n^{t,u}$).

Of course, there are corresponding results for

$$P_{t,u}(dz; \mathcal{G}_t) := \mathbf{P}\{X_{t,u} \in dz \,|\, \mathcal{G}_t\}, \qquad (85)$$

where \mathcal{G}_t was defined in (53). Corresponding results also hold for

$$P_n(dz; (T_i, X_i)_{i \le n-1}) := \mathbf{P}\{X_n \in dz \,|\, \mathcal{F}_{T_{n-1}}\}$$
(86)

or

$$P_n(dz; (X_i)_{i \le n-1}) := \mathbf{P}\{X_n \in dz \mid X_1, \cdots, X_{n-1}\}.$$

(cf. theorem 3.8 and proposition 3.9).

For the mixed Poisson risk process we have the following corollary from theorem 4.1:

4.3 Corollary. Let $((T_n, X_n))_{n\geq 1}$ be a mixed homogeneous Poisson risk process with densities g_t and intensities λ_t given by (10) and (11), and define for $A \in \mathcal{E}$, and $y \in T$

$$H(A,y) := \int_A g(x;y)\gamma(dx) .$$

Then the following prediction formula holds:

$$\mathbf{P}\{X_{t,u} \in A \,|\, \mathcal{F}_t^{\mathcal{N}}\} = \sum_{n \ge 1} \mathbf{1}_{\{T_{n-1} \le t < T_n\}} \frac{\Phi_n^{t,u}(A; (X_i)_{1 \le i \le n-1})}{\Psi_n^t((X_i)_{1 \le i \le n-1})} ,$$

with

$$\Phi_n^{t,u}(A;(x_i)_{1 \le i \le n-1}) = \int_T \left\{ H(A,y)(1 - e^{-(u-t)\lambda(y)}) e^{-t\lambda(y)} \lambda(y)^{n-1} \prod_{i=1}^{n-1} g(x_i;y) \right\} \beta(dy) + 1_A(0) e^{-(u-t)\lambda(y)} ,$$

and

$$\Psi_t^n((x_i)_{1 \le i \le n-1}) = \int_T \left\{ e^{-t\lambda(y)} \lambda(y)^{n-1} \prod_{i=1}^{n-1} g(x_i; y) \right\} \beta(dy) .$$

Thus we have

$$P_{t,u}(dz; \mathcal{F}_t^{\mathcal{N}}) = \sum_{n \ge 1} \mathbb{1}_{\{T_{n-1} \le t < T_n\}} \frac{\Phi_n^{t,u}(dz; (X_i)_{i \le n-1})}{\Psi_n^t((X_i)_{i \le n-1})} .$$

Let us suppose that φ_t only depends on X_1, \dots, X_{n-1} on the set $\{T_{n-1} \leq t < T_n\}$, which is the case, if

$$\varphi_t = \mathbf{E}\{X_{t,u} \,|\, \mathcal{F}_t^{\mathcal{N}}\}$$

- (cf. (61). Then we obtain from the corollary the following two examples:
- (1) For the distance d_+ we have

$$\mathbf{E}\{d_{+}(X_{t,u},\varphi_{t}) \mid \mathcal{F}_{t}^{\mathcal{N}}\} = \sum_{n \ge 1} \mathbb{1}_{\{T_{n-1} \le t < T_{n}\}} \frac{\int_{E} d_{+}(z,\varphi_{t}((X_{i})_{i \le n-1})) \Phi_{n}^{t}(dz;(X_{i})_{i \le n-1})}{\Psi_{n}^{t}((X_{i})_{i \le n-1})}$$

,

where

$$\begin{split} \int_{E} d_{+}(z,\varphi_{t}((X_{i})_{i\leq n-1}))\Phi_{n}^{t}(dz;(X_{i})_{i\leq n-1}) \\ &= \int_{T} \left\{ \left(\int_{E} d_{+}(x,\varphi_{t}((X_{i})_{i\leq n-1}))g(x;y)\gamma(dx) \right) \\ & (1-e^{-(u-t)\lambda(y)})e^{-t\lambda(y)}\lambda(y)^{n-1} \prod_{i=1}^{n-1} g(x_{i};y) \right\} \beta(dy) \; . \end{split}$$

(2) For the distance d_{ε} we have

$$\mathbf{P}\{X_{t,u} \ge \varphi_t + \varepsilon \,|\, \mathcal{F}_t^{\mathcal{N}}\} \\ = \sum_{n\ge 1} \mathbb{1}_{\{T_{n-1}\le t < T_n\}} \frac{\int_E d_\varepsilon(z, \varphi_t((X_i)_{i\le n-1})) \Phi_n^t(dz; (X_i)_{i\le n-1})}{\Psi_n^t((X_i)_{i\le n-1})} ,$$

where

$$\begin{split} \int_E d_{\varepsilon}(z,\varphi_t((X_i)_{i\leq n-1}))\Phi_n^t(dz;(X_i)_{i\leq n-1}) \\ &= \int_T \left\{ \left(\int_E \mathbf{1}_{[\varphi_t((X_i)_{i\leq n-1})+\varepsilon[}(x)g(x;y)\gamma(dx) \right) \\ & (1-e^{-(u-t)\lambda(y)})e^{-t\lambda(y)}\lambda(y)^{n-1}\prod_{i=1}^{n-1}g(x_i;y) \right\} \beta(dy) \,. \end{split}$$

References

.

Brémaud, P. [1981]: Point Processes and Queues - Martingale Dynamics. Berlin – Heidelberg – New York: Springer.

Dettweiler, E. [2004]: Risk Processes. Leipzig: Edition am Gutenbergplatz.

Schmidt, K.D. [1996]: Lectures on Risk Theory. Stuttgart: Teubner.

Egbert Dettweiler Mathematisches Institut Universität Tübingen Auf der Morgenstelle 10 D–72076 Tübingen

 $E-mail: \ e.dettweiler@web.de$