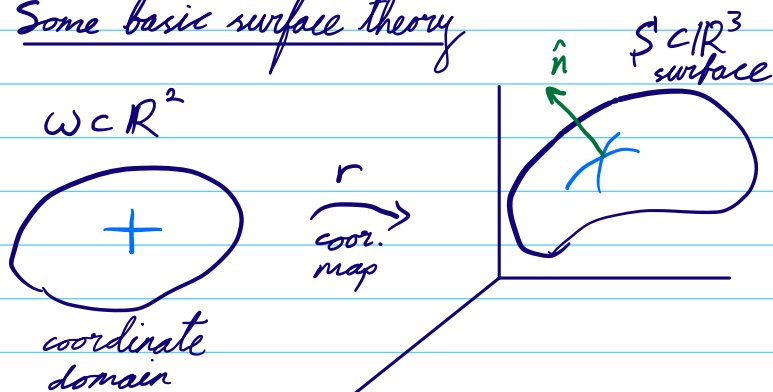


III Thin non-Euclidean elastic bodies

Some basic surface theory



$$\partial_i r \cdot \partial_j r = \bar{g}_{ij} \text{ (1st fund. form - distance on } S)$$

$$-\partial_i r \cdot \partial_j n = \bar{\Pi}_{ij} \text{ (2nd fund. form - change of normal on } S)$$

\bar{g} & $\bar{\Pi}$ satisfy the Gauss-Codazzi equations:

Gauss: $\bar{K} = \frac{\det \bar{\Pi}}{\det \bar{g}}$, \bar{K} = second order in \bar{g}

Codazzi: $\nabla_{[i} \bar{\Pi}_{j]k} = 0$, i.e. $\partial_2 \bar{\Pi}_{1k} - \partial_1 \bar{\Pi}_{2k} = \bar{\Pi}_{11} \Gamma_{k2}^1 + \bar{\Pi}_{12} (\Gamma_{k2}^2 - \Gamma_{1k}^1) - N \Gamma_{1k}^2$

\bar{g} & $\bar{\Pi}$ characterize S up to rigid motion:

Thm: If \bar{g} & $\bar{\Pi}$ satisfy GC and ω is simply connected, then there exists a unique immersed surface (up to rigid motion) S with forms $\bar{g}, \bar{\Pi}$.

Definition: \bar{g} and $\bar{\Pi}$ are symmetric (2,0) tensors on T_S .

The shape operator \bar{S} is a (1,1) tensor associated w. $\bar{\Pi}$, i.e.

$$\bar{g}(\bar{S}(v), w) = \bar{\Pi}(v, w), \text{ or } \bar{g}_{ik} \bar{S}_j^k = \bar{\Pi}_{ij}.$$

It can be easily verified that $\bar{S}(v) = -\nabla_v \hat{n}$.

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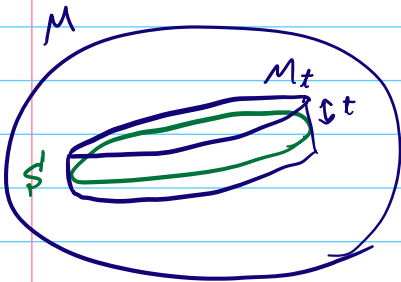
GC and
Riemann's
thm.

Remark: Define $\Omega = W \times (-\epsilon_0, \epsilon_0)$, and a metric \bar{G} on Ω by

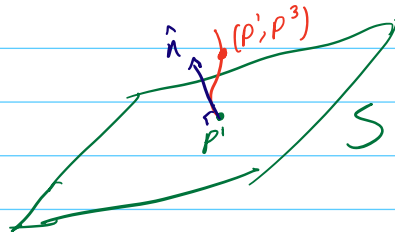
$$\bar{G}(x^1, x_3) = \left(\begin{array}{c|c} \bar{g}(x^1) - 2x_3 \bar{\mathbb{I}}(x^1) + x_3^2 \bar{S}(x^1) \bar{g}(x^1) \bar{S}(x^1) & \\ \hline & 1 \end{array} \right)$$

then \bar{g} & $\bar{\mathbb{I}}$ satisfy GC iff \bar{G} is flat, i.e. if (Ω, \bar{G}) can be (locally) isometrically-immersed in \mathbb{R}^3 .

In the other direction, given a 3-dim. manifold M , and a subman. S



the t -tubular neigh. of S , M_t , is obtained by going via normal geodesics up to time t :



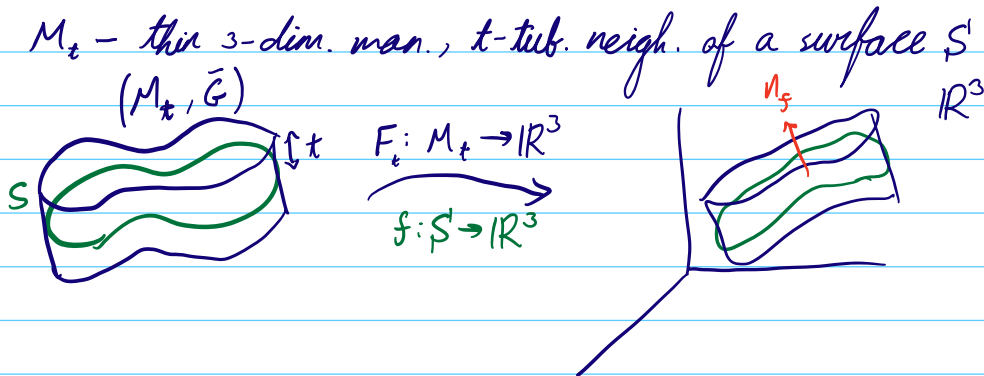
The metric \bar{G} , restricted to \bar{M}_t , satisfies the following expansion:

$$\bar{G}(p^1, p^3) = \left(\begin{array}{c|c} \bar{g}(p^1) - 2p^3 \bar{\mathbb{I}}(p^1) + O(|p^3|^2) & \\ \hline & 1 \end{array} \right)$$

where \bar{g} is the induced metric on S , and $\bar{\mathbb{I}} = \mathbb{I}_{S, M}$ is the second form of S in M .

\bar{g} & $\bar{\mathbb{I}}$ satisfy Gauss-Codazzi iff $R^{\bar{G}}(x, y) = 0 \forall x, y \in TS$, i.e.,
if $R_{12ij}^{\bar{G}}|_S = 0$.

Elastic energy - formal asymptotics



Assume $F_t(p', p^3) = f(p') + p^3 n_f(p')$, and that $W(A) = \text{dist}^2(A, SO(3))$

Then, formally,

$$E_{M_t}(F_t) = \int_S \underbrace{\text{dist}^2(Df \circ \bar{q}^{-1/2}, \overbrace{O(2,3)}^{\text{I}})}_{\text{stretching } E_S^{\text{str}}(f)} dV_{\bar{q}} + \frac{t^2}{3} \int_S \underbrace{|\nabla n_f + Df \circ \bar{S}|^2}_{\text{bending } t^2 E_S^{\text{bnd}}(f)} dV_{\bar{q}} + O(t^3)$$

$E_S(f)$ Kirchhoff shell energy

Remark: An alternative bending energy, which differs from the above by higher order terms, is

$$\frac{t^2}{3} \int_S |\Pi_f - \bar{\Pi}|^2 dV_{\bar{q}}$$

where $\Pi_f = Df^T \nabla n_f$.

While more common in the physics community, it is worse from analytic point of view, because of the product structure of Π_f .

Note that

$$\{f: S \rightarrow \mathbb{R}^3 \mid E_S(f) < \infty\} \stackrel{\text{implies existence}}{=} \{f \in W^{1,2}(S; \mathbb{R}^3) \mid \text{rk } Df = 2 \text{ a.e.}, n_f \in W^{1,2}(S; \mathbb{R}^3)\} =: \text{Imm}^2(S; \mathbb{R}^3)$$

Interesting "critical" Sobolev space, similar to $\{f \in W^{1,2}(S; \mathbb{R}^3) \mid \det Df > 0\}$

Open question: $\text{Imm}^2(S; \mathbb{R}^3) \subset C(S; \mathbb{R}^3)$? (This is true if $\nabla n_f = 0$)
 Goldstein, Šverák, ...
 Does Kirchhoff energy allow for cavitation?

Thm (AKM'22): $\inf E_S = 0 \Leftrightarrow \exists f \in \tilde{C}(S, \mathbb{R}^3)$ iso. imm w. forms $\bar{g}, \bar{\Pi}$.
 In particular, \bar{g} & $\bar{\Pi}$ satisfy GC.
 If S is simply-connected, this also implies $\inf E_S = 0$.

Skip

Pf (sketch): "undo the dimension reduction".

Define a manifold $M = S^x(-\varepsilon_0, \varepsilon_0)$ w. metric

$$\bar{G}_{(x', x_s)}((v, s), (w, r)) = \bar{g}_{x'}(v - s\bar{S}(v), w - r\bar{S}(w)) + sr.$$

Given $f \in \text{Imm}^2(S; \mathbb{R}^3)$, define $F \in W^{1,2}(M; \mathbb{R}^3)$ by

$$F(x', x^3) = f(x') + x^3 n_f(x')$$

Then $\int_M \text{dist}^2(DF \circ \bar{G}^{-\frac{1}{2}}, SO(3)) \leq C E_S(f)$.

Thus, $\inf E_S = 0$ implies $\inf E_M = 0$, and thus \exists smooth iso. imm.

$F: M \rightarrow \mathbb{R}^3$. $F|_{S^x \setminus \{0\}}$ is the wanted map. ▣

This only works for const. curv. target space. For general targets a direct approach is needed (AKM'23)

Non-Euclidean shells - rigorous limits

As $t \rightarrow 0$ we can see that stretching becomes infinitely costly compared to bending, thus we expect

$$\lim_{t \rightarrow 0} \frac{1}{t^2} E_{M_t} = \begin{cases} E_S^{bnd} & E_S^{str} = 0 \\ +\infty & E_S^{str} \neq 0 \end{cases}$$

Note that if $E_S^{str}(f) = 0$ then $Df^T Df = \bar{g}$ a.e., and thus

$$1) f \in \text{Imm}^2(S; \mathbb{R}^3) \Rightarrow f \in W_{\bar{g}}^{2,2}(S; \mathbb{R}^3), \text{ since } \partial_{ij} f = \bar{\Gamma}_{ij}^k \partial_k f - \bar{\Gamma}_{il}^k \bar{g}_{kj} \bar{g}^{lm} n_m$$

We denote this space by $W_{\bar{g}}^{2,2}(S; \mathbb{R}^3)$.

$$2) E_S^{bnd}(f) = \frac{1}{3} \int_S |\mathbb{I}_f - \bar{\mathbb{I}}|^2 dV_{\bar{g}}$$

Then (Sch'07, LP'11, BLS'16, KS'14): ← generalizations of FJM'02, FJMM'03

$$\bullet E_{M_t}(f_t) \leq Ct^2 \Rightarrow f_t \xrightarrow{W^{1,2}} f \in W_{\bar{g}}^{2,2}(S; \mathbb{R}^3) \quad (\text{after rescaling } \dots)$$

$$\bullet \frac{1}{t^2} E_{M_t} \xrightarrow{\Gamma} \begin{cases} E_S^{bnd}(f) & f \in W_{\bar{g}}^{2,2} \\ +\infty & \text{else} \end{cases}$$

Corollary:

(MS'19)

• $\inf E_{M_t} = O(t^2) \Leftrightarrow W_{\bar{g}}^{2,2}(S; \mathbb{R}^3) \neq \emptyset$

S simply-connected

• $\inf E_{M_t} = o(t^2) \Leftrightarrow \exists f \in W_{\bar{g}}^{1,2}(S; \mathbb{R}^3) \cap C^\infty, \mathbb{I}_f = \bar{\mathbb{I}} \Rightarrow \bar{g}, \bar{\mathbb{I}} \text{ satisfy GC}$

$\Leftrightarrow \inf E_{M_t} = O(t^4)$

• $\inf E_{M_t} = o(t^4) \Rightarrow R^{\bar{G}}|_S \equiv 0$ (follows from local estimate)

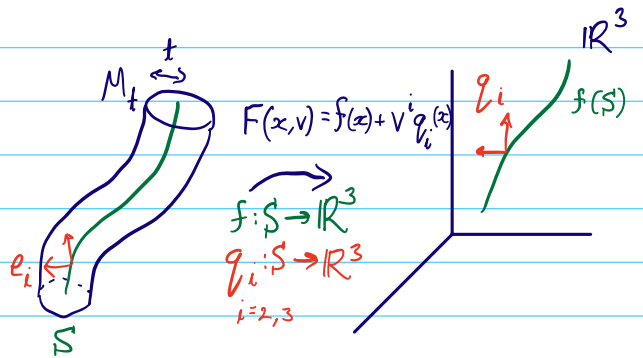
S simply conn.

Higher order scaling in Lewicka '20.

If time permits

Rods

For rods we have a different behavior



Thm (KS'14, Aharoni et al.'12):

• $E_{M_t}(f_t) \leq C t^2 \Rightarrow f_t \xrightarrow{W^{1,2}} f \in W^{1,2}(S; \mathbb{R}^3), Df_t \xrightarrow{L^2} (Df | q_2 | q_3) \in W^{1,2}(S; SO(\bar{G}))$

• $\frac{1}{t^2} E_{M_t} \xrightarrow{\Gamma} \left\{ \begin{array}{l} C | q_2^1 \cdot q_1 - \bar{\Gamma}_{12}^1 |^2 + | q_3^1 \cdot q_1 - \bar{\Gamma}_{13}^1 |^2 + | q_3^1 \cdot q_2 - \bar{\Gamma}_{13}^2 |^2 \\ + \infty \end{array} \right. \quad q \in SO(\bar{G})$

For $W(\cdot) = \text{dist}^2(\cdot, SO(3))$, round cross-section. Otherwise an equivalent energy

Since we can always solve $q' = \begin{pmatrix} 0 & -\bar{\Gamma}_{12}^1 & -\bar{\Gamma}_{13}^1 \\ \bar{\Gamma}_{12}^1 & 0 & -\bar{\Gamma}_{13}^2 \\ \bar{\Gamma}_{13}^1 & \bar{\Gamma}_{13}^2 & 0 \end{pmatrix} q$ (no compatibility conditions)

Cor (MS'19): • $\inf E_{M_t} = O(t^4)$

• $\inf E_{M_t} = o(t^4) \Rightarrow R^{\bar{G}}|_S \equiv 0.$

Summary:

Shells

Rods

Generic scaling of E_{M_t} :

$$t^2$$

$$t^4$$

Behavior of min:

$$\min \int |\Pi_f - \bar{\Pi}|^2$$

Π_f subject to GC

$$\Pi_f = \bar{\Pi}$$

(satisfy curvature, torsion)

if time permits

Comment: In KS'14 dimension reduction at the t^2 scaling is done

$$\text{for any } \underbrace{\dim S}_m < \underbrace{\dim M}_n \hookrightarrow \mathbb{R}^n \quad k = n - m$$

We can choose a orthonormal frame e_1, \dots, e_k of N_S , which induce coordinates on M s.t.

$$\langle \nabla_{\partial_i}^{\bar{G}} \partial_j, e_\alpha \rangle = (\Pi_\alpha)_{ij} \text{ second forms (sym. mat.)}$$

$$\langle \nabla_{\partial_i}^{\bar{G}} e_\alpha, e_\beta \rangle = (\tau_i)_{\alpha\beta} \text{ is the twist matrices (skew)}$$

Then we have

$$E_{M_t}(f_t) \leq C t^2 \Rightarrow f_t \xrightarrow{W^{1,2}} f \in W_{\mathcal{J}}^{1,2}(S; \mathbb{R}^n), Df \xrightarrow{L^2} (Df | \dot{q}^\perp) \in W^{1,2}(S; \mathfrak{so}(\bar{G}))$$

$\dot{q}^1, \dots, \dot{q}^k$

$$\Gamma\text{-}\lim_{t \rightarrow \infty} \frac{1}{t^2} E_{M_t} \stackrel{\text{if not } +\infty}{=} C(m, k) \int_S \sum_\alpha 2 |P_F^\perp \nabla_{\partial_i} \dot{q}_\alpha^\perp|^2 + |DF \cdot S_\alpha^{(k)}|^2 + |P_F^\perp \nabla_{\partial_i} \dot{q}_\alpha^\perp - \sum_\beta (\tau_i)_{\alpha\beta} \dot{q}_\beta^\perp|^2$$

\downarrow proj. on $T(F(S))$ \downarrow shape operator associated w. Π_α
 $\parallel \parallel N(F(S))$

for $W(\cdot) = \text{dist}(\cdot, \mathfrak{so}(n))$
and circular cross-section

Ribbons

ribbons interpolate between these behaviors

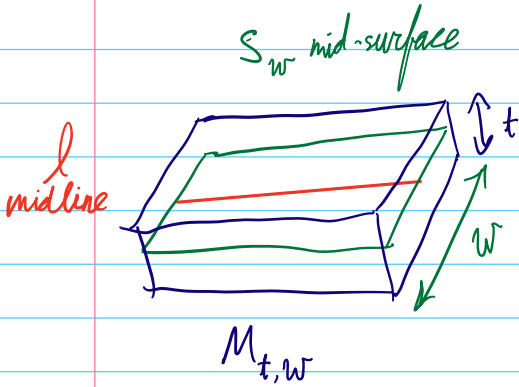
Summary:

Shells \longleftrightarrow Rods

Generic scaling of $E_{M,t}$: t^2 t^4

Behavior of min: $\min \int |\Pi_f - \bar{\Pi}|^2$ $\Pi_f = \bar{\Pi}$
 Π_f subject to GC (satisfy curvature, torsion)

Ribbons see the difference between Gauss & Codazzi



$$t \ll w \ll 1$$

Show examples

$$E_{t,w}(f) = \int_{M_{t,w}} \text{dist}^2(Df \circ \bar{G}^{-\frac{1}{2}}, SO(3)) dV_{\bar{G}}$$

$$E_{t,w}^{2D}(f) = \int_{S_w} \text{dist}^2(Df \circ \bar{g}^{-\frac{1}{2}}, SO(2,1)) dV_{\bar{g}} + t^2 \int_{S_w} |Dn_f + Df \circ \bar{S}|^2 dV_{\bar{g}}$$

$$\approx \int_{S_w} \underbrace{|Df^T Df - \bar{g}|^2}_{\bar{g}_f} dV_{\bar{g}} + t^2 \int_{S_w} \underbrace{|\Pi_f - \bar{\Pi}|^2}_{-Df^T Dn_f} dV_{\bar{g}}$$

Example 1: $S^w = (0, l) \times (-\frac{w}{2}, \frac{w}{2})$, $\bar{g} = \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix}$, $\bar{\Pi} = \begin{pmatrix} 0 & \lambda \\ \lambda & 0 \end{pmatrix}$

\times Gauss: $\det \bar{\Pi} = -\lambda^2$, $K_{\bar{g}} \det \bar{g} = 0$

\checkmark Codazzi: $\partial_i \Pi_{jk} = 0 = \partial_j \Pi_{ik}$ \rightarrow since $\nabla_i^{\bar{g}} = \partial_i$

$$\bar{g}_f = \begin{pmatrix} 1 - K_0(x_1)x_2 + O(x_2^2) & 0 \\ 0 & 1 \end{pmatrix}$$

\rightarrow Gaussian curvature of $f(S^w)$ along the midline.

Thus, formally,

$$E_{t,w}^{2D} = w^4 \int_L K_0^2(x_1) dx_1 + t^2 \int_L |\Pi_f(x_1,0) - \bar{\Pi}|^2 dx_1 + h.o.t$$

leading order constraint: $K_0(x_1) = \det \Pi_f(x_1,0)$

Cor: Wide ribbon ($t \ll w^2$) $K_0 \equiv 0$ $E_{t,w}^{2D} \sim t^2 \int_L |\Pi_f(x_1,0) - \begin{pmatrix} 0 & \lambda \\ \lambda & 0 \end{pmatrix}|^2 dx_1 \sim t^2 \lambda^2$
dev. surface \downarrow $\det \Pi_f = 0$

Narrow ribbon ($w^2 \ll t$) $\Pi_f(x_1,0) = \begin{pmatrix} 0 & \lambda \\ \lambda & 0 \end{pmatrix} \Rightarrow K_0 = -\lambda^2$ $E_{t,w}^{2D} \sim w^4 \lambda^4$
Pure twist

\Rightarrow transition @ $t \sim w^2$

Example 2: $S^W = (0, l) \times (-\frac{w}{2}, \frac{w}{2})$, $\bar{g} = \begin{pmatrix} (1-Kx_2)^2 & 0 \\ 0 & 1 \end{pmatrix}$, $\bar{\Pi} = \begin{pmatrix} 0 & 0 \\ 0 & \lambda \end{pmatrix}$

\checkmark Gauss: $\det \bar{\Pi} = 0 = K_{\bar{g}}$

\times Codazzi: $\nabla_2 \bar{\Pi}_{11} - \nabla_1 \bar{\Pi}_{21} = -\lambda K(1-Kx_2)^2 \neq 0$

$g_f = \begin{pmatrix} (1-Kx_2)^2 - K_0 x_2^2 + \frac{2}{3}(4K K_0 - K_1) x_2^3 + \dots & 0 \\ 0 & 1 \end{pmatrix}$ $\xrightarrow{K_0^{(x)} = K_{g_f}(x_1,0), K_1(x_1) = \partial_2 K_{g_f}(x_1,0)}$

It is always energetically favorable to respect the reference geodesic curvature of the mid-line

having $\Pi_f(x_1,0) = \bar{\Pi}$ is consistent with $K_0 = \bar{K} = 0$, but then

by Codazzi we get $\partial_2 \Pi_f(x_1,0) = -\lambda K$ hence $\Pi_f = \begin{pmatrix} -\lambda K x_2 & 0 \\ 0 & \lambda \end{pmatrix} + h.o.t.$

hence if $\Pi_f(x_1,0) = \bar{\Pi}$ we get $K_1 = -\lambda^2 K \neq 0$, i.e. effectively we have

$$E_{t,w}^{2D} = w^4 \int_L K_1^2(x_1) dx_1 + t^2 \int_L |\Pi_f(x_1,0) - \bar{\Pi}|^2 dx_1 + h.o.t.$$

cannot be simultaneously zero

Thus we expect transition between $\Pi_f = \bar{\Pi}$ for narrow ribbons $t \gg w^3$ and $K_f = O(x_2^2)$ for wide ribbons $t \ll w^3$.

However, it can be shown that the transition can be moved at least to $t \sim w^{\frac{8}{3}}$