

2.4. Linear maps on torus - Arnold's cat map

- dynamical system discrete in time \rightarrow map
- linear map: linear dynamics not just near fixed point, but everywhere

Can that be interesting?

- chaotic

- general concepts

• invariant manifolds

• homoclinic points

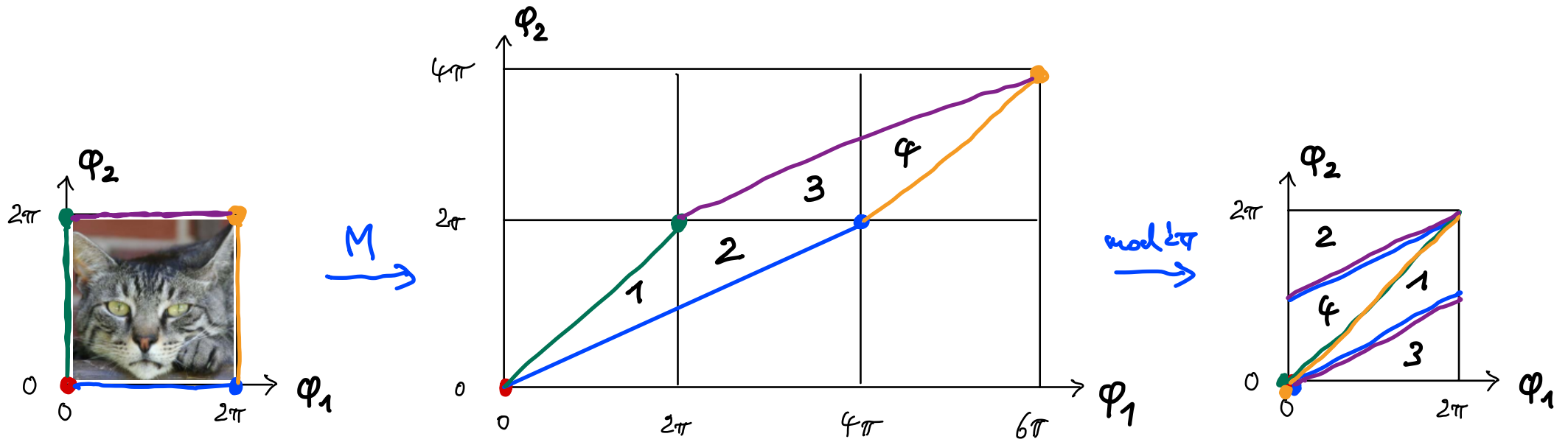
• periodic points

1-torus: $\varphi' = m \varphi \pmod{2\pi}$ volume cons.: $|m|=1$

2-torus:
$$\begin{pmatrix} \varphi_1' \\ \varphi_2' \end{pmatrix} = \underbrace{\begin{pmatrix} m_{11} & m_{12} \\ m_{21} & m_{22} \end{pmatrix}}_M \begin{pmatrix} \varphi_1 \\ \varphi_2 \end{pmatrix} \pmod{2\pi}$$
 volume cons.: $|\det M|=1$

example 1: $M = \begin{pmatrix} 0 & -1 \\ 1 & 0 \end{pmatrix}$ rotation by 90°

example 2: $M = \begin{pmatrix} 2 & 1 \\ 1 & 1 \end{pmatrix}$ Arnold's cat map (Anosov diffeomorphism)



observation: - disorder, "chaos"
 - order after some iterations
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2.4.1. Fixed points and nearby dynamics

Fixed points: $M \vec{x}_f = \vec{x}_f \Rightarrow (M - \mathbb{1}) \vec{x}_f = 0$

Dynamics near fixed point (at origin):

• discrete in time: $\vec{\varphi}' = M \vec{\varphi} \rightsquigarrow \text{solve } M \vec{y} = \gamma \vec{y}$

How is γ related to λ ?

• continuous in time: $\dot{\vec{x}} = A \vec{x} \rightsquigarrow \vec{x}(t) = e^{At} \vec{x}(0)$

$\rightsquigarrow \vec{x}(t+1) = e^A \vec{x}(t)$

$\rightsquigarrow \text{solve } A \vec{y} = \lambda \vec{y}$

$\gamma = e^\lambda$

Cat map:

• fixed points: $M - \mathbb{1} = \begin{pmatrix} 1 & 1 \\ 1 & 0 \end{pmatrix} \Rightarrow \vec{x}_f = \begin{pmatrix} 0 \\ 0 \end{pmatrix}$

• eigenvalues: $\det(M - \gamma \mathbb{1}) = \det \begin{pmatrix} 2-\gamma & 1 \\ 1 & 1-\gamma \end{pmatrix} \stackrel{!}{=} 0 \Rightarrow \gamma_{1/2} = \frac{1}{2}(3 \pm \sqrt{5})$

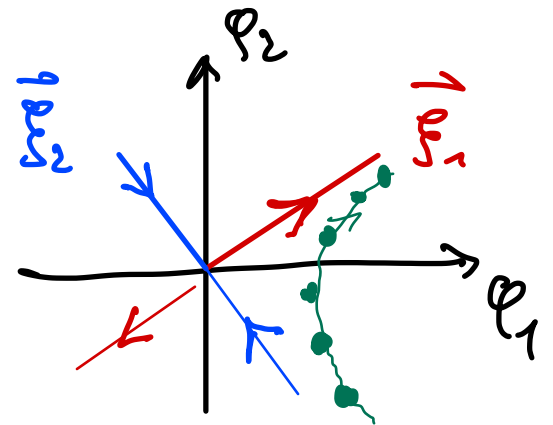
$\Rightarrow \gamma_1 > 1 \quad (\lambda_1 > 0) \quad \text{expanding}$

$\gamma_2 = \frac{1}{\gamma_1} < 1 \quad (\lambda_2 = -\lambda_1 < 0) \quad \text{contracting}$

\Rightarrow hyperbolic fixed point (no $\text{Re} \lambda = 0 \Leftrightarrow$ no $|\gamma| = 1$)

• eigenvectors:

$$\vec{v}_{1/2} = \sqrt{\frac{2}{5 \pm \sqrt{5}}} \begin{pmatrix} 1 \\ \frac{\pm \sqrt{5} - 1}{2} \end{pmatrix}$$



• dynamics near fixed point:

$$\vec{\varphi}' = M \vec{\varphi} = M (\alpha \vec{v}_1 + \beta \vec{v}_2) = \gamma_1 \alpha \vec{v}_1 + \gamma_2 \beta \vec{v}_2$$

(here: orthogonal)

2.4.2. Invariant manifolds

Which set of points approaches hyperbolic fixed points?

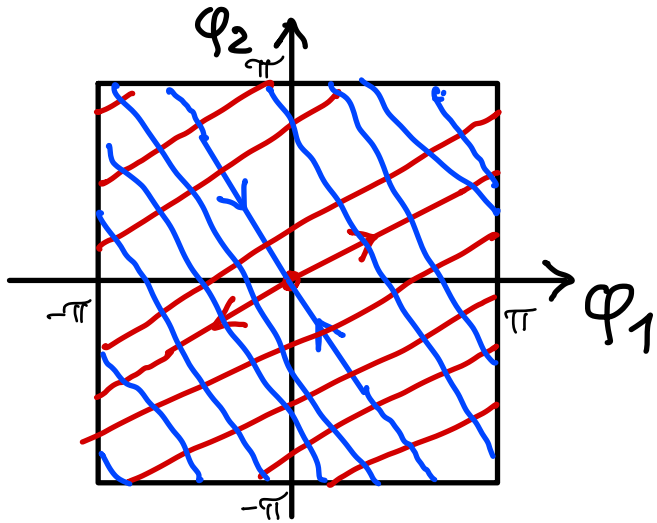
$$\text{Stable invariant manifold } W^s := \left\{ \vec{x} \mid \lim_{n \rightarrow \infty} T^n \vec{x} = \vec{x}_f \right\}$$

Which set of points approaches hyperbolic fixed points in negative time?

$$\text{Unstable invariant manifold } W^u := \left\{ \vec{x} \mid \lim_{n \rightarrow \infty} T^{-n} \vec{x} = \vec{x}_f \right\}$$

- Defs.:
- invariant: a set W is invariant under a map T if $TW = W$
 - manifold of dimension N : topological space locally homeomorph to \mathbb{R}^N

Cat map:



• W^u is straight line along $\overline{\mathbb{S}}_1$

• W^s is straight line along $\overline{\mathbb{S}}_2$

(general stable/unstable manifolds are not straight lines, just close to fixed point)

• slope of W^u, W^s is irrational $\Rightarrow W^u, W^s$ are dense on torus (Jacobi theo.)

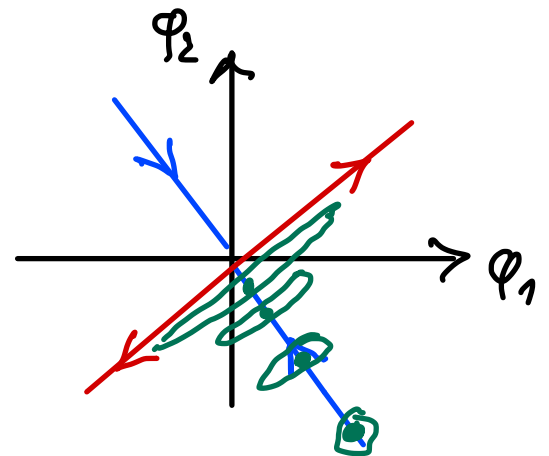
• check Poincaré recurrence theorem:

all points on W^s converge to fixed point

- they never return to their neighborhood

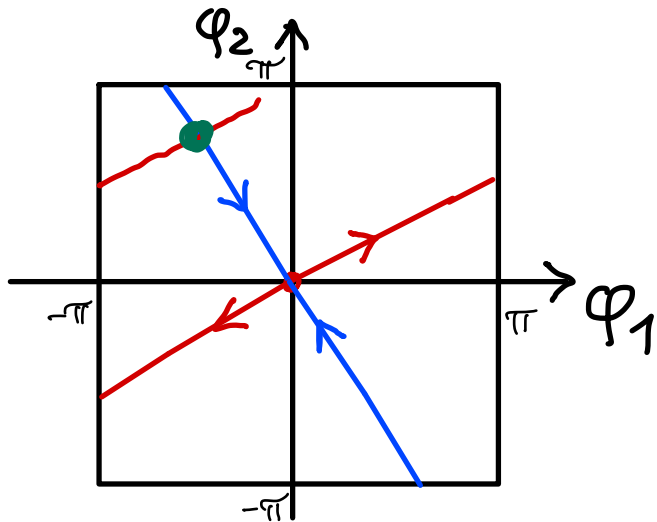
- this set is dense

but of measure zero



2.4.3. Homoclinic points

Def.: Intersection of **stable** and **unstable** manifold
of the same hyperbolic fixed point \rightarrow homoclinic point
(of different hyperbolic fixed points \rightarrow heteroclinic point)



remark:

existence of one homoclinic point

\Downarrow (later, homoclinic tangle)

Chaotic dynamics

Cat map:

- chaotic dynamics (sensitive dependence on initial condition)

- choose $\vec{\varphi}_\alpha, \vec{\varphi}_\beta$ with $|\vec{\varphi}_\alpha - \vec{\varphi}_\beta| \ll 2\pi$

$$\vec{\varphi}_\alpha = \alpha_1 \vec{s}_1 + \alpha_2 \vec{s}_2 \Rightarrow \vec{\varphi}_\alpha^{(n)} = M^n \vec{\varphi}_\alpha = \alpha_1 \gamma_1^n \vec{s}_1 + \alpha_2 \gamma_2^n \vec{s}_2 \pmod{2\pi}$$

$$\vec{\varphi}_\beta = \beta_1 \vec{s}_1 + \beta_2 \vec{s}_2 \Rightarrow \vec{\varphi}_\beta^{(n)} = \beta_1 \dots \beta_2 \dots$$

$$\Rightarrow \vec{\varphi}_\alpha^{(n)} - \vec{\varphi}_\beta^{(n)} = (\alpha_1 - \beta_1) \underbrace{\gamma_1^n}_{\infty} \vec{s}_1 + (\alpha_2 - \beta_2) \underbrace{\gamma_2^n}_{0} \vec{s}_2 \pmod{2\pi}$$

$$\Rightarrow \left| \vec{\varphi}_\alpha^{(n)} - \vec{\varphi}_\beta^{(n)} \right| \overset{n \gg 1}{\approx} |\alpha_1 - \beta_1| \gamma_1^n \quad \begin{array}{l} \text{exponential growth of initial} \\ \text{distance along } \vec{s}_1 \text{ until } O(2\pi) \end{array}$$

- \exists ∞ -many homoclinic points. They are dense for cat map.

proof: • \exists one, as \vec{e}_1, \vec{e}_2 are not parallel

• iteration gives new h.p.

• no periodicity, since convergence to fixed point

$\Rightarrow \infty$ -many \square

• W^u and W^s of cat map are dense and intersect (90°)

\Rightarrow h.p. are dense \square

2.4.4 Periodic points

Def.: $\vec{\varphi}_0$ is a **periodic point** with period p if

$$T^p \vec{\varphi}_0 = \vec{\varphi}_0$$

remark: A periodic point is a fixed point of the p -fold map.

→ exercise 2.3