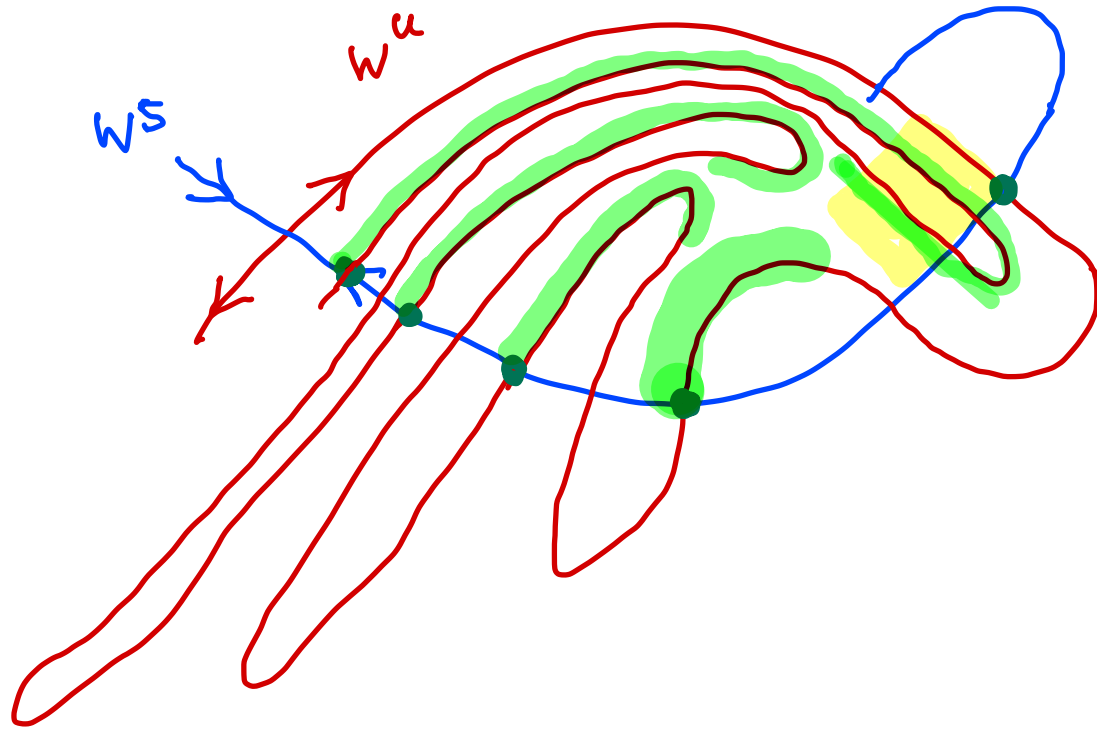


## 4.4. Smale's horseshoe map and symbolic dynamics



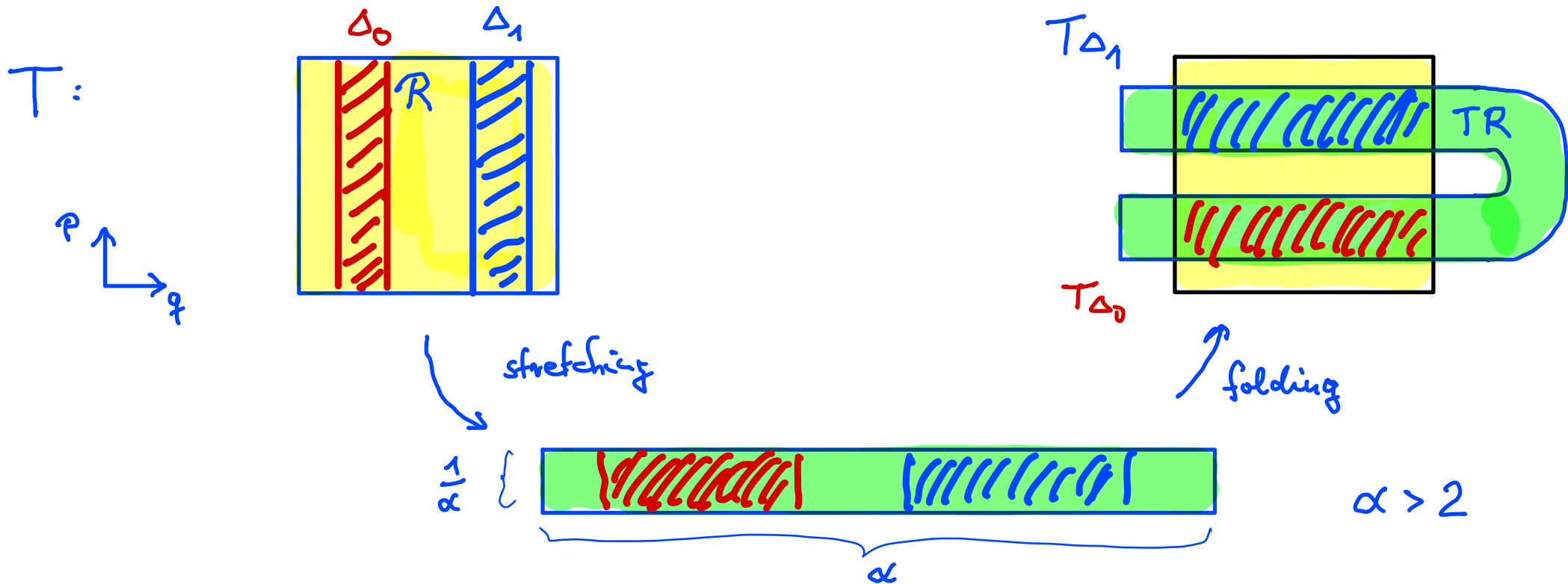
region  $R$

↓ 4 iterations

horseshoe  
intersecting with  $R$

aim: simple model for stretching and folding  
→ understand complex dynamics

Def.: Smale's horseshoe map  $T$



Consider dynamics of points remaining in  $R$ :

$$\begin{pmatrix} q \\ p \end{pmatrix} \in \Delta_0 : T \begin{pmatrix} q \\ p \end{pmatrix} = \begin{pmatrix} \alpha q + \delta_1 \\ \frac{1}{\alpha} p + \delta_2 \end{pmatrix}$$

$$\begin{pmatrix} q \\ p \end{pmatrix} \in \Delta_1 : T \begin{pmatrix} q \\ p \end{pmatrix} = \begin{pmatrix} -\alpha q + \delta_3 \\ \frac{1}{\alpha} p + \delta_4 \end{pmatrix}$$

Def: trapped set  $\Lambda := \left\{ x = \begin{pmatrix} q \\ p \end{pmatrix} \in R : T^n x \in R \quad \forall n \in \mathbb{Z} \right\}$

$T^{-1}$  for  $T_{\Delta_0}, T_{\Delta_1}$   
defined similarly

aims: i) properties of  $\Lambda$ , ii) properties of orbits in  $\Lambda$ , iii) generalization

i) Properties of trapped set  $\Delta$

$$\Delta := \left\{ x = \begin{pmatrix} q \\ p \end{pmatrix} \in \mathbb{R} : T^n x \in \mathbb{R} \quad \forall n \in \mathbb{Z} \right\}$$

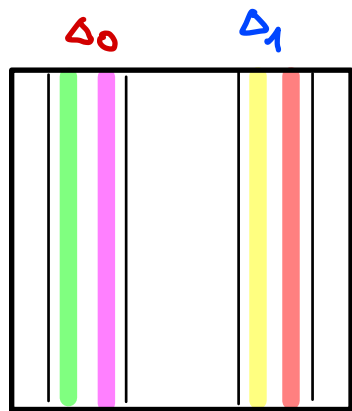
• one step approximation (forward and backward)

$$\Delta_1 := \left\{ x = \begin{pmatrix} q \\ p \end{pmatrix} \in \mathbb{R} : Tx \in \mathbb{R} \text{ and } T^{-1}x \in \mathbb{R} \right\} = \bigcap_{n=-1}^1 T^n(\mathbb{R})$$

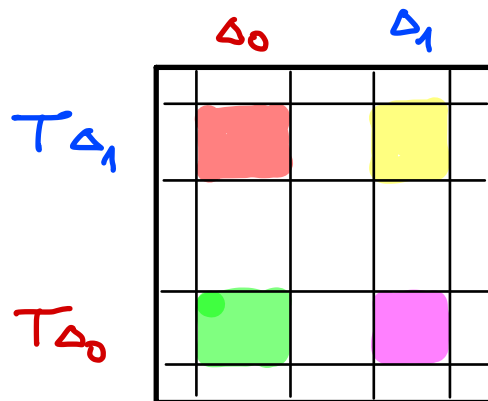
$T^{-1}(\Delta_1)$

$\Delta_1$

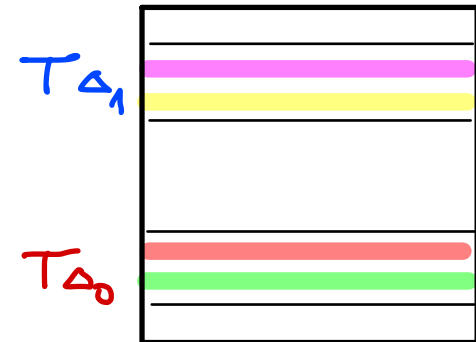
$T(\Delta_1)$



$T^{-1}$   
←

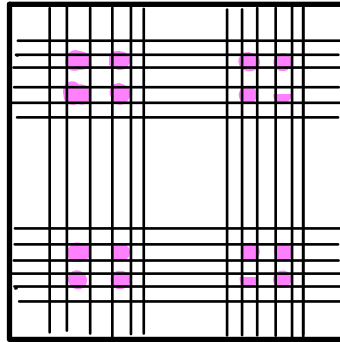


→  
 $T$



- two step approximation (forward and backward)

$$\Delta_2 := \left\{ x = \begin{pmatrix} q \\ p \end{pmatrix} \in \mathbb{R} : T^n x \in \mathbb{R}, -2 \leq n \leq 2 \right\} = \bigcap_{n=-2}^2 T^n(\mathbb{R})$$



- general structure of trapped set  $\Omega = \bigcap_{n \in \mathbb{Z}} T^n(\mathbb{R})$

$$\text{• invariance: } T^{\pm 1}(\Omega) = \bigcap_{n \in \mathbb{Z}} T^{n \pm 1}(\mathbb{R}) = \bigcap_{n \in \mathbb{Z}} T^n(\mathbb{R}) = \Omega$$

- $\Omega$  is hyperbolic: all points of  $\Omega$  are hyperbolic, i.e. expanding and contracting direction

$\Rightarrow$  trapped set  $\Omega$ : hyperbolic invariant set (chaotic saddle)

$$\text{• } \Omega \text{ is of measure zero: } \mu(\Omega) = 4^n \cdot \left(\frac{1}{\alpha^2}\right)^n = \left(\frac{2}{\alpha}\right)^{2n} \xrightarrow[\alpha > 2]{n \rightarrow \infty} 0$$

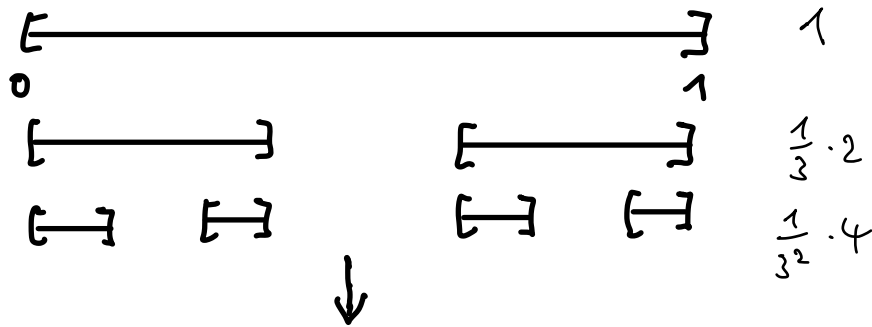
•  $\Lambda$  is a Cantor set

Def: Cantor set:

- closed (all accumulative points within set)
- nowhere dense (no intervals, everywhere gaps)
- nowhere isolated (every point has in its neighborhood other points)

example: Middle Third Cantor set

construction:



Middle Third Cantor set  $\left(\frac{1}{3}\right)^n \cdot 2^n = \left(\frac{2}{3}\right)^n \xrightarrow{n \rightarrow \infty} 0$

zero measure, uncountable

fractal dimension: How many boxes  $N$  of size  $\varepsilon$  needed to cover?

$$N(\varepsilon) \sim \varepsilon^{-D}$$

$D$ : box counting dimension (in typical cases = Hausdorff dimension)

Middle Third Cantor set:  $\varepsilon = \left(\frac{1}{3}\right)^n$ ;  $N(\varepsilon) = 2^n = \varepsilon^{-D} \Rightarrow D = \frac{\ln 2}{\ln 3} = 0.6309$

$\Lambda$  of horseshoe map:  $\varepsilon = \left(\frac{1}{\alpha}\right)^n$ ;  $N(\varepsilon) = 4^n = \varepsilon^{-D} \Rightarrow D = \frac{\ln 4}{\ln \alpha} = 2 \frac{\ln 2}{\ln \alpha} < 2$

## ii) Symbolic dynamics on $\Lambda$

dynamics on  $\Lambda$ :

initial condition:  $x_0 \in \Lambda$

orbit:  $(x_n)_{n \in \mathbb{Z}}$  with  $x_n := T^n x_0$

$\dots, x_{-1}, x_0, x_1, x_2, \dots$



symbolic orbit:

$\dots, i_{-1}, i_0, i_1, i_2, \dots, i$

binary number

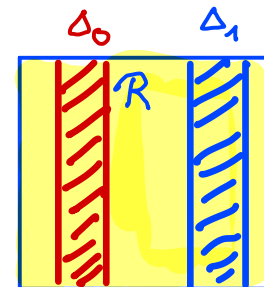
0 0 1 . 0 1 1 0

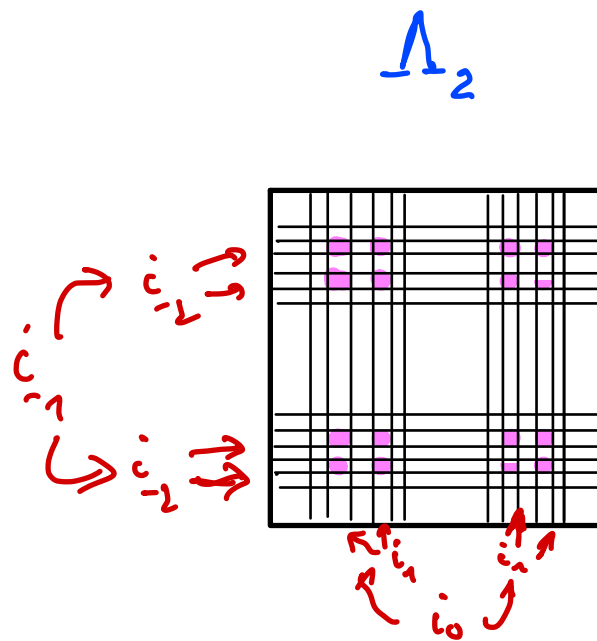
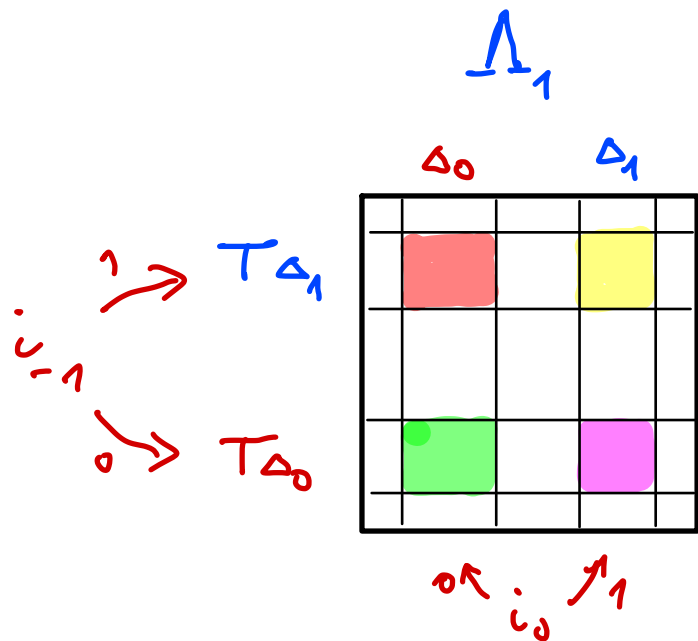
$$\text{symbol } i_n := \begin{cases} 0 & ; x_n \in \Delta_0 \\ 1 & ; x_n \in \Delta_1 \end{cases}$$

unique, as  $\Delta_0 \cap \Delta_1 = \emptyset$

$x_0 \rightarrow i$  unique

$i \rightarrow x_0$  unique?





$$M_{i_{-1}, i_0} = \left\{ x \in \mathbb{R} \mid T^k x \in \Delta_{i_k}, -1 \leq k \leq 0 \right\}$$

4 squares

$2^2$  symbolic orbit of length 2

$$M_{i_{-n}, \dots, i_{n-1}} = \left\{ x \in \mathbb{R} \mid T^k x \in \Delta_{i_k}, -n \leq k \leq n-1 \right\}$$

$4^n$  squares

$2^{2n}$  symbolic orbit of length  $2n$

$n \rightarrow \infty$  : . square  $M_{i_{-n}, \dots, i_{n-1}}$  converges to some point  $x_0$  with  $T^k x_0 \in \Delta_{i_k} \forall k$

. no other point  $y_0 \in \mathbb{R}$  has this property

$\Rightarrow i \rightarrow x_0$  unique!



⇒ one-to-one correspondence of  
elements in  $\Omega$  and symbolic orbit

implications:

1. mapping continuous: nearby points in  $\Omega$  have symbolic orbits which are identical over large regions

2. dynamics: map  $T$  on  $\Omega$   $\longleftrightarrow$  shift of symbols

Def. shift  $S$ :  $S i = j$  with  $j_n = i_{n+1}$

i)  $\exists$  periodic orbits with arbitrary periods

e.g.: ... 011 011 011 011 ...

$$T^3 x = x$$

ii) periodic orbits are dense within set of all orbits

given  $x_0 \in \Omega$  and its symbolic sequence  $i$

construct  $j \equiv \left\{ \begin{array}{l} j_n = i_n \text{ for } -m \leq n \leq m-1 \\ \text{other } j_n \text{ by periodic extensio.} \end{array} \right\} \rightarrow \text{periodic syu. orbit } j$

→ periodic orbit

iii)  $\exists$  orbits dense in  $\Omega$

Symbolic orbit from all possible finite symbol sequences:

... 0 1 0 0 0 1 1 0 1 1 0 0 0 0 0 1 0 1 0 0 1 1 ...

iv) practical indeterminism

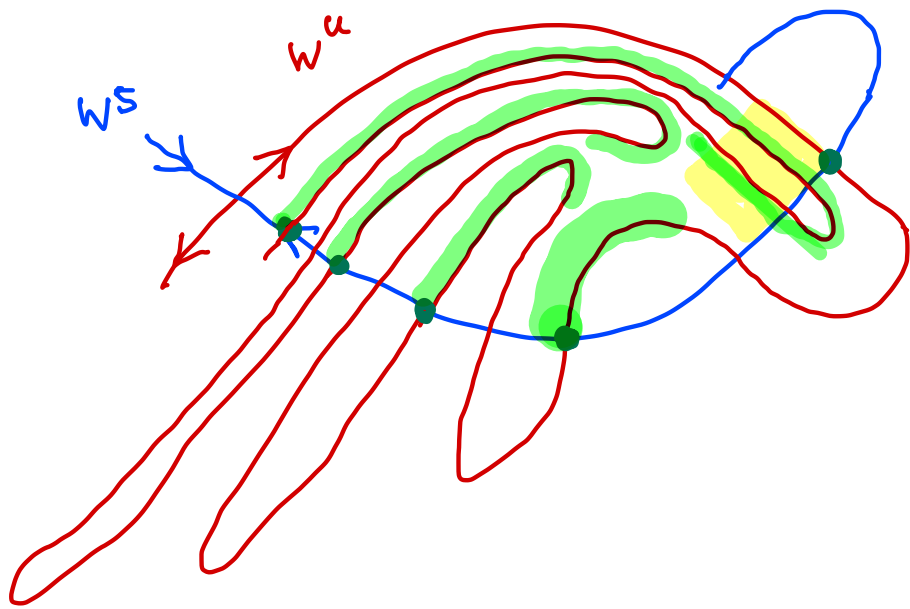
Let  $x_0$  be known with precision  $\alpha^{-n}$ , i.e.  $x \in M_{i_{-n} \dots i_{n-1}}$

$\Rightarrow i_{-n}, \dots, i_{n-1}$  known, but not  $i_n, i_{n+1}, \dots$

$\Rightarrow$  prediction error  $O(1)$  for  $x_n, x_{n+1}$

v) dynamics corresponds to coin flipping

### iii) generalization



Smale-Birkhoff homoclinic theorem

Let  $T$  be a diffeomorphism  
with a hyperbolic fixed point  
and a transverse homoclinic point

- $\Rightarrow$
1.  $\exists$  a hyperbolic invariant set  $\Lambda$
  2.  $T$  on  $\Lambda$  is equivalent  
to a shift on symbolic orbit
  3.  $\Lambda$  is a Cantor set

- $\Rightarrow$
- infinite number of periodic orbits
  - sensitive dependence