

4 Renormalization group (RG)

4.1 Concept of RG

Assumption: The relevant physics describing phases and phase transition is governed by the behavior at large length scales ($\hat{=}$ low energy) $L \gg a$

$\begin{matrix} \downarrow & \leftarrow \\ \text{typical length scale} & \text{length scale} \\ \text{microscopic} \end{matrix}$

Example (magnet): $\langle S_i^z S_{i+1}^z \rangle \neq 0$ for all T

$$\lim_{|i-j| \rightarrow \infty} \langle S_i^z S_j^z \rangle \left\{ \begin{array}{ll} = 0 & \text{for } T > T_c \\ \neq 0 & \text{for } T < T_c \end{array} \right.$$

Idea: Successively integrate out short-distance ($\hat{=}$ high-energy) modes to obtain an effective theory at large length scales ($\hat{=}$ low energy)

E.g.: $S(g_1, g_2, \dots) \mapsto S(g'_1, g'_2, \dots)$

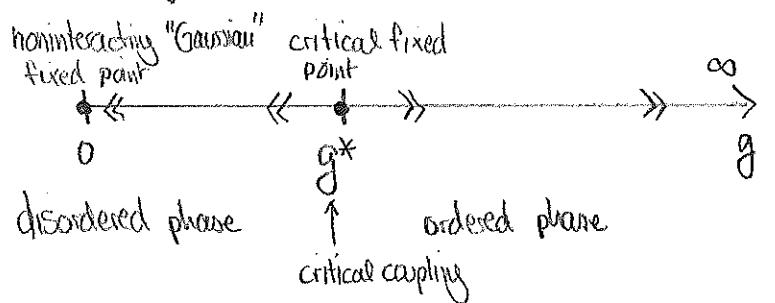
\uparrow
 couplings \uparrow
 if S is sufficiently general

\Rightarrow couplings because scale-dependent $g_i \rightarrow g_i(L)$

RG flow:

Change of couplings under the successive integration of modes

RG flow diagram (example):



4.2 Scaling transformation and scaling dimension

Rescaling of lengths / momenta:

$$x \mapsto x' = \frac{x}{s} \quad , \quad k \mapsto k' = b k \quad \text{with } b > 1$$

Infinitesimal RG step:

$$b = e^{\frac{dt}{s}} \quad \text{with } dt \ll 1 \quad , \quad t = \int_0^t dt' \quad \text{"RG time"}$$

RG flow:

$$\frac{dg_i}{dt} = \beta_i(g_i)$$

↑
beta functions

Fixed point:

$$\left. \frac{dg_i}{dt} \right|_{g_i^*} = 0$$

Linearized RG flow (around Gaussian fixed point $g^* = 0$ in theory with one coupling g):

$$\beta(g) = \Theta g + O(g^2) \quad \text{with } \Theta = \dim[g] = \text{const.} \quad \text{"scaling dimension of } g\text{"}$$

constant term vanishes
since $g=0$ is a fixed point

Integrated flow:

$$\frac{dg}{dt} = \Theta g \quad \Rightarrow \quad g(t) = g(0) e^{\Theta t}$$

Classification of couplings:

$\dim[g] > 0$ "relevant coupling" g increases in RG time

$\dim[g] < 0$ "irrelevant coupling" g decreases in RG time

$\dim[g] = 0$ "marginal coupling" higher-order terms decide its fate
(marginally relevant, marginally irrelevant,
or exactly marginal)

Classification of fixed points:

"stable fixed point": all couplings irrelevant near fixed point

"critical fixed point": exactly one relevant direction

"multicritical fixed point": number of relevant directions $2 \leq n \leq n_0$
where n_0 is the number of tuning parameters

"unstable fixed point": number of relevant directions $n > n_0$

4.3 Momentum-shell RG for the O(N) model

Action (O(N) model):

$$S = \int d\vec{x} \left[\frac{1}{2} (\vec{\nabla} \phi^a(\vec{x}))^2 + \frac{1}{2} (\phi^a(\vec{x}))^2 + \frac{u}{4!} (\phi^a(\vec{x}))^2 \right] \quad , \quad a=1, \dots, N$$

↑ tuning parameter ("mass")
↑ self-interaction coupling

$$= \int_0^\Lambda \frac{d^d k}{(2\pi)^d} \frac{1}{2} \phi^a(\vec{k}) (\vec{k}^2 + \phi^a(\vec{k})) \phi^a(\vec{k}) + \frac{u}{4!} \int_0^\Lambda \frac{d^d k_1 d^d k_2 d^d k_3}{(2\pi)^{3d}} \phi^a(\vec{k}_1) \phi^a(\vec{k}_2) \phi^b(\vec{k}_3) \phi^b(-\vec{k}_1 - \vec{k}_2 - \vec{k}_3)$$

where we have rescaled $\xi_0^2(\phi^a) \mapsto \phi^a$ and introduced an ultraviolet momentum cutoff Λ , $0 \leq |\vec{k}| \leq \Lambda$, with, e.g., $\Lambda \sim \frac{\pi}{a}$ (a : lattice constant).

Three stages of RG transformation:

1. Eliminate "fast" modes ϕ_s with momenta $\frac{\Lambda}{b} \leq |\vec{k}| < \Lambda$ ("momentum shell").

$$\phi(\vec{k}) = \Theta\left(\frac{\Lambda}{b} - |\vec{k}|\right) \phi_s(\vec{k}) + \Theta(|\vec{k}| - \frac{\Lambda}{b}) \phi_f(\vec{k})$$

↑ slow modes
 $0 \leq |\vec{k}| \leq \frac{\Lambda}{b}$ ↑ fast modes
 $\frac{\Lambda}{b} \leq |\vec{k}| < \Lambda$

2. Rescale momenta $\vec{k} \mapsto \vec{k}' = b\vec{k}$ with $0 \leq |\vec{k}'| < \Lambda$ for slow modes.

3. Introduce "renormalized" fields $\phi'(\vec{k}') = b^\gamma \phi_s(\vec{k}'/b)$ with γ chosen such that the new action in terms of ϕ' has the same coefficient for a certain quadratic term.

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RG for Gaussian model ($u=0$):

1. Mode elimination:

$$Z = \int D\phi_s \int D\phi_f e^{-S_0[\phi_s, \phi_f]}$$

with

$$S_0[\phi_s, \phi_f] = \int_0^{\Lambda/b} \frac{d^d k}{(2\pi)^d} \frac{1}{2} \phi_s(-\vec{k})(\vec{k}^2 + r) \phi_s(\vec{k}) + \int_{\Lambda/b}^{\Lambda} \frac{d^d k}{(2\pi)^d} \frac{1}{2} \phi_f(-\vec{k})(\vec{k}^2 + r) \phi_f(\vec{k})$$

Thus:

$$Z = \int D\phi_s e^{-\underbrace{\int_0^{\Lambda/b} \phi_s(\vec{k}^2 + r) \phi_s}_{= S_{\text{eff}}} - \text{const.}} \quad \begin{matrix} \uparrow \text{independent of } \phi_s \\ \left[Z_{0s} = \int D\phi_s e^{-S_{0s}} = \left[\det(\vec{k}^2 + r) \right]^{-1/2} \right] \end{matrix}$$

2. Momentum rescaling:

$$S_{\text{eff}} = \int_0^{1/b} \frac{d^d \vec{k}}{(2\pi)^d} \frac{1}{2} \phi(-\vec{k}) (k^2 + r) \phi_c(\vec{k}) \left[\begin{array}{l} \vec{k}' = b \vec{k} \\ d^d \vec{k}' = b^d d^d \vec{k} \end{array} \right]$$

$$= \int_0^1 \frac{d^d \vec{k}'}{(2\pi)^d} b^{-d} \frac{1}{2} \phi_c(-\vec{k}'/b) (b^{-2} k'^2 + r) \phi_c(\vec{k}'/b)$$

3. Field renormalization:

with $\phi'(\vec{k}') = b^y \phi_c(\vec{k}'/b)$:

$$S_{\text{eff}} = \int_0^1 \frac{d^d \vec{k}'}{(2\pi)^d} \frac{1}{2} \phi'(-\vec{k}') \left(b^{-d-2-2y} k'^2 + b^{-d-2y} r \right) \phi'(\vec{k}')$$

has the same form as original S for $y = -\frac{d+2}{2}$.

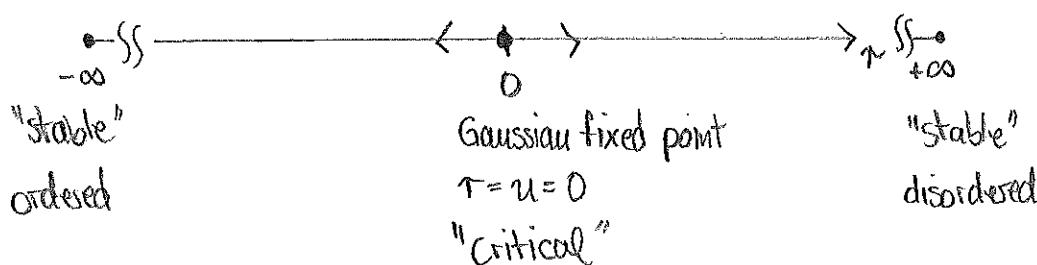
Then:

$$Z = \int D\phi_c e^{-\int_0^1 \frac{1}{2} \phi'(\vec{k}'^2 + r') \phi' d\vec{k}'} \quad \text{with } \underline{\underline{r' = b^2 r}}$$

Beta function ($0 < \ln b \ll 1$):

$$\beta_r = \frac{dr}{d\ln b} = 2r \quad (\text{for } u=0)$$

RG flow diagram:



RG for ϕ^4 model ($u > 0$ with $N=1$):

1. Mode elimination:

$$\begin{aligned} Z &= \int D\phi_< \int D\phi_> e^{-S_{0<} - S_{0>} - S_{\text{int}}[\phi_<, \phi_>]} \\ &= \int D\phi_< e^{-S_{0<}} \int D\phi_> e^{-S_{0>}} \left(1 - S_{\text{int}}[\phi_<, \phi_>] + O(u^2) \right) \end{aligned}$$

with

$$\begin{aligned} S_{\text{int}}[\phi_<, \phi_>] &= \frac{u}{4!} \left[\int_0^{Nlb} \sum_{k_1, k_2, k_3} \phi_< \phi_< \phi_< \phi_< + \int_{Nlb}^{\Lambda} \sum_{k_1, k_2, k_3} \phi_> \phi_> \phi_> \phi_> \right. \\ &\quad \left. + \binom{4}{2} \int_0^{\Lambda} \sum_{k_1, k_2, k_3} \phi_< \phi_< \phi_> \phi_> \right] \quad \left[\int_0^{\Lambda} \sum_k = \int_0^{\Lambda} \frac{d^d k}{(2\pi)^d} \right] \end{aligned}$$

Thus:

$$\begin{aligned} Z &= Z_{0>} \int D\phi_< e^{-S_{0<}} \left(1 - \frac{u}{4!} \left[\int_0^{Nlb} \langle \phi_< \phi_< \phi_< \phi_< \rangle_{0>} + \int_{Nlb}^{\Lambda} \langle \phi_> \phi_> \phi_> \phi_> \rangle_{0>} \right. \right. \\ &\quad \left. \left. \begin{array}{c} \times \text{"tree-level"} \\ \uparrow \text{average w.r.t. } S_{0>} \\ \langle \dots \rangle_{0>} \equiv \int D\phi_> e^{-S_{0>}} (\dots) / Z_{0>} \end{array} \right] + O(u^2) \right) \end{aligned}$$

Wick's theorem:

$$\langle \phi_< \phi_< \phi_> \phi_> \rangle_{0>} = \langle \phi_< \phi_< \rangle_{0>} \langle \phi_> \phi_> \rangle_{0>} \quad [\text{exercise sheet 3, problem 1c}]$$

Feynman rules (momentum shell RG):

- vertex $\star \stackrel{u}{\sim} \frac{u}{4!} \delta(\vec{k}_1 + \vec{k}_2 - \vec{k}_3 - \vec{k}_4)$

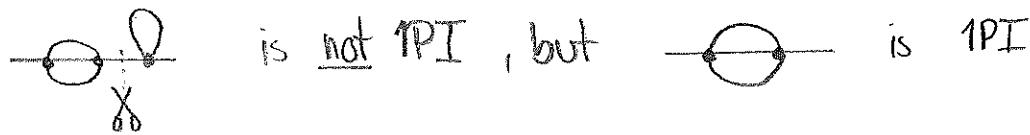
- internal line $\longleftrightarrow \stackrel{\hat{}}{\sim} \langle \phi, \phi \rangle_0$

- external line $\longrightarrow \stackrel{\hat{}}{\sim} \phi_\zeta$

Remark:

Only one-particle irreducible (1PI) connected diagrams (that remain connected after cutting one internal line) contribute to the RG flow.

Example:



Reexponentiation:

$$Z = Z_0 \int D\phi_\zeta e^{-S_{0\zeta} - \underbrace{\frac{u}{4!} \left[\int_0^{\Lambda b} \phi_\zeta \phi_\zeta \phi_\zeta \phi_\zeta + \binom{4}{2} \left(\int_0^{\Lambda b} \phi_\zeta \phi_\zeta \right) \left(\int_0^{\Lambda b} \frac{1}{k^2 + r} \right) \right]}_{=-S_{\text{eff}}} + O(u^2)}$$

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$$\text{with } \int_0^{\Lambda b} \frac{1}{k^2 + r} = \frac{S_d}{(2\pi)^d} \frac{\Lambda^d}{\Lambda^2 + r} \ln b + O(\ln b)$$

2. Momentum rescaling: $\vec{k}' = b\vec{k}$

$$S_{\text{eff}} = S_{0\zeta} + \frac{u}{4!} \left[\int_0^{\Lambda} b^{-3d} \phi_\zeta \phi_\zeta \phi_\zeta \phi_\zeta + \binom{4}{2} \int_0^{\Lambda} b^{-d} \phi_\zeta \phi_\zeta \left(\frac{S_d}{(2\pi)^d} \frac{\Lambda^d}{\Lambda^2 + r} \ln b \right) \right] + O(u^2, \ln^2 b)$$

3. Field renormalization: $\phi'(\vec{k}') = b^{-\frac{d+2}{2}} \phi_{\infty}(\vec{k}'/b)$

$$S_{\text{eff}} = \int_0^{\Lambda} \frac{1}{2} \phi' (\vec{k}'^2 + b^2 r + \underbrace{\frac{u}{2} \frac{S_d}{(2\pi)^d} \frac{\Lambda^d}{\Lambda^2 + r} \ln b}_{\equiv r^2}) \phi' + \int_0^{\Lambda} \underbrace{\frac{u'}{4!} b^{4-d}}_{\frac{u'}{4!}} \phi' \phi' \phi' \phi' + O(u^2, \ln^2 b) \quad [b^2 = 1 + O(\ln b)]$$

Then:

$$r^2 = b^2 r + \frac{u}{2} \frac{S_d}{(2\pi)^d} \frac{\Lambda^d}{\Lambda^2 + r} \ln b + O(u^2, \ln^2 b)$$

$$u' = b^{4-d} u + O(u^2, \ln^2 b)$$

Introduce dimensionless variables (for convenience):

$$r \mapsto t = \frac{r}{\Lambda^2}$$

$$u \mapsto g = \frac{S_d}{(2\pi)^d} \frac{u}{\Lambda^{d-4}}$$

Beta functions:

$\beta_t = \frac{dt}{d\ln b} = 2t + \frac{g}{2} \frac{1}{1+t} + O(g^2)$
$\beta_g = \frac{dg}{d\ln b} = (4-d)g + O(g^2)$

Remarks:

- Scaling dimensions $\text{dim}[r] = 2$ and $\text{dim}[u] = 4-d$ agree with power-counting dimensions:

$$0 = [S] = \underbrace{[r^2]}_2 + [\phi^2] + \underbrace{[d^d x]}_{-d} \Rightarrow [\phi] = \frac{d-2}{2}$$

$$0 = [S] = [u] + \underbrace{[\phi^4]}_{2(d-2)} + \underbrace{[d^d x]}_{-d} \Rightarrow [u] = 4-d = \text{dim}[g]$$

- To compute the leading interaction correction to β_g we need to compute the g^2 contribution.

Reading interaction correction to β_g (diagrammatically):

$$= (-1) \frac{1}{2!} \left(\frac{-u}{4!} \right)^2 (\phi \phi \phi \phi) (\phi \phi \phi \phi) \times \left(\frac{1}{2} \right)^2 \cdot 2$$

↑
re-expansion
of $\exp(\cdot)$

where $\underline{\phi\phi} = \langle \phi, \phi \rangle_{\text{os}}$

$$= - \frac{1}{4!} \frac{3}{2} u^2 \phi \phi \int \limits_{\text{Allb}}^{\Lambda} \frac{1}{(k^2 + \tau)^2}$$

Thus:

$$\beta_g = (4-d)g - \frac{3}{2} g^2 \frac{1}{(1+t)^2} + O(g^3)$$

Generalization to $O(N)$ model:

$$\beta_t = \frac{dt}{d\ln b} = 2t + \frac{N+2}{6} \frac{g}{1+t} + O(g^2)$$

$$\beta_g = \frac{dg}{d\ln b} = (4-d)g - \frac{N+8}{6} \frac{g^2}{(1+t)^2} + O(g^3)$$

Fixed points:

(a) Gaussian fixed point: $t^* = g^* = 0$

Near this fixed point:

$$\dim[u] = 4-d \quad \text{irrelevant for } d > 4$$

$$\dim[u_6] = 6-2d \quad \text{irrelevant for } d > 3$$

↑
 ϕ^6 coupling

(b) Wilson - Fisher fixed point: Assume $\varepsilon = 4-d \ll 1$ "fractional dimension"

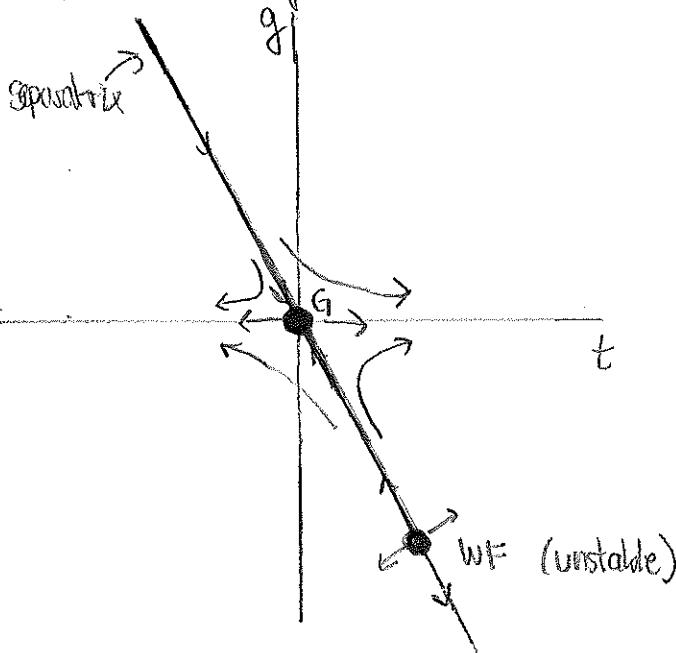
$$g^* = \frac{6}{N+8} \varepsilon + O(\varepsilon^2)$$

$$t^* = -\frac{N+2}{2(N+8)} \varepsilon + O(\varepsilon^2)$$

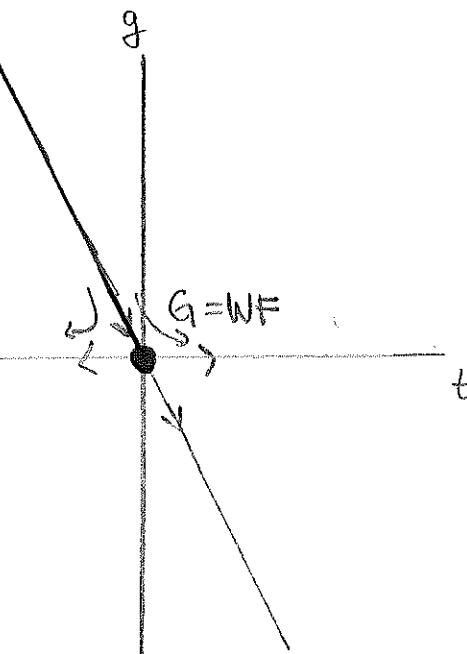
Remark:

Systematic loop expansion: contributions at $O(\varepsilon^n)$ arise from n -loop Feynman diagrams

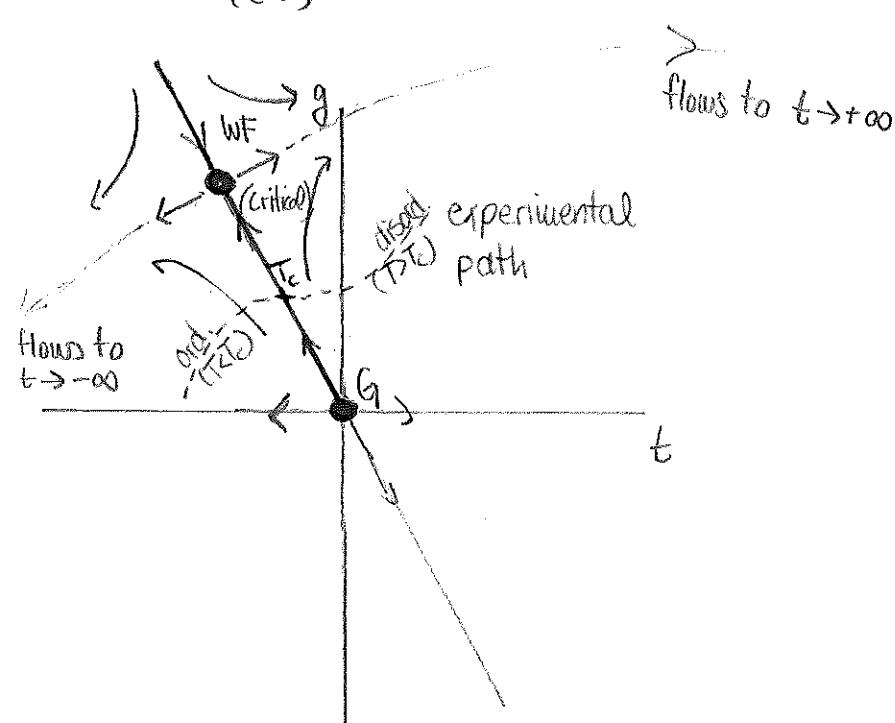
RG flow diagrams :



$d > 4$
($\varepsilon < 0$)



$d = 4$
($\varepsilon = 0$)



$d < 4$
($\varepsilon > 0$)

Remarks:

- The Gaussian (Wilson-Fisher) fixed governs the critical behavior for $d > 4$ ($d < 4$).
- $d = d_c^+ = 4$ is the upper critical dimension.

- For $d > d_c^+$ Landau theory becomes (asymptotically) exact because the theory is effectively Gaussian at criticality.
- An experimental system at T_c flows to the respective critical fixed point and the system becomes scale invariant.
- The critical behavior is governed by the flow in the vicinity of the critical fixed point.

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Perturbations to the Wilson-Fisher fixed point

Consider RG flow near the WF fixed point:

$$t = t^* + \delta t$$

$$g = g^* + \delta g$$

with $\delta t \ll t^*$ and $\delta g \ll g^*$.

Linearized flow equations ($O(N)$ model):

$$\frac{d}{dt} \begin{pmatrix} \delta t \\ \delta g \end{pmatrix} = \underbrace{\begin{pmatrix} 2 - e^{\frac{N+2}{N+8}} & \frac{N+2}{6} \left(1 + e^{\frac{N+2}{N+8}}\right) \\ 0 & -\varepsilon \end{pmatrix}}_{=: (B_{ij})} \begin{pmatrix} \delta t \\ \delta g \end{pmatrix} + O(\delta^2)$$

"stability matrix"

Diagonalization of stability matrix:

$$\sum_{j=1}^2 B_{ij} v_j^I = \theta^I v_i^I \quad I=1,2 \text{ (no sum!)} \quad \begin{matrix} \uparrow & \uparrow \\ \text{eigenvectors} & \text{eigenvalues} \end{matrix}$$

Remarks:

- $\Theta^I = \dim [v^I]$ is the scaling dimension of the coupling v^I
at the WF fixed point
- Any critical fixed point has exactly one $\Theta^I > 0$ (w.l.o.g. for $I=1$)

Integration of the relevant direction:

$$v^I(b) = v^I(0) b^{\Theta^I} \quad \text{with } \Theta^I > 0$$

Scaling transformation of reduced temperature t_{red} (other tuning parameters):

$$t_{\text{red}} \sim \delta t \sim v^2 \Rightarrow t_{\text{red}} \mapsto b^{\theta_1} t_{\text{red}} \Rightarrow \theta_1 = y_z$$

Correlation-length exponent:

$$\boxed{v = \frac{1}{\theta^I}}$$

Wilson-Fisher fixed point:

$$v = \frac{1}{2} + \frac{N+2}{4(N+8)} \epsilon + O(\epsilon^2)$$

Gaussian fixed point:

$$v = \frac{1}{2}$$

Remarks:

- For $N=1$ and $\varepsilon=1$ we get

$$v = \frac{1}{2} + \frac{1}{12} \pm \dots \approx 0.58$$

- Higher-order calculations ($D=3$):

$$v = 0.629(3) \quad (\text{six-loop } \varepsilon \text{ expansion + Borel summation})$$

$$v = 0.631(4) \quad (\text{high-temperature expansion})$$

$$v = 0.6300(1) \quad (\text{MC simulation})$$

$$v = 0.64(1) \quad (\text{neutron scattering of FeF}_2)$$

[Guida & Zinn-Justin,
J.Phys.A 31, 8103 (1998)]

4.4 Field-theoretical perspective and anomalous dimension

Idea: Perturbation theory in "renormalized" coupling u_R :

$$u_R = u - \frac{N+8}{6} u^2 \int_0^\infty \frac{d^d k}{(2\pi)^d} \frac{1}{(k^2 + \tau)^2} + O(u^3)$$

$$\begin{array}{c} u_R \\ \text{---} \end{array} = \text{---} + \text{---} + \dots$$

Remarks:

- u_R is the effective coupling after integrating out all modes.
- Dimensionless coupling:

$$u \mapsto g = \frac{S_d}{(2\pi)^d} \frac{u}{\tau^{(d-4)/2}} \quad \text{diverges for } \tau \rightarrow 0 \text{ when } d < d_c = 4$$

\Rightarrow standard perturbation theory (in u) breaks down at criticality

- "Renormalized" perturbation theory (in u_R) can be set up to yield finite result.

Example (anomalous dimension, sketch):

(Expected critical correlator:

$$\langle \phi(-k) \phi(k) \rangle \propto \frac{1}{k^{2-\eta}} \quad \text{anomalous dimension}$$

Standard perturbation theory:

$$\langle \phi(-k) \phi(k) \rangle \propto \frac{1}{k^2 + \tau - \Sigma(k)}$$

with the "self-energy"

$$\Sigma(k) = \text{---} \circlearrowleft + \text{---} \circlearrowright + \dots$$

"tadpole"
 contributes only
 to $\Sigma(0)$

 "sunset"
 leading nontrivial
 momentum dependence

Critical point: $\tau_R = \tau - \Sigma(0) = 0$

Sunset diagram yields in $D=4-\epsilon$:

$$\Sigma(k) - \Sigma(0) = u^2 \left[c_1 k^2 \ln\left(\frac{\Lambda}{k}\right) + O(k^4, \epsilon) \right] + \dots$$

\uparrow constant

To the leading order $u_R = u + O(u^2)$ and thus

$$\langle \phi(-k) \phi(k) \rangle \propto \frac{1}{k^2 \left[1 + c_2 g_R^2 \ln\left(\frac{\Lambda}{k}\right) \right]} + O(g_R^3)$$

$$= \frac{1}{k^2} \left(\frac{k}{\Lambda} \right)^{c_2 g_R^2} + O(g_R^3)$$

$$[k^* = 1 + x \ln k + O(x)]$$

with $g_R = g^*$ at the critical point.

Reinstating the constants, we read off

$$\eta = c_2(g^*)^2 = \frac{N+2}{2(N+8)^2} \varepsilon^2 + O(\varepsilon^3)$$

Remarks:

- The last step $1 + c_2 g_R^2 \ln\left(\frac{k}{\Lambda}\right) = \left(\frac{k}{\Lambda}\right)^{c_2 g_R^2} + O(g_R^4)$ effectively resums an infinite number of diagrams
- For $N=1$ and $\varepsilon=1$ (3D Ising):

$$\eta = \frac{1}{54} + \dots \approx 0.02$$

to be compared with (almost exact) value from MC

$$\eta_{MC} = 0.0363(1)$$

1.6.

4.5 Phase transitions and critical dimensions

Universality: different microscopic models flow to the same RG fixed point at criticality

Critical dimensions:

- Upper critical dimension d_c^+ : Mean-field theory asymptotically exact for $d \geq d_c^+$
- Lower critical dimension d_c^- : Fluctuations destroy ordered phase at any temperature for $d \leq d_c^-$
- Critical exponents typically depend on d for $d_c^- < d < d_c^+$ and become d -independent for $d > d_c^+$ [exception: system with sufficiently long-ranged interactions].

- Classical magnets [with short-range interactions [$O(N)$ models]]: (48)

$$d_c^+ = 4 \quad \text{and} \quad d_c^- = \begin{cases} 2 & \text{for } N > 2 \\ 1 & \text{for } N = 1 \end{cases}$$

(The case $N=2$ and $d=2$ is special.)

Physics near upper critical dimension [$\alpha(N)$ models]:

- For $d < d_c^+ = 4$: critical fixed point = Wilson-Fisher fixed point, observables computable in renormalized perturbation theory in $u^* = u^*(d)$, hyperscaling valid.
- For $d > d_c^+ = 4$: critical fixed point = Gaussian fixed point, observables computable in standard perturbation theory in u , exponents take mean-field values, e.g. $\alpha = 0$, $\eta = 0$, $\nu = \frac{1}{2}$, etc. hyperscaling validated: e.g.

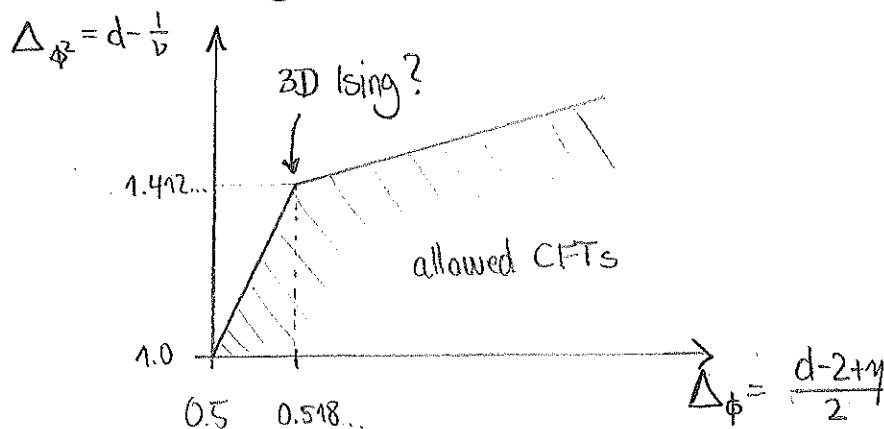
$$2 - \alpha \neq d\nu \quad (\text{Josephson})$$

can be traced back to presence of dangerously irrelevant coupling u (free energy nonanalytic at $u = u^* = 0$.)

- For $d = d_c^+ = 4$: logarithmic corrections to mean-field behavior

Analytical alternatives to $\varepsilon = 4\text{-D}$ expansion:

- $\frac{1}{N}$ expansion (exercise sheet 3)
- $2+\varepsilon$ expansion : expansion in $T_c(\varepsilon) \propto O(\varepsilon)$
- Conformal bootstrap : use symmetry and unitarity arguments to constrain scaling dimensions of operators assuming conformal invariance



World record in precision, e.g.:

$$\nu = 0.629971(4) \quad (3\text{D Ising}, \text{Kos et al., 2016})$$

[tinyurl.com/isising-lbs]

Summary :

