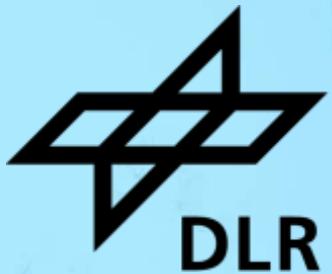


# **Accelerating the FlowSimulator: Tracing and Profiling of Python Toolchains for Industry-Grade Simulations**

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# Goal: green aviation



## EU FlightPath 2050

- 75 % CO<sub>2</sub> reduction
- 90 % NO<sub>x</sub> reduction
- 65 % noise reduction

=> Radically different aircraft designs needed

## Aircraft development & certification

Flight envelope analyses requires:

- > 10,000 data points
- > 1,000 flight hours
- > 100 steady-state, high-fidelity simulations

# Motivation for simulations

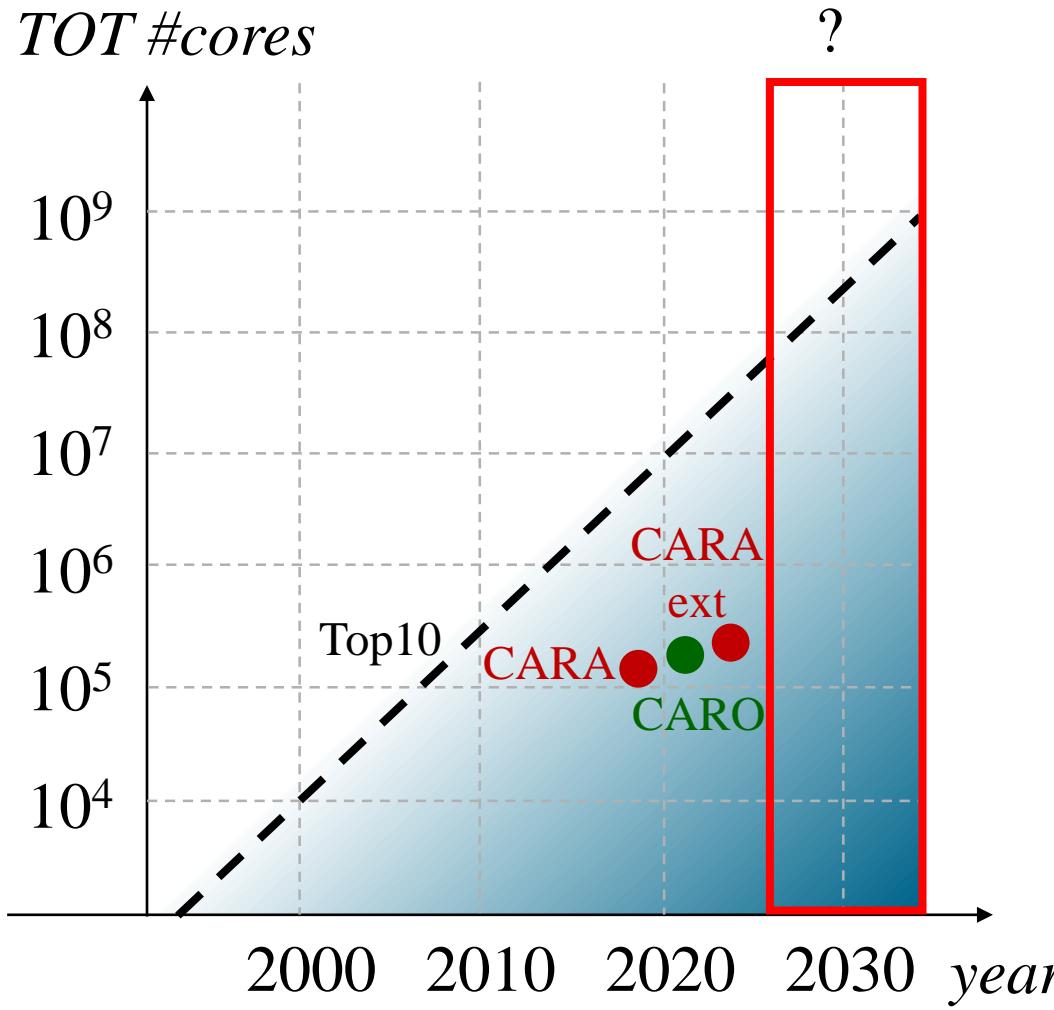


- Simulations with acceptable accuracy **may** replace costly/unfeasible testing

5.5 Engineering Analysis. An engineering analysis that includes the effects of the ice accretions as defined in Part II of Appendix C and Appendix O to CS-25 may be used to substantiate the performance and handling characteristics. The

- Aeroelastic problems can be modelled with fluid-structure interaction simulations:
  - CFD solver
  - CSM solver
  - Interpolation
  - Mesh deformation
- **High-performance computing** can be exploited to reach **acceptable time-to-solution** of high-fidelity simulations

# Trend in HPC computational resources



Increase in resources  
↓  
**shorter time-to-solution**  
&

**larger meshes**  
2006      A380\*       $\sim 50 \cdot 10^6$  elements  
2024      HLPW5\*\*       $\sim 1.2 \cdot 10^9$  elements

**BUT WE NEED  
SCALABLE SOFTWARE!**

\* Schwamborn et al “The DLR TAU-code:  
recent applications in research and industry,” *ECCOMAS 2006*

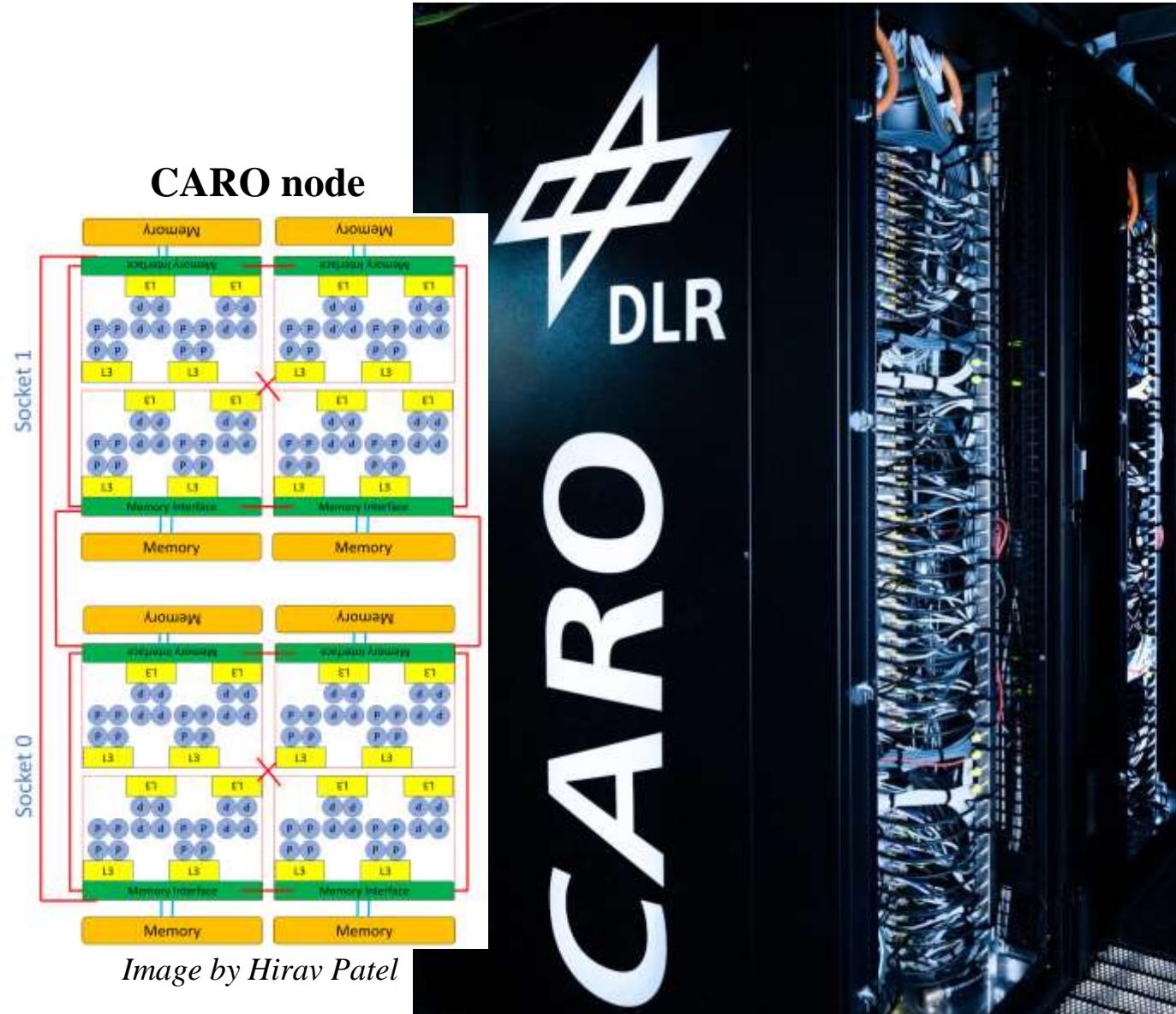
\*\*<https://commonresearchmodel.larc.nasa.gov/>

# Measurement platform

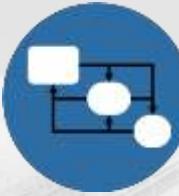


## CARO

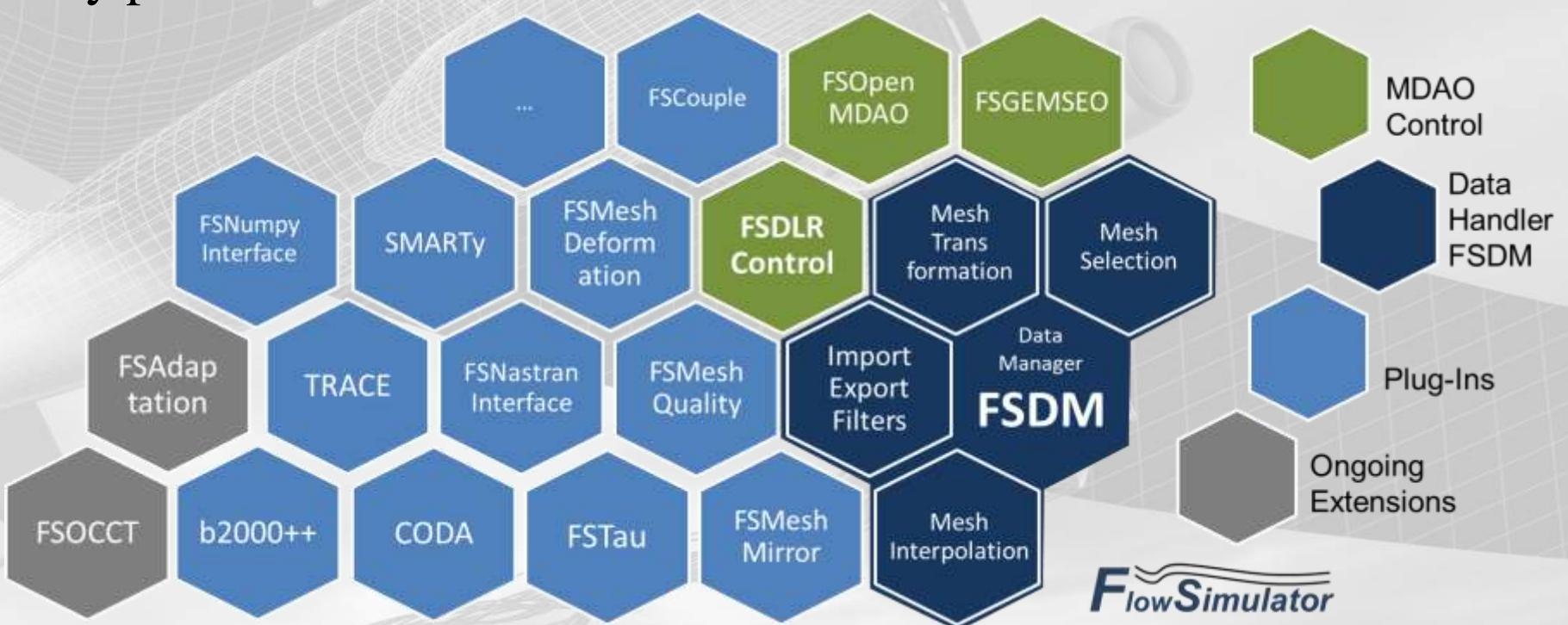
- DLR HPC System
- 174,592 cores
- #135 Top500 (11/2021)
- Göttingen (DE)
- each node:
  - 2x AMD EPYC 7702 (64 cores)
  - RAM: 256 GB DDR4
  - 16 cores per NUMA domain
  - 16 MB L3 cache shared among 4 cores



&



Innovative simulation softwares  
for high-fidelity predictions on HPC



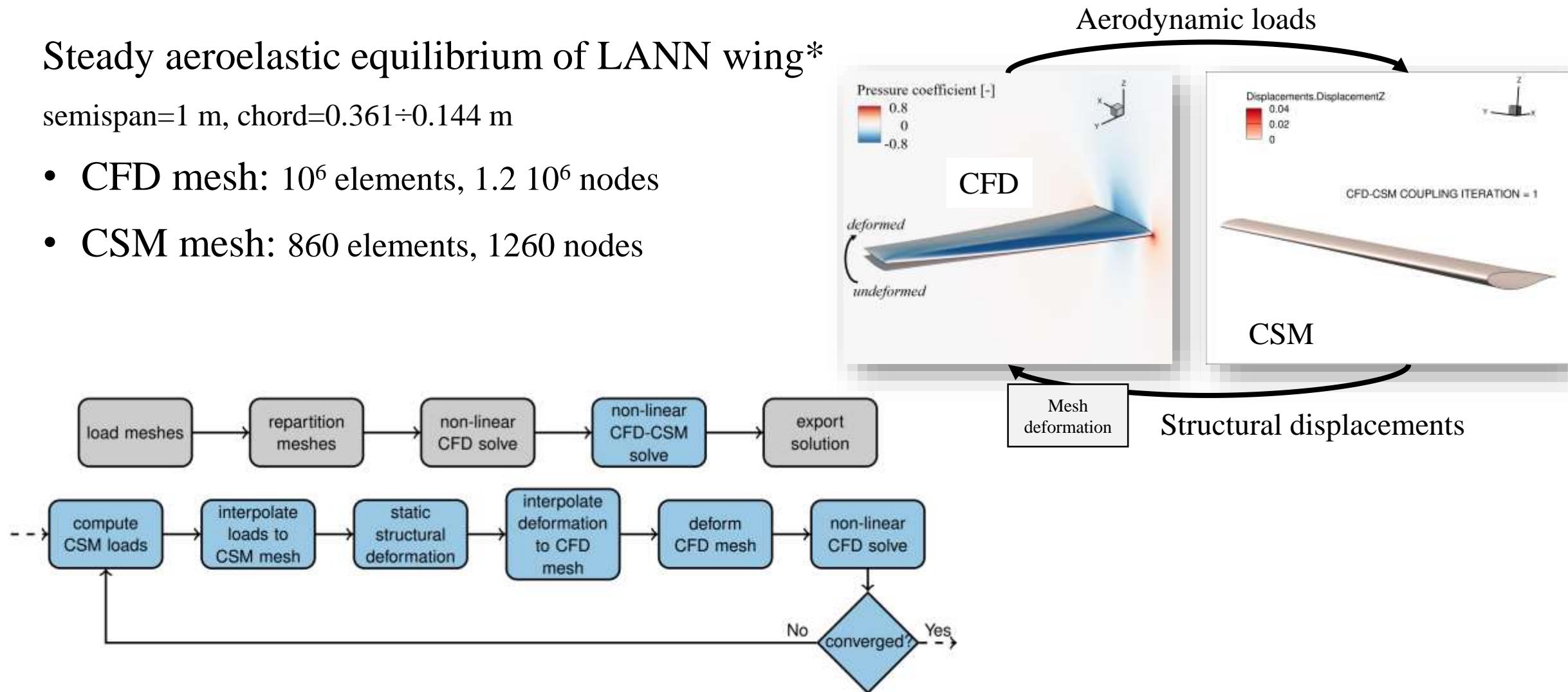
# Test case



## Steady aeroelastic equilibrium of LANN wing\*

semispan=1 m, chord=0.361÷0.144 m

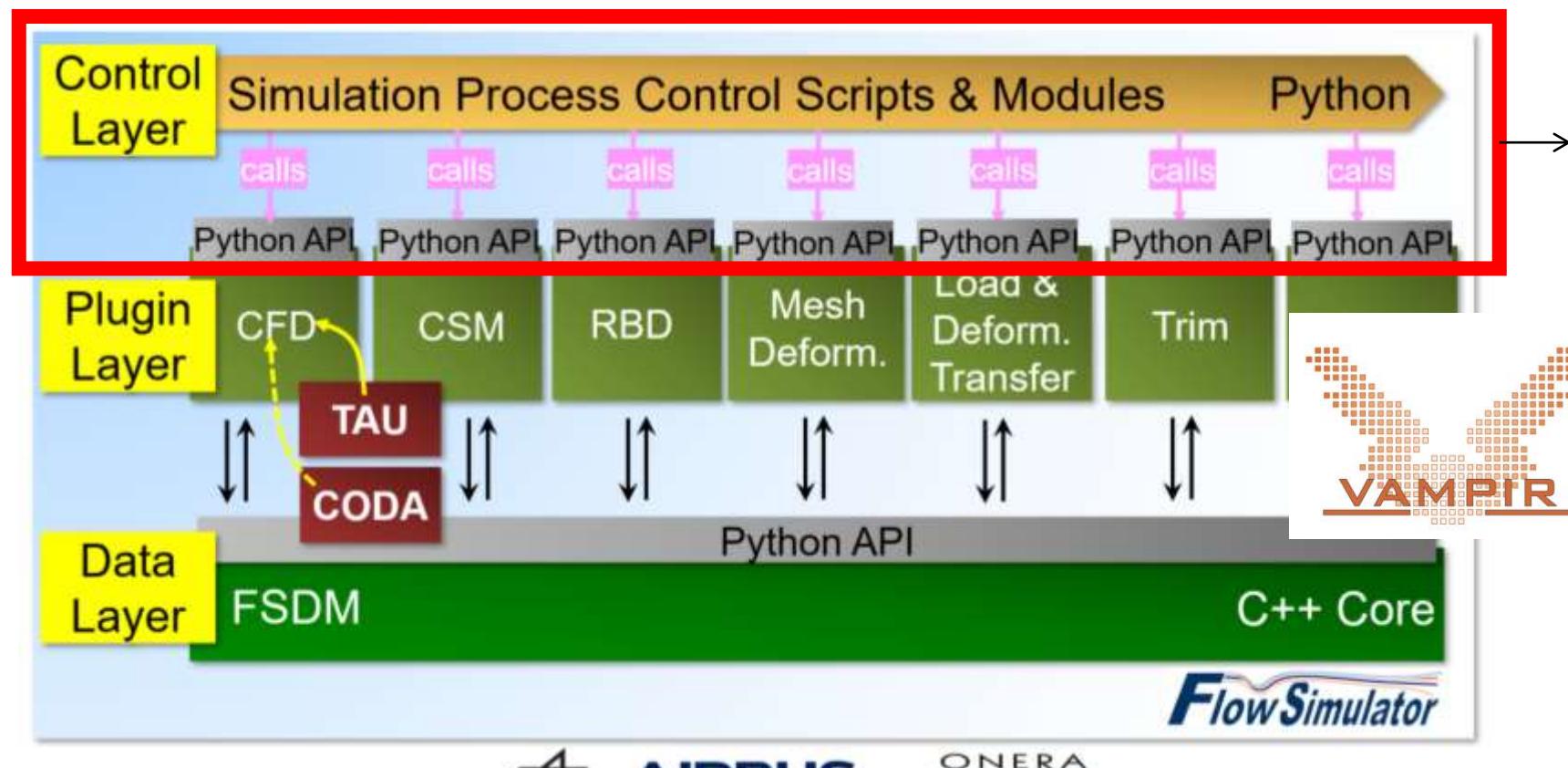
- CFD mesh:  $10^6$  elements,  $1.2 \cdot 10^6$  nodes
- CSM mesh: 860 elements, 1260 nodes



\*Firth, George C. "LANN wing design." NASA. Langley Research Center Cryogenic Wind Tunnel Models (1983).

\*\*Cristofaro, et al. "Accelerating the FlowSimulator: Improvements in FSI simulations for the HPC exploitation at industrial level," Coupled 2023

# FlowSimulator code structure and Score-P Python binding



**py-scorep-binding**  
can profile and trace  
complex simulation toolchains:

```
python -m scorep script.py
```

Load trace with **Vampir**

Runtime  
overview with  
almost no effort



\*Reimer et al "Virtual Aircraft Technology Integration Platform:  
Ingredients for Multidisciplinary Simulation and Virtual Flight Testing." AIAA 2021

# py-scorep-binding compiler problem



On CARO:

```
> spack load py-scorep-binding  
> module load flowsim  
> python -m scorep script.py      : command ['/usr/bin/cc', '-c', '../scorep_init.c', ...] failed
```

Problem:

py-scorep-binding wants to use /usr/bin/cc, but

```
> which cc      : /usr/bin/cc  
> which gcc     : /sw/rev/23.05/linux-rocky8-zen/gcc-8.5.0/gcc-10.4.0-xozig6/bin/gcc
```

Workaround:

In subsystem.py under py-scorep-binding installation folder add:

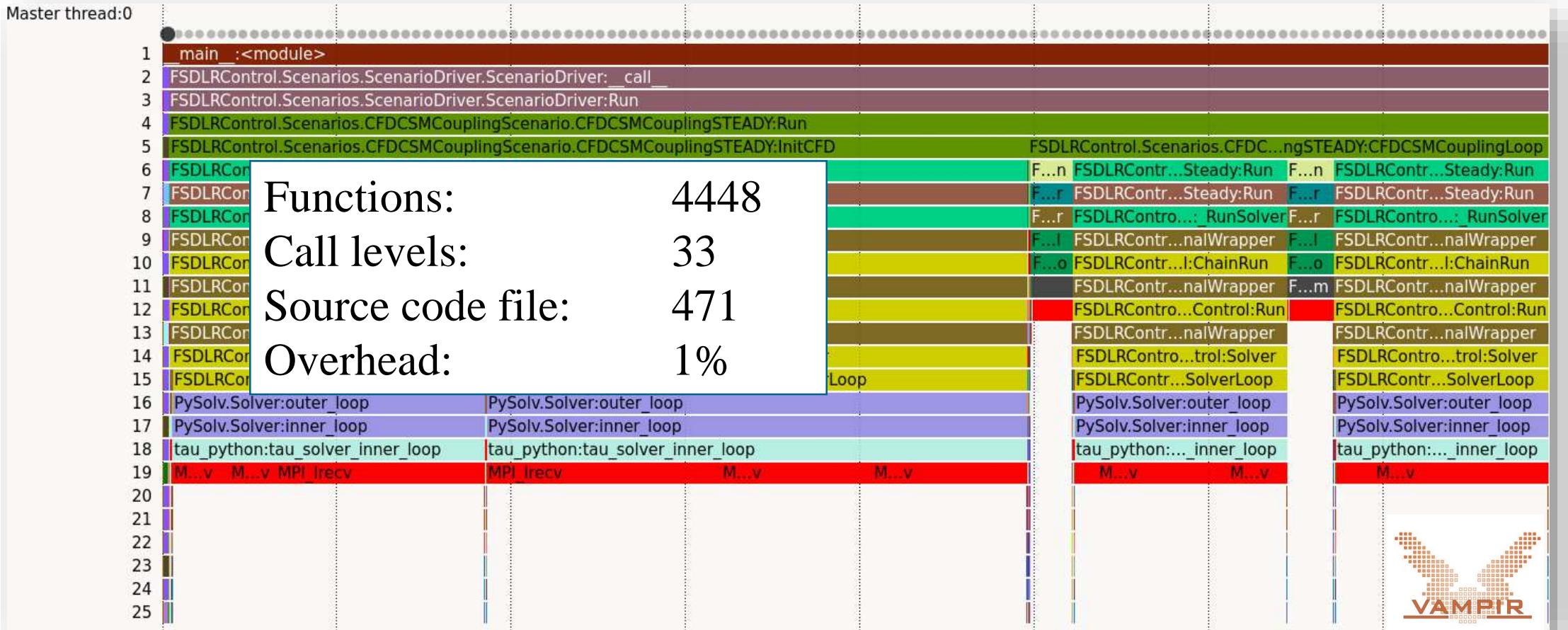
```
cc.set_executable("compiler", "gcc")  
cc.set_executable("compiler_so", "gcc")
```

# Only Python wrapping (no instrumentation)



Ready to use sbatch:

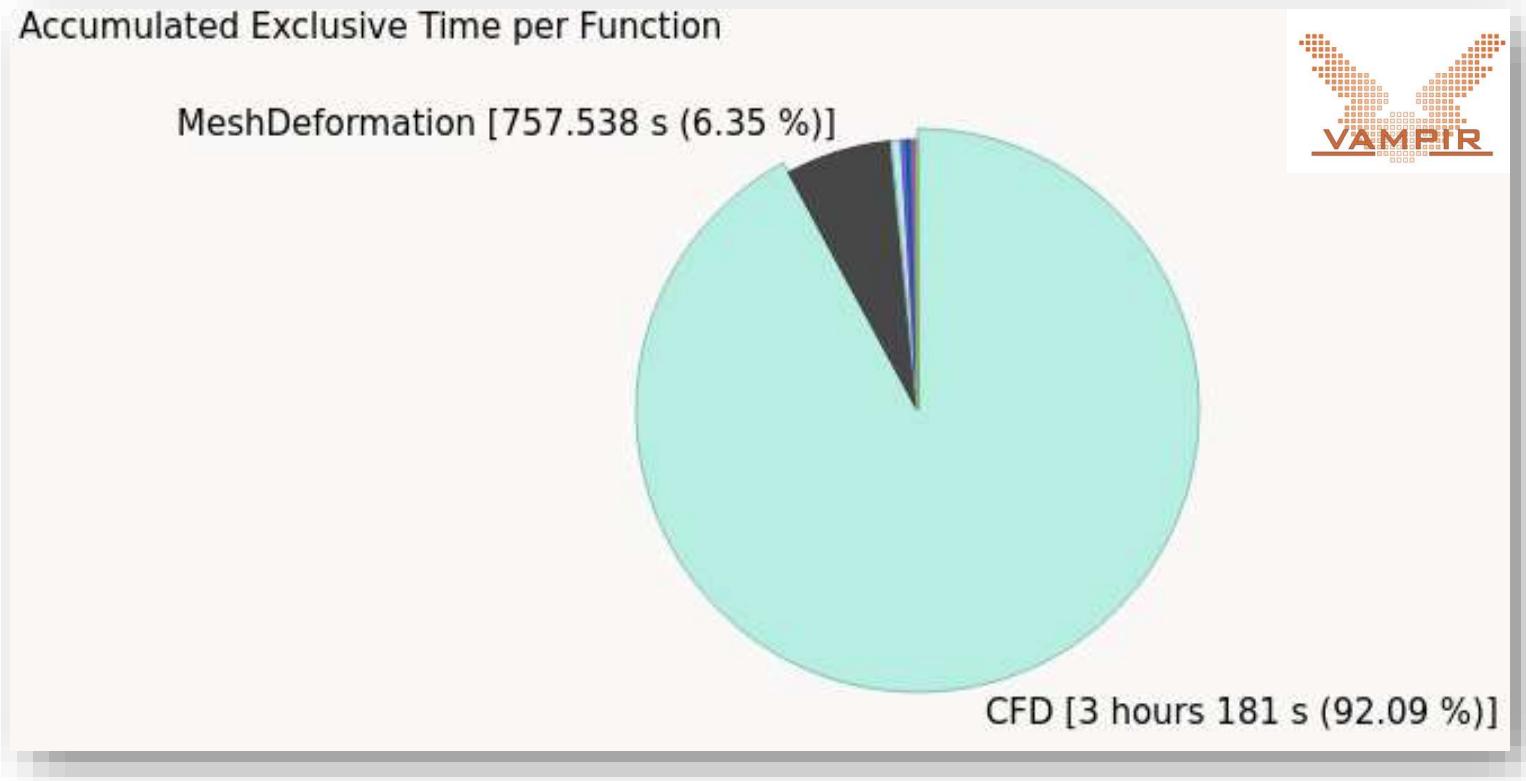
```
spack load py-scorep-binding
module load flowsim
srun python -m scorep --mpp=mpi --thread=omp script.py
```



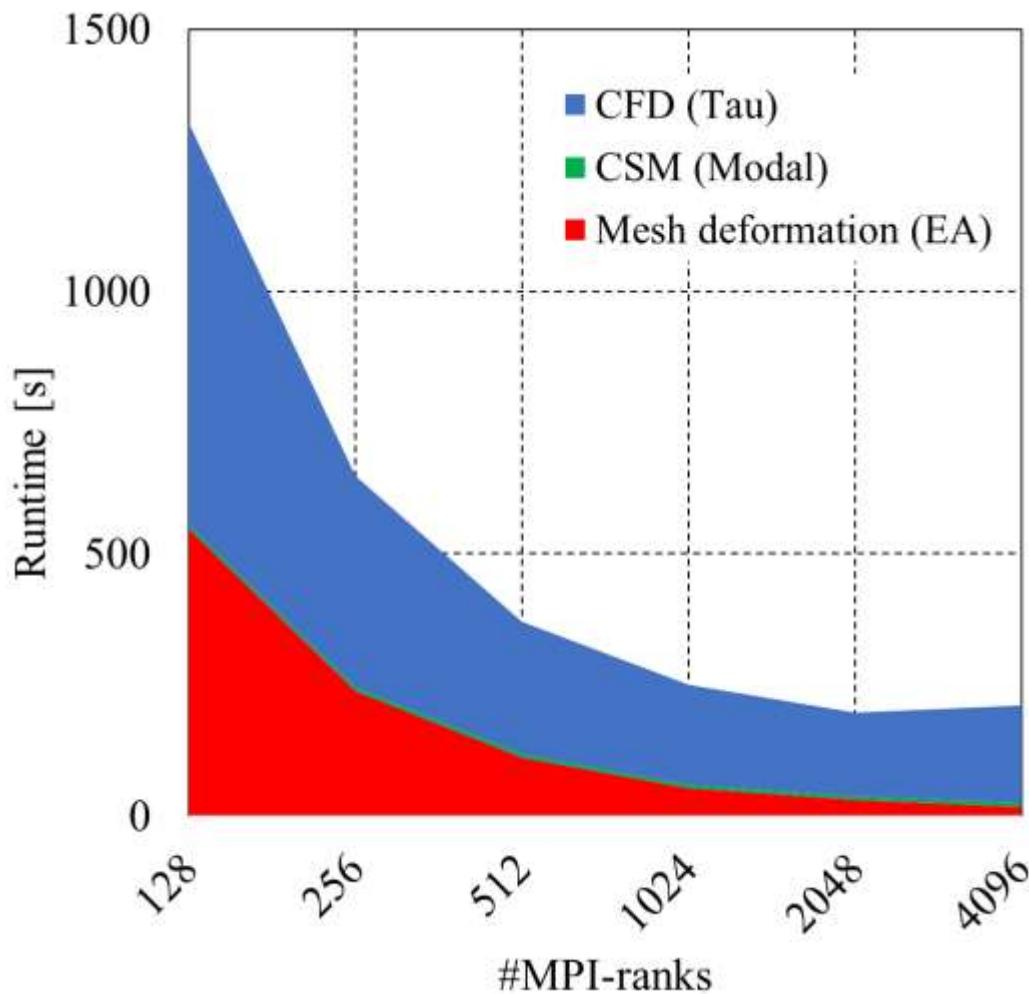
# Runtime distribution (2 MPI x 4 OpenMP)



- MPI\* filtered out
- Most time consuming simulation blocks:
  - *CFD*
  - *MeshDeformation*
- Negligible simulation blocks:
  - *MeshImport*
  - *CSM*
  - *Interpolation*
  - *MeshExport*



# Strong scaling of steady aeroelastic simulation



“Manual” measurements need:

- Predict relevant simulation blocks
- Print runtimes
- Extract for plotting

# Strong scaling with only Python wrapping

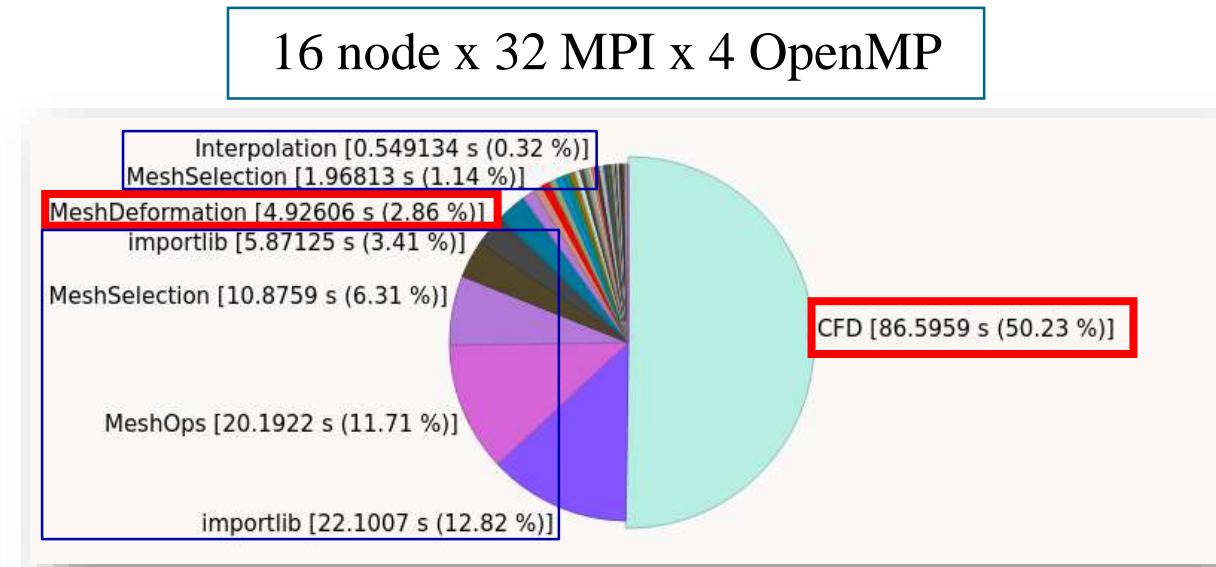
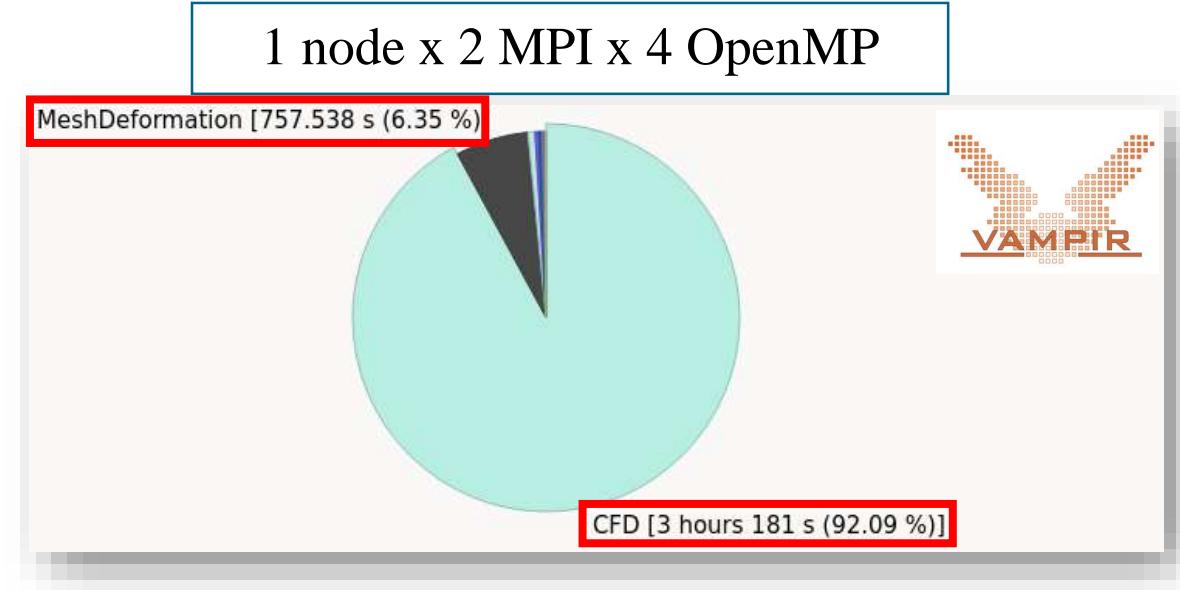


From 2 MPIs to 512 MPIs

- main blocks runtime decrease:
  - *CFD*
  - *MeshDeformation*
- new blocks appears:
  - *importlib* (one time)
  - *MeshOps* for reading meshes (one time)
  - *MeshSelection* for interpolation  
(mostly init phase)



**Not analysed with “manual”  
scaling measurements**



# Missing info in Cpp plugins



Master thread:0

```
1 main_ :<module>
2 FSDLRControl.Scenarios.ScenarioDriver.ScenarioDriver:_call_
3 FSDLRControl.Scenarios.ScenarioDriver.ScenarioDriver:Run
4 FSDLRControl.Scenarios.CFDSCMCouplingScenario.CFDSCMCouplingSTEADY:Run
5 FSDLRControl.Scenarios.CFDSCMCouplingScenario.CFDSCMCouplingSTEADY:InitCFD
6 FSDLRControl.Scenarios.CFDSolverTAU.CFDSolverTAUSteady:Run
7 FSDLRControl.Scenarios.CFDSolverBase.CFDSolverTAUSteady:Run
8 FSDLRControl.Scenarios.CFDSolverTAU.CFDSolverTAUSteady: RunSolver
9 FSDLRControl.PluginControl.APIMethod:InternalWrapper
10 FSDLRControl.TauControl.TauControl:ChainRun
11 FSDLRControl.PluginControl.APIMethod:InternalWrapper
12 FSDLRControl.TauControl.TauControl:Run
13 FSDLRControl.PluginControl.APIMethod:InternalWrapper
14 FSDLRControl.TauC...TauControl:Solver FSDLRControl.TauControl.TauControl:Solver
15 FSDLRControl.TauC...ontrol:SolverLoop FSDLRControl.TauControl.TauControl:SolverLo
16 PySolv.Solver:outer_loop PySolv.Solver:outer_loop
17 PySolv.Solver:inner_loop PySolv.Solver:inner_loop
18 tau_python:tau_solver_inner_loop tau_python:tau_solver_inner_loop
19 M...v M...v MPI_Irecv MPI_Irecv M...v
20
21
22
23
24
25
```

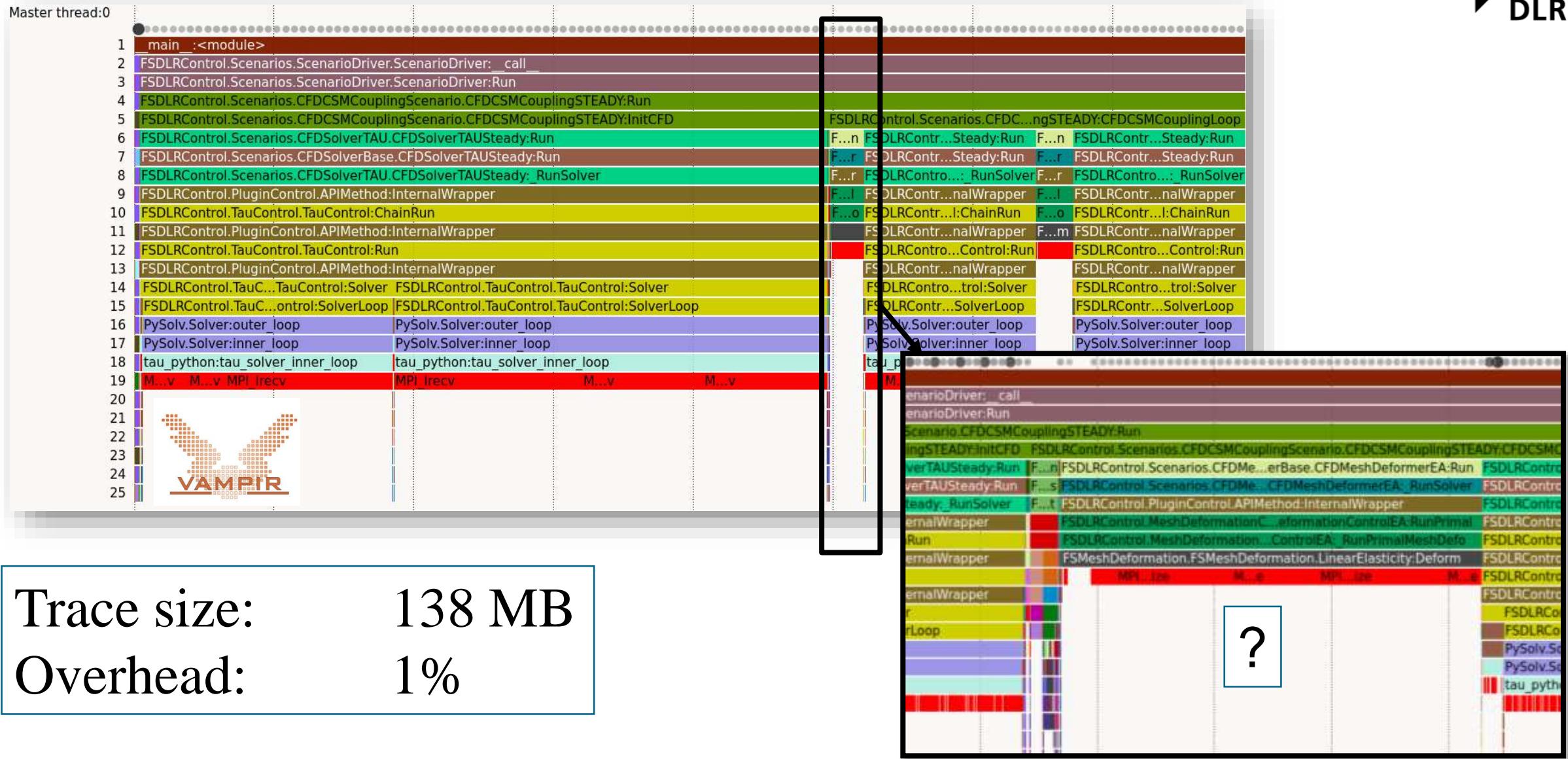


FSDLRControl.Scenarios.CFDC...ngSTEADY:CFDCSMCouplingLoop	F...n FSDLRContr...Steady:Run	F...n FSDLRContr...Steady:Run
F...r FSDLRContr...Steady:Run	F...r FSDLRContr...Steady:Run	F...r FSDLRContr...Steady:Run
F...r FSDLRContro...: RunSolver	F...r FSDLRContro...: RunSolver	F...r FSDLRContro...: RunSolver
F...l FSDLRContr...nalWrapper	F...l FSDLRContr...nalWrapper	F...l FSDLRContr...nalWrapper
F...o FSDLRContr...l:ChainRun	F...o FSDLRContr...l:ChainRun	F...o FSDLRContr...l:ChainRun
FSDLRContr...nalWrapper	F...m FSDLRContr...nalWrapper	FSDLRContr...nalWrapper
FSDLRContro...Control:Run		FSDLRContro...Control:Run
FSDLRContr...nalWrapper		FSDLRContr...nalWrapper
FSDLRContro...trol:Solver		FSDLRContro...trol:Solver
FSDLRContr...SolverLoop		FSDLRContr...SolverLoop
PySolv.Solver:outer_loop		PySolv.Solver:outer_loop
PySolv.Solver:inner loop		PySolv.Solver:inner loop

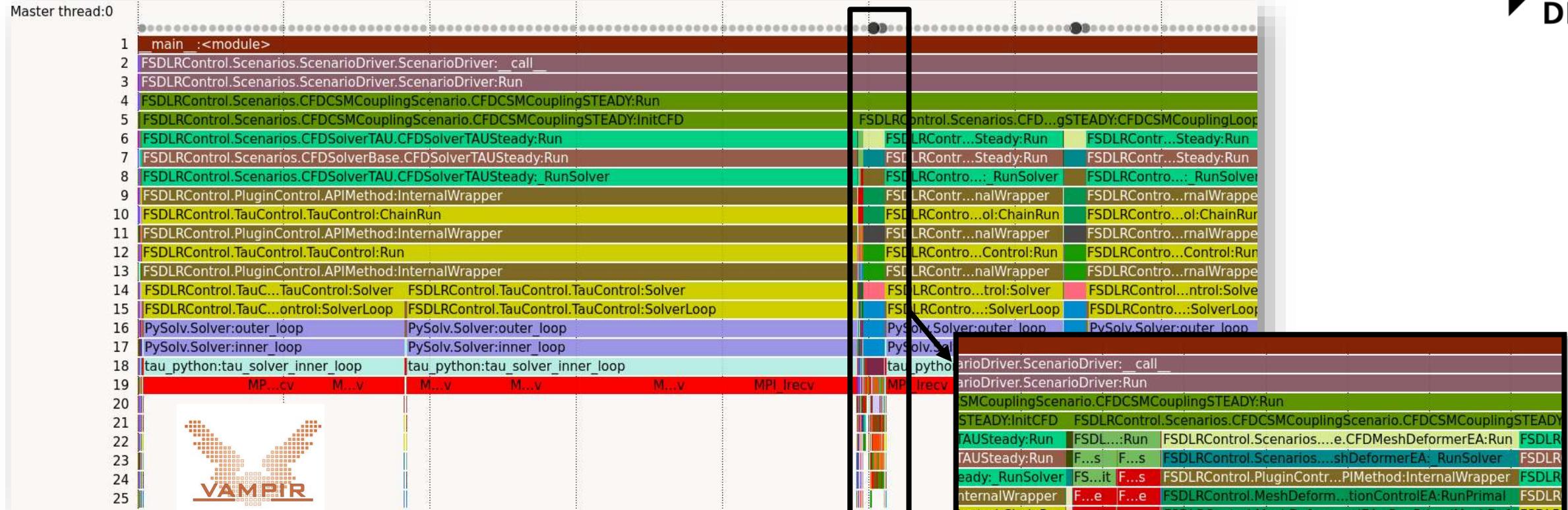
## Cpp plugins tracing requires:

- Score-P wrapper should work with all plugins build systems  
(implementation effort)
- Re-build everything with Score-P wrapper  
(a few hours)
- Define Score-P filters to limit trace size  
(automatic with `scorep-score -g` or manual)

# Traces with no code instrumentation



# Traces with Cpp instrumentation

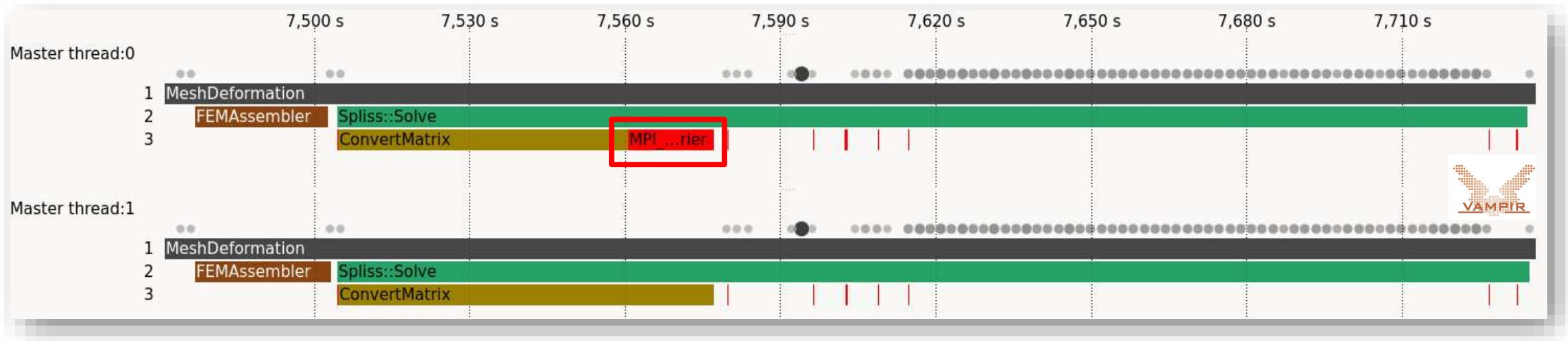


Trace size:  
5 GB  
Overhead:  
6%  
*depends on filter*

# Mesh deformation (2 MPI x 4 OpenMP)



## Focusing on *MeshDeformation*

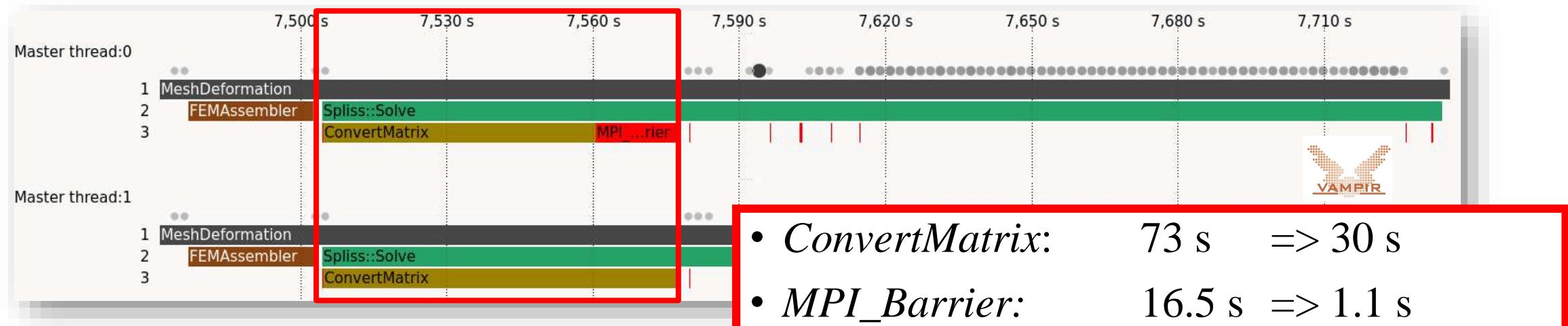


- *ConvertMatrix* 73 s
  - 27% of *MeshDeformation* runtime
  - More than *FEMAssembler*
  - 16.5 s: *MPI\_Barrier*

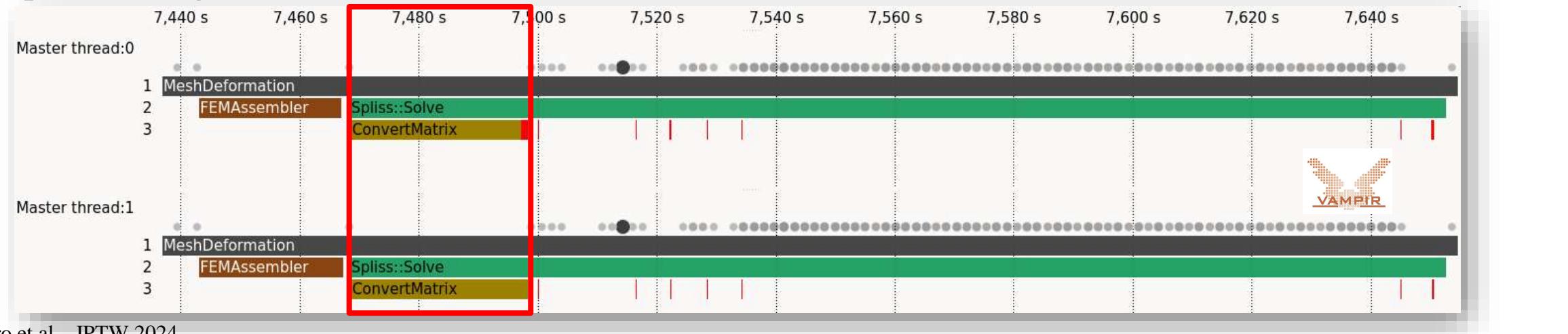
# Matrix conversion algorithm improvement (2 MPI x 4 OpenMP)



## Original algorithm



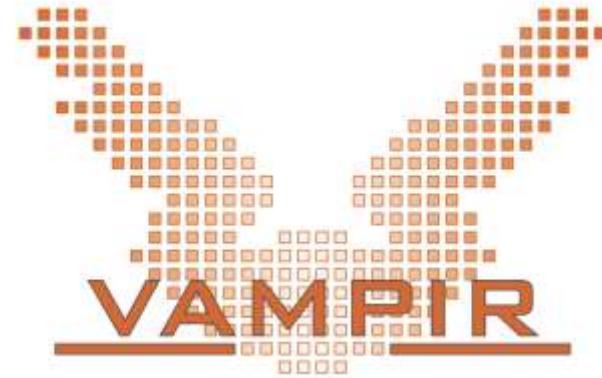
## Improved algorithm



# Conclusion



- Tracing of steady aeroelastic simulations
  - industrial-grade toolchain
  - aircraft design and certification with HPC
  - *FlowSimulator* (>50 plugins)
- Only Python binding
  - Readily available with pre-installed software
  - Good overview of main simulation blocks runtime
  - No info about Cpp implementations
- With instrumentation
  - Time consuming:
    - work to fit all build systems
    - re-build everything
    - define filters
  - Large traces  
=> beneficial to specific code analyses



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